SEMANTIC FOUNDATIONS OF DATA FLOW ANALYSIS

by

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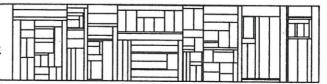
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ABSTRACT:

Abstract Interpretation (P.Cousot, R.Cousot and others) is a method for program analysis that is able to describe many data flow analyses. We investigate and weaken the assumptions made in abstract interpretation and express abstract interpretation within Denotational Semantics. As an example we specify constant propagation.

Some authors have used abstract interpretation to formulate "available expressions" (a so-called "history-sensitive" data flow analysis). Our development of "available expressions" is better justified, semantically.

In traditional data flow analysis and abstract interpretation it is generally assumed that the "Meet Over all Paths" solution is wanted. We prove that the solution specified by our approach is the "Meet Over all Paths" solution to a certain system of equations obtained from the program.

To indicate the usefulness of our approach we show how to validate a class of program transformations, including "constant folding".

Throughout this paper we use a toy language consisting of declarations, expressions and commands (involving conditional and iteration). Excluded are procedures and jumps.

KEYWORDS:

denotational semantics, non-standard semantics, data flow analysis, abstract interpretation, constant propagation, available expressions, meet over all paths solution, program transformation, constant folding.

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Index to the notation and the concepts.

We do not list notation or concepts that is more or less standard. We generally omit notation that is only used in the section where it is defined. References are to pages (1:2), tables (2.2-A) or definitions etc. (2.1.3-10).

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CHAPTER 1

Introduction

Efficient implementation of programming languages necessitates program transformations. The transformations may be between intermediate representations of some source program or between source programs (source-to-source transformations). The purpose of the transformations is to obtain a program that somehow is "better" than the original: it can be interpreted more efficiently or more efficient code can be generated from it.

Data Flow Analysis is necessary for all but the simplest program transformations. To detect the applicability of a transformation some information about the program is usually required. It is the purpose of data flow analysis to collect that information.

Often, there is a close connection between program transformations and data flow analyses. Data flow analysis is, however, also studied in its own right. This is mostly the approach we take. We develop a framework that can express several data flow analyses for an example high-level language, and we give semantic characterizations of "constant propagation" and "available expressions". The main ingredients in our approach are Abstract Interpretation and Denotational Semantics.

Literature on program analysis

Early development of <u>data flow analysis</u> was rather ad-hoc. The advent of lattice theoretic formulations of data flow analysis provided an important formalization. It made it possible to succinctly express the desired data flow information without stating which algorithm should compute it. Furthermore, the lattice theoretic approach extended the class of data flow analysis problems that could be handled.

But even in the lattice theoretic approach (e.g. [KaU77], [Ki173]) the data flow analysis is syntactic in nature: One is unable to formally verify the correctness of the obtained data flow information, i.e. that claims made by data flow analysis about executions of programs are indeed satisfied by any program execution. This implies that there is no way to make sure that each and every pitfall has been considered. A simple example is to make available expression analysis without consideration of possible sharing.

Abstract Interpretation, like data flow analysis, deals with program analysis. It is described in the "Cousot papers": [CoC77a], [CoC77b], [CoC77c], [CoH78], [CoC79], [Cou79] and similar ideas appear in [Sin72] and [Weg75]. Like the lattice theoretic approach to data flow analysis it distinguishes between specifying the desired information and specifying how to compute it. Unlike data flow analysis, the abstract interpretation approach is semantic in nature; This makes it possible to prove the correctness of data flow analysis information.

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Data flow analyses may, somewhat informally, be classified as being "history-insensitive" or "history-sensitive". The phrase "history-sensitive" is used in [Coc79]; below we briefly explain the intentions with the phrases. "History-insensitive" analyses are analyses such as constant propagation, that characterize the sets of states that reach some point in the program. Many papers apply abstract interpretation to formulate, and prove correct, analyses of this kind. "History-sensitive" analyses may be forward analyses like available expressions, that characterize the computational history, or backward analyses such as live variables, that characterize the computational future. The attempts to handle "history-sensitive" analyses by means of abstract interpretation ([Coc79,p.278], [Coc77a,p.241], [Weg75,p.276]) are less satisfactory: the interpretations may be formulated but correctness is not considered or only considered inadequately.

Overview of this paper

In this paper we give a semantic characterization of typical data flow analyses. The semantic foundation will be Denotational Semantics. This seems to be an appropriate choice for two reasons: Firstly, Denotational Semantics is widely used to define languages. It appears to be a better choice than e.g. operational semantics (see <code>[Sto77, chapter2]</code> for a discussion). Secondly, our development may be related to the compiler development of <code>[Mis76]</code>. As indicated in <code>[Nie79,p.1.45]</code> data flow analysis may be relevant to this approach to compiler development.

Two key papers that have influenced our work are [CoC79] and [Don79]. Cousot&Cousot [CoC79] describe abstract interpretation, which is the method we use to specify data flow analyses. Donzeau-Gouge [Don79] defines non-standard semantics that specify various data flow analyses. Part of our initial motivation was to unify the approach of [Don79] with abstract interpretation [CoC79]. For those parts of [Don79] we have considered we believe that our approach is more systematic and more general than her approach and that it provides a better link to "traditional data flow analysis".

In chapter 2 we review the foundations for this paper. We survey parts of Lattice theory: definitions, functions between complete lattices, and construction of complete lattices. Our use of denotational semantics is explained: the notation, the mathematical foundations and the kind of semantics (store semantics in continuation style). Key notions from "traditional" <a href="Mathematics of the traditional semantics of the traditional semant

In chapter 3 we formulate abstract interpretation in the framework of denotational semantics. This generalizes parts of [Don79] and [Don78]. We illustrate our approach by two examples of "constant propagation". One is close to that of [Don79], the other is reasonable close to the traditional notion of constant propagation.

In chapter 4 we show how "available expressions" may be handled satisfactorily, i.e. so that correctness can be proven (in some suitable sense). This shows that abstract interpretation is applicable to some forward

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"history-sensitive" analyses.

The MOP solution is generally considered the desired solution to a data flow analysis. In chapter 5 we show that our approach does specify the MOP solution.

In chapter 6 we show how our approach can be used to validate a class of program transformations (including "constant folding"). This is briefly related to the methods of other papers.

Finally, chapter 7 contains the conclusions, including an assessment of problems in our approach.

Requirements upon the reader

Chapter 2 mostly is intended as a review. This implies that the reader must be acquainted with lattice theory, denotational semantics, data flow analysis and abstract interpretation. We detail these requirements below.

We expect the reader to have a good knowledge of Denotational Semantics including proof methods (structural induction) and mathematical foundations (lattice theory). This is covered by either [Sto77] or [MiS76], whereas [Gor79] and [Ten76] only cover the use of Denotational Semantics.

Data flow analysis is described in the text books [Hec77] and [AhU78] and the survey paper [Ull75]. We expect the reader to have encountered terms like "constant propagation", "available expressions" and "MOP solution".

By abstract interpretation we understand the framework described in the "Cousot papers" (listed above). It is preferable if the reader is acquainted with at least one of these papers. We do not expect the reader to be acquainted with [Don79] or [Don78].

How to read this paper

To understand chapter 3 the material of chapter 2 is needed. However, subsection 2.4.2 can be postponed until it is needed in section 3.2. Subsection 2.4.3 can be omitted on a first reading. Sections 2.1 and 2.3 need only be skimmed if the reader has sufficient background in lattice theory and data flow analysis.

Chapters 4, 5 and 6 are mostly independent of one another. So it should be possible to read them in any order.

CHAPTER 2

Foundations

This chapter contains a review of foundational material that will be needed. In section 2.1 we review parts of lattice theory. Then (in section 2.2) we introduce our toy language and explain its denotational semantics. In section 2.3 we briefly explain the notions from data flow analysis that we will need. Finally (in section 2.4) we present abstract interpretation. We define some example concretization functions that will be needed later. However, parts of section 2.4 are not review but further development of abstract interpretation.

2.1 Lattice Theory

In subsection 2.1.1 we define the fundamental notions of complete lattices. Then (in subsection 2.1.2) we consider functions upon complete lattices and we review some of the properties of these functions. Finally (in subsection 2.1.3) we consider methods for constructing non-reflexive complete lattices.

The definitions and results of this section are used throughout the paper but an explicit reference is rarely given.

We denote by B the set {true, false}. We use the conditional IF truthvalue THEN truecase ELSE falsecase and sometimes in the form truthvalue -> truecase, falsecase. We use ordinary mathematical notation like \forall , \exists , =, \neq , \land and \lor . We denote by $\mathcal{P}(L)$ the power-set of L and by L1%L2 the cartesian product of sets L1 and L2. We use λ -notation freely [Sto77]. We only consider total functions, so f:L->M means that f is a total function from L to M. Functional composition is denoted fog and means $\lambda x.f(g(x))$. Free variables in formulae are universally quantified. For typographical reasons we often write x[i] or xi instead of xi.

2.1.1 Fundamental Definitions

DEFINITION 2.1.1-1: (L,E) is a partially ordered set iff

a) L is a set

b) Ξ is a partial order on L, i.e.

≤ is reflexive (∀l€L: L⊆L)

E is anti-symmetric (∀l1, l2€L: l1El2 ∧ l2El1 => l1=l2)

 Ξ is transitive (\forall 1, \l2, \l3\in L: \l1\in \l2 \lambda \l2\in \l3\)

When LSL and LsL {a} we abbreviate $\forall l' \in \underline{l}$: lsl' to lsl and $\forall l' \in \underline{l}$: l'sl to Lsl. We define x3y to mean ysx.

[{]a} In general, if variable v ranges over a set V, then \underline{v} will range over the power-set $(\mathcal{P}(V))$ of V.

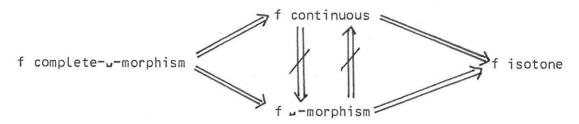
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DEFINITION 2.1.1-2: (L, \(\xi\)) is a complete lattice iff
 a) (L, E) is a partially ordered set
 c) ∀[$L: ∃[€L: ∀['€L: ['E[ <=> ['E[
                                                                                       Case b) says that for any <u>l</u> there is at least one l such that <u>LEL' <=> LEL'</u>.
 By anti-symmetry of \mathbf{E} it follows that there is exactly one \mathbf{l}, called \underline{\mathbf{the}}
 Least upper bound of L. The least upper bound of L is usually denoted UL,
 where U is called join. Similar remarks apply to c): the greatest lower
 bound of \underline{l} is denoted \Pi \underline{l}, where \Pi is called meet. This motivates:
DEFINITION 2.1.1-3: For a complete lattice (L,=) define:
 a) U: \mathcal{P}(L) \rightarrow L by \forall \underline{L} \subseteq L: \underline{L} \subseteq \underline{L} \subseteq L
 b) Π: P(L) ->L by ∀<u>l</u> ≤L: ∀l ∈L: <u>l</u> ≥l <=> Π<u>l</u> ≥l
 c) \mu = 100 = \Pi L (called "bottom") and \tau = 100 = 10L (called "top")
 d) ∀l,l'€L: lul'=∐{l,l'} (u is also called join)
          and Inl'=TK1,1'} (n is also called meet)
                                                                                       For a complete lattice (L,\Xi) each symbol \Xi,\Box,\Pi,\bot,\tau,\cup,\eta ought to have been
 indexed by L. To avoid excessive notation we elide these indices. If (M, E)
 is also a complete lattice then we expect the two € to be different partial
 orders, and we expect the two _ to be distinct, etc. We often abbreviate
 (L,E) to L.
DEFINITION 2.1.1-4: (L, =) is a <u>flat lattice</u> iff there are =1,=1 (and =1) so
 that ∀l, l'€L: lEl' <=> (l=1 v l=l' v l'=7).
OBSERVATION 2.1.1-5: Any flat lattice is a complete lattice.
                                                                                       EXAMPLE 2.1.1-6: Define N=\{1,7,0,1,2,...\} where we tacitly assume that
 Then N is a flat lattice.
    Define T=\{x,T,\text{true},\text{false}\}\ and t \le t' by (t=x \ v \ t'=x). Then T is a
 flat lattice.
    Define Q = \{1, T\} \cup U\{\text{textstrings of length } m \mid m \ge 0\} and
 q = q' \ll q = 1 \vee q = q' \vee q' = \tau). Then Q is a flat lattice.
                                                                                       A useful result is:
LEMMA 2.1.1-7 If L is a complete lattice and X \in P(L) then
 \eta\{\eta\overline{\Gamma} \mid \overline{\Gamma} \in X\} = \eta(\Omega\{\overline{\Gamma} \mid \overline{\Gamma} \in X\})
 \Pi\{\Pi\underline{L} \mid \underline{L}\in X\} = \Pi(U\{\underline{L} \mid \underline{L}\in X\})
                                                                                       (Note U in both equations).
2.1.2 Functions Upon Complete Lattices
    In the sequel we assume that (L,\Xi), (Li,\Xi) and (M,\Xi) are complete
 lattices.
DEFINITION 2.1.2-1: A function f:L->M is isotone (monotone [Sto77]) iff
¥11,12€L: 11512 => f(11)5f(12).
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DEFINITION 2.1.2-2: A set L⊆L is directed iff \finitel'⊆L ∃l'∈L: L'⊑L'. []

DEFINITION 2.1.2-3: A function f:L->M is

- a) a <u>u-morphism</u> (distributive [KaU77]) iff \finite, nonempty L\(\subseteq\L\): f(\(\overline{U}\)\) = \(\overline{U}\)\(\left\(\ell\)\)\(\left\(\ell\)\)
- b) continuous iff \directed LSL: f(\ullet_L) = \ullet\{f(\llet_L)\|\ellet_L\}
- c) a complete-u-morphism iff $\forall L \subseteq L : f(UL) = U \{f(L) | L \in L\}$

LEMMA 2.1.2-4: For a function f:L->M we have (in general):



f continuous \wedge f \cup -morphism \wedge f(\bot)= \bot

Proof is shown in appendix 2.

Note that Lemma 2.1.2-4 (or rather its dual -- see later) contradicts Observation 2.18 and Figure 2.7 of [Hec77].

DEFINITION 2.1.2-5: A function f:L->M is a <u>complete-n-morphism</u> iff $\forall \underline{L} \in \Gamma$ $f(\Pi \underline{L}) = \Pi \{f(\underline{L}) \mid \underline{L} \in \underline{L}\}$

DEFINITION 2.1.2-6: A function f:L->L is

- a) extensive iff ∀l∈L: f(l) ≥ l
- b) idempotent iff ∀l∈L: f(f(l))=f(l)
- c) reductive iff ∀l∈L: f(l)⊆l
- d) an upper closure operator iff it is isotone, extensive, and idempotent[]

DEFINITION 2.1.2-7: A function f:L->M is <u>strict</u> iff $f_{\perp}=_{\perp}$ and <u>doubly strict</u> iff $f_{\perp}=_{\perp}$ and $f_{\tau}=_{\tau}$. A function f:L1 χ L2->M is <u>very strict</u> iff it is doubly strict in both arguments, except that $f_{\perp}\tau=f_{\tau}=_{\perp}$.

We say that leL is <u>proper</u> iff $\{\{1,r\}\}$. If $f:L\to\mathbb{M}$ is a function required to be doubly strict then one needs only mention f's definition on proper elements. Similarly, if $f:L1XL2\to\mathbb{M}$ is a function required to be very strict then one needs only mention f's definition on $\{\{1,l2\}\$ proper and $\{2,l2\}\$

- LEMMA 2.1.2-8: For functions f:L2->L3 and g:L1->L2: If f and g are both isotone (υ -morphisms, continuous, complete- υ -morphisms) then the same holds for feg.
- LEMMA 2.1.2-9: Let F be a collection of functions L->M and $g=\lambda l.U\{f(l)|f\in F\}$. If all $f\in F$ are isotone (u-morphisms, continuous, complete-u-morphisms) then the same holds for g.

We now consider fixed points of (isotone) functions:

DEFINITION 2.1.2-10: If $f:L\to L$ then $l\in L$ is a $\underline{fixed\ point}$ of f iff f(l)=l. Define $LFP(f)=\Pi\{l|f(l)=l\}$ FIX(f)= $\Pi\{l|f(l)=l\}$ where $f^{\bullet}=\lambda l$. l and $f^{m+1}=f \circ f^{m}$. []

THEOREM 2.1.2-11 [Tar55]: If $f:L\to L$ is isotone then $(\{l|f(l)=l\}, \{l\})$ is a complete lattice $LFP(f)=\Pi\{l|f(l)=l\}$ is the bottom of $\{l|f(l)=l\}$

THEOREM 2.1.2-12 [Sto77][San73]: If f:L->L is continuous then FIX(f)=LFP(f)

It is easy to show that if (L, Ξ) is a complete lattice then also (L, Ξ), called the dual of (L, Ξ), is a complete lattice (partly proved in EGrä71,p.3]). If we make some assertion then the dual assertion is obtained by replacing (concepts defined in terms of) Ξ with (similar concepts defined in terms of) Ξ . The <u>duality principle</u> says that if some assertion is true in all complete lattices then the dual assertion is also true in all complete lattices [Grä71,p.3][San73,p.19].

The dual assertion of "LFP(f) is the least fixed point of f" is "GFP(f) is the greatest fixed point of f" where GFP(f)= $U\{\{\{\{\}\}\}\}\}$. Obviously, U and LFP correspond to Π and GFP in the dual lattice.

2.1.3 Construction of Complete Lattices

We take the ordinary mathematical notion of tupling for granted, e.g. $\langle a,b \rangle$ with $\langle a1,b1 \rangle = \langle a2,b2 \rangle \langle = \rangle$ a1=a2 \wedge b1=b2; Also that $\langle \rangle$ (the empty tuple) is well-defined.

Cartesian Product

DEFINITION 2.1.3-1: For $n\geq 2$ define $L1X...XLn = \{<l1,...,ln> | l1eL1,...,lneLn\}$ and $<l1,...,ln> \subseteq <l1',...,ln'> <=> l1 \(l1',...,ln' \) for ie\{1,...,ln} define <math>\forall i: L1X...XLn-> Li$ by $<l1,...,ln> \forall i=li$.

LEMMA 2.1.3-2: L1 λ ... λ Ln is a complete lattice with $UL = \langle ..., U\{l \forall i \mid l \in L\} \rangle$... \rangle $\Pi = \langle ..., \Pi\{l \forall i \mid l \in L\} \rangle$ and $\forall i$ is continuous. [7] Proof is shown in appendix 2.

COROLLARY 2.1.3-3: If fi:L->Mi and L \leq L then <...,U $fi(l)|l\in L$ },...> = Ufi(l),...> |l $\in L$ }

Separated Sum

DEFINITION 2.1.3-4: For n \geq 2 define L1+...+Ln = {1, τ } $_{\upsilon}$ U {<i,li> | li ϵ Li $_{\iota}$ 1 \leq i \leq n} with L $_{\iota}$ 1 \leq L $_{\iota}$ 2 \leq L $_{\iota}$ 4 \in L $_{\iota}$ 4 \in L $_{\iota}$ 4 \in L $_{\iota}$ 4 \in

Define (informally) "inL1+...+Ln" as the (generic [Gor79]) function Li->L1+...+Ln so that li inL1+...+Ln = <i,li> if lieLi.

Define (informally) ELi as the doubly strict function L1+...+Ln->T so that (i,j)=ELi=(i,j)-t true, false).

Define (informally) |Li as the doubly strict function L1+...+Ln->Li so that $\langle j,lj \rangle |Li = (i=j-> lj, \tau)$ [MiS76].

The definitions of inL1+...+Ln, £Li and |Li are intended to be as in Denotational Semantics. Note that inL1+...+Ln is ambiguous [MiS76] [Nie79,p.1.7]; the ambiguity will not arise in the situations where we use the notation.

LEMMA 2.1.3-5: L1+...+Ln is a complete lattice. Also inL1+...+Ln, £Li and [Li are continuous.

We have followed <code>[Sto77]</code> <code>[MiS76]</code> in using the separated sum rather than the coalesced sum <code>[Sto77,p.92,p.110]</code>. In this paper we dispense with error-elements throughout, so + does not introduce a new error element <code>[Sto77,p.145]</code> and <code>T</code> does not contain an error element. The reason is that for our purposes it is unnatural to introduce an error element in $\mathcal{P}(L)$ (to be described below) and the convention that ?->l1,l2 is ? (see <code>[Sto77,p.152]</code>) would then require all domains to contain error elements.

DEFINITION 2.1.3-6: For any complete lattice L define $L^0=\{\bot,\tau\}$ where \bot,τ are distinct elements not in L. Also define l1 Ξ l2 <=> (l1= \bot v l1 Ξ L l2 v l2= τ).

OBSERVATION 2.1.3-7: L° is a complete lattice.

We sometimes write S° where S is a set, i.e. a partially ordered set with 5 being =. Then S° is a flat lattice. Also any set with one element is often regarded as a complete lattice.

Lists

#<ll,..., lm> = m.
For i>O define "i:L*->L* to be the doubly strict function satisfying <ll,...,lj>"i = (i<j -> <l[i+1],...,lj>, <>) [MiS76].
Define \$:L*XL*->L* to be the very strict function satisfying <ll,...,ln> \$ <l[n+1],...,lm> = <ll,...,lm>.

LEMMA 2.1.3-9: L* is a complete lattice. Also $\forall i$, # and "i are continuous. Function $\lambda l^* l^* \forall \# l^*$ is continuous and $\lambda < l^* l^* l^* \mid s$ continuous.

Powersets

DEFINITION 2.1.3-10: $(P(L), \le)$ is the power-set of L with \le as ordering. Similarly, $(P'(L), \ge)$ is the power-set of L with \ge as ordering.

OBSERVATION 2.1.3-11: $\mathcal{P}(L)$ and $\mathcal{P}'(L)$ are complete lattices and $\mathcal{P}(L)$ has \mathcal{U} to be \mathcal{U} whereas $\mathcal{P}'(L)$ has \mathcal{U} to be \mathcal{O} .

There are other possible orderings on the powerset of L. One is the Egli-Milner ordering: L15L2 <=> (\forall l1 \in L1 \exists l2 \in L2: L15L2) \land (\forall l2 \in L2 \exists l1 \in L1: l15L2). This ordering depends on the partial order of L, contrary to \subseteq and \supseteq . For our purposes, however, orderings \subseteq and \supseteq are more adequate. We also discuss

powersets in section 3.1 and chapter 7.

Functions

DEFINITION 2.1.3-12: Define L-t>M = {f | f:L->M} (t for total) L-i>M = {f | f:L->M and f isotone} L-c>M = {f | f:L->M and f continuous} and $f = f < -\infty$

Γ٦

LEMMA 2.1.3-13:

- 1) L-t>M is a complete lattice with $U\underline{f} = \lambda l \cdot U\{f(l) \mid f \in \underline{f}\}$ and $N\underline{f} = \lambda l \cdot N\{f(l) \mid f \in \underline{f}\}$ (where $f \subseteq L t > M$).
- 2) L-i>M is a complete lattice with \square and \square as above.
- 3) L-c>M is a complete lattice with U as above and $\Pi \underline{f} = U \{ g \mid g \in L c > M \land \forall f \in \underline{f} : f \ni g \}$. This Π may differ from the above. [] Proof is shown in appendix 2.

We sometimes write S-t>M where S is a set. Clearly S-t>M is also a complete lattice.

In domain definitions -t>, -i> and -c> associate to the right and have lower precedence than + and χ_{*}

2.2 Denotational Semantics

In this section we introduce a toy language and explain its denotational semantics. We will later perform data flow analysis on this toy language.

The abstract syntax of our toy language is shown in table 2.2-A. The language consists of programs, declarations, commands, expressions, identifiers, basic values, and operators. The commands include input/output, a conditional, and a while-loop. We have not included nested declarations, procedures, jumps, and escapes. This is motivated in section 3.1.

We shall view a program in two ways. In Denotational Semantics one usually perceives a program as an (abstract) parse tree [Sto77,p.148]. Another approach is to perceive a program as a labelled parse tree. The root is labelled by the empty tuple (<>) and if some node is the j th son of a node labelled occ then it is labelled occ \$<j>. Following [Don79] these labels are called occurrences. If occ is an occurrence labelling some node in the program pro then pro at occ denotes the labelled subtree with that node as its root. — It is not necessary to be more formal with these definitions (until we consider program transformations).

The syntactic categories Pro, Dec, Cmd, Exp, Bas, Ide and Ope are sets, not flat lattices. This is advantageous later.

The semantics of our toy language has been separated into three tables (2.2-B, 2.2-C) and (2.2-D). We first give an overview of the tables, then explain them in detail.

Table 2.2-C defines the semantic functions \mathcal{P} , \mathcal{A} , \mathcal{E} and \mathcal{E} that give meaning to programs, declarations, commands, and expressions (respectively). Some domains, constants and functions are not defined in Table 2.2-C. They are

TABLE 2.2-A --- ABSTRACT SYNTAX

```
Syntactic Categories
  pro € Pro
              programs
 dcl € Dcl
cmd € Cmd
              declarations
              commands
 exp e Exp
              expressions
              identifiers
 bas € Bas
              (representations
              of) basic values
  ope € Ope
              operators
Syntax
 pro ::= BEG dcl IN cmd END
 dcl ::= dcl1 ; dcl2
       | DCL ide := bas
 IF exp THEN cmd1 ELSE cmd2 FI
          WHILE exp DO cmd OD WRITE exp READ ide
 exp ::= exp1 ope exp2
          ide
          bas
 ide ::= A | B | ...
 bas ::= TRUE | FALSE | 0 | 1 | ...
 ope ::= + | X | ...
```

TABLE 2.2-B --- COMMONLY USED SEMANTIC DOMAINS

```
sta € Sta = EnvXInpXOutXWit
env € Env = Ide ° -c> Val
inp € Inp = Val*
out € Out = Val*
                                                states
                                                environments
                                                inputs
                                                outputs
stacks of witnessed values
wit € Wit = Val*
val e Val = N + T +{"nil"}
occ e Occ = N*
pla e Pla = N*XQ
                                                values
                                                occurrences
                                                places
(see
                                                          Ex. 2.1.1-6)
Ex. 2.1.1-6)
Ex. 2.1.1-6)
  n \in \mathbb{N}
                                                 (see
   t e
   q & Q
                                                 (see
```

defined in Table 2.2-D or Table 2.2-B, thus completing the semantics. The purpose of Table 2.2-B is to contain some domain definitions that will be used throughout this paper.

That Table 2.2-D is separated from Table 2.2-C is advantageous because we give several semantics for the toy language; many of these can be defined by supplying a substitute for Table 2.2-D. The phrase "substitute for Table 2.2-D" can be made more precise by requiring the substitute to be an "interpretation":

DEFINITION 2.2-1: An <u>interpretation</u> is a table defining

- a) complete lattices C, I, A and S for continuations, inputs, answers and states (respectively).
- b) constants wrong€C and finish€C

TABLE 2.2-C --- SEMANTIC FUNCTIONS

Semantic Equations

```
\mathcal{P} \in \text{Pro } -t > I -t > A
                                                                   "8 € Cmd -t> Occ -c> C -c> C
                                                                        %F cmd1 ; cmd2 I occ c =
attach<occ,"(cmd">;
%Fcmd1I occ§<1>;
%Fcmd2I occ§<2>;
attach<occ,"cmd)">;c
    finish)
D ∈ Dcl -t> Occ -c> C -c> C
                                                                        %F ide := exp I occ c =
attach<occ,"(cmd">;
%FexpI occ $<2>;
assignFideI;
attach<occ,"cmd)">;c
   DE dcl1 ; dcl2 I occ c =
  attach<occ,"(dcl">;
  DEdcl1I occ <<1>;
  DEdcl2I occ <<2>;
  attach<occ,"dcl)">;

                                                                        DE DCL ide := bas { occ c =
   attach<occ, "(dcl">;
        push Ebas 1;
        assignFide1;
attach<occ, "dcl)">;c
ξ ε Exp -t> Occ -c> C -c> C
                                                                         FIX()c'. Fexpl occs<1>;
cond(Fexpl occs<2>;c'
attach<occ,"(cmd">;
FIX()c'. Fexpl occs<1>;
cond(Fexpl occs<2>;c'
attach<occ,"cmd)">;c))
     F exp1 ope exp2 I occ c = attach<occ,"(exp");
FEexp1I occ <<1>;
FEexp2I occ <<3>;
applyFopeI;
attach<occ,"exp)">;c
                                                                        %I WRITE exp I occ c =
attach<occ,"(cmd">;
**ExpI occ**<1>;
     %F ide I occ c =
  attach<occ,"(exp">;
  contentFideI;
  attach<occ,"exp)">;c
                                                                           write;
                                                                           attach<occ,"cmd)">;c
                                                                        % IF READ ide If occ c =
attach<occ,"(cmd">;
     fF bas I occ c =
attach<occ,"(exp">;
                                                                           read;
assignFideT;
attach<occ,"cmd)">;c
       pushEbas1;
attach<occ,"exp)">;c
```

```
c) auxiliary functions: setup \epsilon C -c> I -t> A cond \epsilon C X C -c> C attach \epsilon Pla -c> C -c> C
```

```
attach € Pla -c> C -c> C

d) primitive functions
apply € Ope -t> C -c> C
content € Ide -t> C -c> C
read € C -c> C

write € C -c> C
```

Obviously, Definition 2.2-1 is closly connected with Table 2.2-C. We write Ope -t> C -c> C because we consider Ope as a set, whereas in Denotational Semantics it is often considered as a flat lattice (Ope°). Similar remarks apply to Ide and Bas. If int is the name of an interpretation we write Eint, int-apply, int-C, etc. to precisely describe which "version" of E, apply, C etc. that we mean.

TABLE 2.2-D(a) --- INTERPRETATION std

```
Domains (of std)
   c \in C = S - c > A
   i \in I = Inp
  a \in A = Out + \{\text{"wrong"}\}\
  s eS = Sta
Constants (of std)
  wrong € C
                               error continuation
  wrong = \alphas. "wrong" in A
  finish € C
  finish = λ<env,inp,out,wit>. out inA
Pseudo-Semantic Functions (of std)
   B ∈ Bas° -c> Val

σ ∈ Ope° -c> (Val X Val -c> Val)
Auxiliary Functions (of std)
   setup \in C -c> I -c> A
     c < λide."nil" inVal, i, <>, <> >
  cond € C X C -c> C
Vcond € S -c> T
Scond € S -c> T
Bcond € S -c> S
                                                 (conditional)
("verify")
("select")
("body")
  cond(c1,c2) s =
  Vcond(s) -> (Scond(s) -> c1, c2) (Bcond(s)),
                      wrong s
  Vcond< env, inp, out, wit > = (#wit<<1) → false, wit \( \psi \) = Scond< env, inp, out, <t inVal>\( \beta \) wit > =
  Bcond< env, inp, out, <t inVal>§wit > = 
<env, inp, out, wit>
  attach € Pla -c> C -c> C
  attach(pla) c =
     C
```

The semantics of our toy language can be characterized as a store semantics [Sto77][MiS76] in continuation style that employs a one-stage mapping between identifiers and values.

We use continuation style rather than direct style, although the toy language can be defined without using continuations. The use of continuations is useful in chapter 4; also [Gor79,p.52] argues in favour of using continuations. It is further discussed in chapter 7.

The association between identifiers and values is by means of a one-stage mapping, i.e. we do not use locations. This tends to simplify the later development, but is otherwise unimportant. In fact the draft of this paper employed a two-stage mapping.

The semantics is not a standard semantics [Sto77][MiS76] but much closer to a store semantics [MiS76]. Why this is desirable cannot be satisfactorily explained until chapter 3 (Theorem 3.1-6).

The essential difference between a store semantics (without locations) and a standard semantics (without locations) is that in the former there is a Wit

component in the domain Sta of states (Table 2.2-B). This domain is called "stacks of witnessed values", and the purpose of witeWit=Val* is to hold the partial results arising during evaluation of an expression: Each & I expI pushes one value upon the stack of witnessed values before supplying the new state to the argument continuation.

TABLE 2.2-D(b) --- INTERPRETATION std

Before explaining the tables in detail we explain the notation. It is influenced by [Mos79], e.g. in using ';' to denote functional application that associates to the right. It has the lowest presedence of all operators. The operator # has higher precedence than ';' but still lower than "i and vi.

We assume that ++, \wedge , \vee , <<, ... are the very strict extensions of +, \wedge , \vee , <, ... on the appropriate flat lattices. Clearly they are continuous. We assume that == is a continuous function LXL->T. Also

```
DEFINITION 2.2-2: Define the predicate pure[L]:L->B by

a) If L is flat: pure[L](l) = (l∉{1, τ})

b) If L = L1½...¾Ln: pure[L]<l1,...,ln> = ∀ie{1,...,n}:pure[Li](li)

c) If L = L1+...+Ln: pure[L](τ)=pure[L](⊥)=false

pure[L](li inL) = pure[Li](li)

d) If L = M*: pure[L](l) = (l∉{1,τ} ∧ ∀ie{1,...,#l}: pure[M](l∀i))

[]
```

ASSUMPTION 2.2-3: pure[L](l1) \wedge pure[L](l2) => (l1 == l2) = (l1=l2)

Whenever teT and l1, l2eL by t->l1, l2 is meant l1 if t=true, l2 if t=false, \bot if t= \bot and \lnot if t= \lnot . We define f[y/x] to mean λ z.z==x->y, f(z). One can show that ...[.../...] and ...->..., are continuous.

Now consider Table 2.2-C. We write $\mathscr{E} \in \mathsf{Cmd} - \mathsf{t} > \mathsf{Occ} - \mathsf{c} > \mathsf{C} - \mathsf{c} > \mathsf{C}$ rather than $\mathscr{E} \in \mathsf{Cmd}^{\circ} - \mathsf{c} > \mathsf{Occ} - \mathsf{c} > \mathsf{C} - \mathsf{c} > \mathsf{C}$. Functions \mathscr{E}, \mathscr{E} and \mathscr{D} take an occurrence as a parameter: In $\mathscr{E} = \mathsf{E} = \mathsf$

The main use of occurrences is to be a component of a place plaePla=OccXQ, which is passed as an argument to the function attach. The intention of <occ, "exp)"> is to say that pro at occ is an expression, and that the corresponding attach function was placed "last" in the sequence of functions. In chapters 3 and 4 attach<occ, "exp)"> plays an important role; in Table 2.2-D it is merely the identity.

Consider Table 2.2-D defining interpretation std (for "standard") and Table 2.2-B. We have placed output in the state. Since FIX(g)= $_{\perp}$
this implies that a looping program does not produce any output. According to [MiS76,p.218] this is of little importance in practice. Finally, we have kept the error handling at a minimum in order to keep the semantics small.

The primitive functions of Table 2.2-D are defined according to the

pattern:

g(par)(c)(sta) = Vg(par)(sta)->c(Bg(par)(sta)),(wrong sta)
where Vg ∈ Par -t> Sta -c> T and Bg ∈ Par -t> Sta -c> Sta. Here Par is a set
of "parameters", that may or may not be present (depending on which g it is).
The purpose of Vg (for "verify") is to verify that the state is in a special
format. Only then Bg (for "body") is applied to the state. It aids the
readability to write the state according to the format (as in [Mos79,p.12]).
It should be clear how one can avoid this syntactically sugared notation:
e.g. in the case of BassignFide1:

BassignFideI<env,inp,out,wit> = <env[wit\1/ide],inp,out,wit\1>
The advantage of expressing primitive functions in a common form is to make

the interpretations easier to read and to simplify proofs.

The parameters (in Par), that some primitive functions have, are syntactic objects corresponding to Leaves of the parse-tree. In Table 2.2-D there are some unspecified "pseudo"-semantic functions ($\mathcal B$ and $\mathcal O$) mapping the syntactic objects into semantic objects.

Tables 2.2-B, 2.2-C and 2.2-D (essentially) constitute a denotational definition in the style of [Sto77]. Therefore the mathematical foundations of [Sto77] ensure that $\mathcal{P}, \mathcal{D}, \mathcal{E}$ and \mathcal{E} are well-defined. In later interpretations we introduce powersets. As it is unclear how to define a retract (in LAMBDA [Sto77]) for powersets we explicitly provide an alternate mathematical foundation:

THEOREM 2.2-4: When int is an interpretation then Table 2.2-C and int define functions \mathcal{P} int, \mathcal{A} int, \mathcal{C} int and \mathcal{C} int. They are of functionalities as shown in Table 2.2-C and no function is supplied with an argument of the wrong type. When setup \in C -c> I -i> A then \mathcal{P} int \in Pro -t> I -i> A, and when setup \in C -c> I -c> A then \mathcal{P} int \in Pro -t> I -c> A.

In LAMBDA there is no danger of supplying an argument of the wrong type because retracts do a coercion, if necessary, so that even supplying an argument of the wrong type is well-defined. To avoid these issues we explicitly stated that the situation does not arise. Because of our alternate mathematical foundation we must show:

LEMMA 2.2-5: Table 2.2-D specifies an interpretation. []
Proof is shown in appendix 2.

One assumption fulfilled by Tables 2.2-B, 2.2-C, 2.2-D and later interpretations is:

ASSUMPTION 2.2-6: All domains are complete lattices, and we take fixed points only of continuous functions.

This is weaker than the usual requirements of Denotational Semantics: For simplicity we do not assume that domains are countably based and continuous [Sto77]; so for us "domain" simply means "complete lattice". Also we allow non-continuous functions because they are needed later (normally all functions must be continuous).

2.3 Data Flow Analysis

In this section we review some of the concepts from data flow analysis. In the literature the details vary, but our treatment agrees with the intentions of most authors.

In traditional data flow analysis a program is viewed as a graph ("flowchart"). The nodes (called basic blocks) contain very simple instructions, e.g. a sequence of assignment statements where the expressions contain only one operator. The instructions in a node are executed in the order of appearance. The possibility of error stops is often ignored. Arcs represent flow of control between nodes. Obviously, programs in our toy language must be transformed before they conform to this view.

In the process of data flow analysis some information is associated with arcs, entries to nodes, or exits from nodes. We prefer to talk in terms of arcs. <u>Global analysis</u> associates information with arcs. To reduce the space required to represent this information one usually makes nodes as large as possible. <u>Local analysis</u> propagates information inside nodes. It is usually quite simple and is often ignored when a data flow analysis is discussed.

We now review three data flow analysis problems.

<u>Constant propagation</u> is a data flow analysis problem where "constant computations are evaluated at compiletime" [Kil73]. The global analysis consists in associating a pool of tuples with arcs. The first component of a tuple is an identifier and the second component is its constant value (at this arc). Formally, a pool is an element of

f pool G IdeXVal | (<ide1,val1>&pool \(<ide2,val2>&pool \)
ide1=ide2) => val1=val2 }

Here Ide and Val are sets of identifiers and values (respectively). So-called <u>transfer functions</u> [AhU78,p.497] describe how a pool is transformed when passing through a node.

Data flow information computed by constant propagation is often used for the program transformation "constant folding", which is the "replacement of run-time computations by compile-time computations"[AhU78].

<u>Available Expressions</u> is a "history-sensitive" data flow analysis problem (in the terminology of <code>Ccoc79,p.278J)</code>. We want to determine for each computation of some expression exp whether it "has previously been computed and has suffered no subsequent change in value, where an expression is considered to have changed in value whenever any of the <code>CidentifiersJinvolved</code> in it has changed" <code>CRos79J.</code>

In global analysis one associates with each arc a pool of available expressions, i.e. expressions that have previously been computed and have suffered no subsequent change in value. In this description we have tacitly assumed that sharing does not occur (in accordance with most of the literature). The transfer function is of the form $\lambda \exp(\exp n)$ preserved) u generated, where \exp preserved and generated are subsets of Exp.

<u>Live variables</u> is another "history-sensitive" data flow analysis. Here "we wish to know for Eidentifier] A and Earc] p whether the value of A at p could be used along some path in the ... graph starting at p. If so, we say that A is live at p; otherwise A is dead at p"EAhU78,p.489]. In global analysis one associates a pool of live identifiers to each arc.

We now consider solutions to data flow analysis problems.

Consider a graph representing a program. We assume that the graph contains a unique entry arc (start) and a unique exit arc (stop). We say that ⟨arc1,...,arcn⟩ is a path iff n≥1 and for every i∈{1,...,n-1} that arc[i+1] leaves the node that arci enters. We assume that there is no path of the form ⟨arc,start⟩ or ⟨stop,arc⟩.

Let L be any complete lattice of data flow information, and let init ϵ L. (Many authors have init= \pm and slightly different requirements upon L). For each path of the form $\langle \arctan 2 \rangle$ we are given a forward transfer function Bf $\langle \arctan 2 \rangle$ ϵ L-t>L or a backward transfer function Bb $\langle \arctan 2 \rangle$ ϵ L-t>L. The forward transfer function describes the effect of "going" from arc1 to arc2. The backward transfer function specifies the effect of "going" from arc2 to arc1. When $\langle \arctan 2 \rangle$ and $\langle \arctan 3 \rangle$ arc4> are paths such that arc1 and arc3 enter the same node it is natural to assume that Bf $\langle \arctan 2 \rangle$ = Bf $\langle \arctan 3 \rangle$ arc4> and similarly for Bb. For convenience we define Bf $\langle \arctan 2 \rangle$ = Bb $\langle \arctan 2 \rangle$ and When n>2: Bf $\langle \arctan 2 \rangle$ = Bb $\langle \arctan 2 \rangle$ arcn> • Bf $\langle \arctan 2 \rangle$ and Bb $\langle \arctan 2 \rangle$ and Bb $\langle \arctan 2 \rangle$ = B

Usually one considers a MOP (meet over all paths) solution and a MFP (maximal fixed point) solution. These terms have been coined by authors using lattices dual to ours; as discussed in section 2.1.2 this is of little importance. We define the <u>forward MOP solution</u> (to the data flow analysis defined by Bf):

λarc.U{ Bf<start,...,arc>init | <start,...,arc> is a path}
This formulation essentially is that of [Hec77,p.169]. Similarly, we can define the backward MOP solution (defined by Bb).

To define the <u>forward MFP solution</u> we assume Bf $\langle arc1, arc2 \rangle \in L-i \rangle L$. We define a "system of equations" $F \in (Arc-t \rangle L) -i \rangle (Arc-t \rangle L)$ by $F(inf)(arc) = (arc=start) - \rangle init, U \{ Bf \langle pred, arc \rangle \} is a path \}$

where inf € Arc-t>L. This may be compared to the formulation of [Hec77,p.173] (Kildall's MFP solution) or preferably [Hec77,p.178] (Kam&Ullman's MFP solution). The forward MFP solution is LFP(F) which exists by Theorem 2.1.2-11. Similarly we can define the backward MFP solution.

When Bf<arc1,arc2> (and Bb<arc1,arc2>) are continuous there are iterative methods converging to the MFP solution. When Bf<arc1,arc2> (and Bb<arc1,arc2>) are complete—u—morphisms the MFP solution is equal to the MOP solution, otherwise the MOP solution is better (E) than the MFP solution [CoC79]. One way to obtain the MOP solution (for finite L and Bf<arc1,arc2> and Bb<arc1,arc2> isotone) is the "merge after expansion" algorithm of [Cweg75].

The forward solutions are used for constant propagation and available expressions ("forward analyses"), whereas the backward solutions are used for live variables ("backward analysis"). It is generally assumed that the MOP solution is wanted, but the arguments are intuitive: "It appears generally true that for data flow analysis problem, we search for the 'meet over all paths' solution. Intuitively, this solution is the calculation for each node in the program ... graph of the maximum information, relevant to the problem at hand, which can be derived from every possible execution path from the initial node to that node"[Hec77,p.169].

We distinguish between two ways of defining the lattice L of data flow information: the "independent attribute method" and the "relational method" [JoM78]. In order to explain the two methods imagine that there are n identifiers and a set M whose elements describe properties of the values of one identifier. For the explanation assume that M is Val, the set of values.

In the <u>independent attribute method</u> we have $L=(\mathcal{P}(M))^n$. If let is associated with some arc, then the description of the set of possible values of the j'th identifier is l\(\psi_j\). Most methods in literature and in practice are of this type.

In the <u>relational method</u> we have $L=P(M^n)$. If $l\in L$ is associated with some arc, then the description of the set of possible values for the j'th identifier is $\{v\psi_j|v\in l\}$. In general the relational method is stronger than the independent attribute method, e.g. in our example when determining whether two identifiers have the same value at some arc. But the relational method is potentially of much higher computational complexity than the independent attribute method[JoM78]. In e.g. the determination of linear relationships ([COH78]) it appears mandatory to work from a "kind of" relational method.

2.4 Abstract Interpretation

In this section we explain abstract interpretation. A detailed development of the central concepts is given in subsection 2.4.3. This development extends that of [CoC79] in two ways: We hope our motivation of the definitions ("pair of adjoined functions") gives more insight. Furthermore, we introduce concepts (e.g. "pair of semi-adjoined functions") that are less restrictive than those of [CoC79]. A substantial part of our further development will be performed using these definitions.

The overall motivation underlying abstract interpretation is reviewed in subsection 2.4.1. We also state the key definitions and results of subsection 2.4.3, so that 2.4.3 perhaps can be omitted on a first reading. Some example pairs of adjoined functions are defined in subsection 2.4.2; these are used in section 3.2.

2.4.1 The Overall Motivation

We assume, as in section 2.3, that a program is represented by a graph. By Arc we denote the (finite) set of arcs and by L we denote a complete lattice of data flow information. For the purposes of this explanation it is convenient to think of L as P(Sta), where Sta is the set of program states. Since backward analysis is treated in a way similar to forward analysis [CoC79] we will only consider forward analysis. Let inite be the set of initial states and let Bf<arc1,arc2> describe the effect upon a set of states as a node is traversed. In this way Bf<arc1,arc2> relates to the static semantics of Floyd (see [CoC77a]). By $inf \in Arc-t>L$ we denote a solution to the data flow analysis specified by Bf. It is convenient to think of inf as the MOP solution so that inf(arc) is the set of states that can occur at arc.

One use of inf is to detect the applicability of some program transformation. Many program transformations (e.g. constant folding) can be characterized by some predicate p:Sta->B, so that the transformation may be performed upon some node if: for any one arc arc' entering that node and for any one sta ϵ inf(arc') that p(sta) holds. Define lp={sta|p(sta)}; then this can be expressed by U{inf(arc')| arc' enters the node} \subseteq lp.

Presumably, we want to implement the data flow analysis on a computer. Maybe the solution is not computable, or it takes too much time to compute it, or it takes too much space to store the solution. The remedy we consider is to replace L by another complete lattice M of approximate description elements of L for which the above problems maybe do not arise. We do not consider the widening and narrowing of <code>[CoC77a]</code>.

EXAMPLE 2.4.1-1: Imagine a program with one identifier taking values in the set INT = $\{..., -1, 0, 1, ...\}$ of integers. Then L= \Re INT) and initeL is the set of initial (or input) values. Function Bf $\{arc1, arc2\}:L-\}$ L describes the effect upon the set of possible values when going from arc1 to arc2.

A possible predicate is p(i) = (i=27) from which $lp=\{27\}$. Let inf be the (MOP) solution specifying for each arc the set of values reaching that arc (for some initial value in init). If arc1, ..., arcm are the arcs entering some node n, and if $ll=\{i,i=1,\dots,m\}$ $ll=\{1,\dots,m\}$ $ll=\{1,\dots,m\}$ be then we may hope to perform constant folding on the node n, e.g. replace some use of the identifier with the constant 27.

A possible choice of \mathbb{M}^{\bullet} is the flat lattice INT. The intention is that e.g. $7 \in \mathbb{M}$ corresponds to $\{7\} \in \mathbb{L}$, while $\tau \in \mathbb{M}$ corresponds to any set in L containing two or more constants. This is further developed below.

The data flow analysis problem (as specified in terms of L, init, Bf) is transformed to another data flow analysis problem (specified in terms of M, init', Bf'). Denote by inf:Arc->L and inf':Arc->M the respective solutions. We now consider the connection between the two formulations.

We want to relate M to L in order to make use of the data flow information inf'(arc). We transform inf'(arc) to L rather than inf(arc) to M, because it is in L we have Lp and perform the tests ... Ξ Lp {a}; intuitively speaking, we know how to interpret L&L but not how to interpret m&M. To this end we define a <u>concretization function</u> conc:M->L (denoted γ in [CoC79]). Then inf'(arc) is a representation in M of conc(inf'(arc))&L. It is reasonable to

[{]a} In subsection 2.4.3 we show how to transform the test ... !! p to a test in M.

require that conc(inf'(arc)) <code>Elp => inf(arc) 5 lp</code>, because otherwise it would be hard to see how inf'(arc) could be exploited. Clearly conc(inf'(arc)) <code>Elp => inf(arc) 5 lp</code> holds for any <code>lp iff inf(arc) 5 conc(inf'(arc))</code>. We take this as the desired <code>correctness condition</code> between inf and inf'. That is, we approximate a set of states by (a description of) a larger set of states. — This may be compared to the "make errors on the conservative side" of <code>EAhU78.p.504</code>].

It is convenient also to define an <u>abstraction function</u> uabs:L->M (denoted \triangleleft in [CoC79]). It is used to approximate members of L by members of M, e.g. init' = uabs(init). The condition inf(arc) \subseteq conc(inf'(arc)) for arc=start then amounts to init \subseteq conc(uabs(init)). This motivates:

ASSUMPTION 2.4.1-2: concouabs is extensive.

Following [CoC79] we impose the intuitively desirable:

ASSUMPTION 2.4.1-3: conc and wabs are isotone.

ГЗ

Intuitively, that uabs is isotone means that it "preserves the amount of information": If we get more information in L then we also get more information in M. Similar remarks apply to conc. Technically, in some proofs (e.g. Theorem 3.1-10) our reasoning exploits the isotony of conc. We do not investigate whether assumption 2.4.1-3 can be weakened.

The above assumptions make it reasonable to request <uabs,conc> to be a pair of semi-adjoined functions between L and M:

DEFINITION 2.4.1-4: <uabs,conc> is a pair of semi-adjoined functions (between L and M) iff

- a) uabs € L -i> M
- b) conc € M -i> L
- c) concouabs is extensive

Often we write: "uabs and conc are semi-adjoined" instead of "<uabs,conc> is a pair of semi-adjoined functions".

OBSERVATION 2.4.1-5: uabs and conc are semi-adjoined iff they are isotone and ∀leL,meM: uabs(l)⊆ m => l⊆conc(m). []

If conc is isotone and conc(τ)= τ then there always exists a uabs such that uabs and conc are semi-adjoined, e.g. uabs= λ l. τ .

Sometimes it is desirable that uabs and conc satisfy stronger properties than merely semi-adjoined.

DEFINITION 2.4.1-6: <uabs,conc> is a pair of <u>adjoined</u> functions (between L and M) iff \text{\forall \in \text{W} \in \text{M}: uabs(\l) \in \text{m} <=> \left \text{conc(m).}

In subsection 2.4.3 we motivate this definition and we show that any pair of adjoined functions is also a pair of semi-adjoined functions. One nice property of a pair <uabs,conc> of adjoined functions is that one determines the other, e.g. uabs = $\lambda l. \Pi\{m| conc(m) = l\}$ (Lemma 2.4.3-3). Often we write "uabs and conc are adjoined" instead of "<uabs,conc> is a pair of adjoined functions".

DEFINITION 2.4.1-7: A pair <uabs, conc> of adjoined functions is exact iff uabs • conc = λm_*m

In [CoC79] it is stated that <uabs,conc> is exact iff uabs is onto iff conc is one-one.

EXAMPLE 2.4.1-1(cont.): Define conc:INT $^{\circ}$ -> ρ (INT) by conc(\bot)=0, conc(τ)=INT and conc(i)={i} otherwise. Define uabs: ρ (INT)->INT $^{\circ}$ by uabs(0)= \bot , uabs(i)=i and uabs(i)= τ whenever i contains two or more elements. Then <uabs.conc> is an exact pair of adjoined functions.

An approximate data flow propagation function Bf' may be defined by Bf'<arc> = \(\lambda \text{m.m.} \) Bf'<arc1,arc2> = uabs \(\text{Bf} \) Arc1,arc2> \(\text{conc} \) and when m>2: Bf'<arc1,arc2>; Bf' is induced by <uabs,conc> from Bf. Suppose init' = uabs(init), that inf and inf' are the MOP solutions and that uabs and conc are adjoined. Then \(\text{Coc79,7.1.0.2(2)} \) implies (for a special choice of Bf) that \(\text{Varc: inf(arc) } \text{ } \text{conc(inf'(arc))} \). One can show that \(\text{Varc: inf(arc) } \text{ } \text{conc(inf'(arc))} \) holds when uabs and conc are only semiadjoined provided that \(\text{Varc1, \text{Varc2: Bf<arc1,arc2>} \) is isotone (and init' = uabs(init)).

2-4-2 Defining Example Pairs of Adjoined Functions

In chapter 3 we develop and apply our framework for expressing data flow analyses. For the application we need to define a pair of semi-adjoined functions. Often it is convenient to define a pair <uabs.conc> of semi-adjoined functions by composing others (<uabs.conc>):

LEMMA 2.4.2-1: If <uabsi,conci> (for i (1,...n)) is a pair of semi-adjoined (adjoined) functions between Li and L[i+1] then <uabsn o... ouabs1, conc1 o... oconcn> is a pair of semi-adjoined (adjoined) functions between L1 and L[n+1].

Proof is shown in appendix 2.

In each application one may use pairs <uabsi,conci> that are generally applicable. Typically, <uabsi,conci> depends on the structure of a domain (like those of Table 2.2-B) defined in terms of the usual domain constructors +, χ , -c> and \star . Some of the pairs are best understood as transforming information between a relational formulation and an independent attribute formulation. Below we define such "generally applicable" pairs of semiadjoined functions. We assume that L, Li and M are complete lattices.

Cartesian Product

To transform between independent attribute formulation and relational formulation:

DEFINITION 2.4.2-2: Define concX: $\mathcal{P}(L1)$ XX $\mathcal{P}(Ln)$ -> $\mathcal{P}(L1$ XXLn) by concX< $L1$,, Ln > = {<1,, Ln > $\forall i \in \{1,,n\}$: LieLi}.	
Define uabs $X(\underline{l}) = \langle, \{l \forall i l \in \underline{l}\}, \rangle$.	[]
LEMMA 2.4.2-3: <uabsx,concx> is a pair of adjoined functions.</uabsx,concx>	[]
Proof is shown in appendix 2.	

To assist in building pairs of semi-adjoined functions from others:

DEFINITION 2.4.2-4: If f is a function Li->Mi then (Ci f):L1 χ ... χ Ln -> L1 χ ... χ Mi χ ... χ Ln is defined by Ci f <l1,... χ ln> = <l1,... χ f(li), ... χ ln>

LEMMA 2.4.2-5: If <uabs,conc> is a pair of adjoined functions (semi-adjoined functions) between Li and Mi then <Ci uabs, Ci conc> is a pair of adjoined functions (semi-adjoined functions) between L1X...XLnand L1X.

Finally we need:

DEFINITION 2.4.2-6:

Define uabs:no[i] :L1%...XLn -> L1%...XL[i-1]XL[i+1]X...XLn by uabs:no[i]<\li___,\li

LEMMA 2.4.2-7: <uabs:no[i], conc:no[i]> is an exact pair of adjoined functions between L1X...XLiX...XLn and L1X...XL[i-1]XL[i+1]X...XLn. []

Separated Sum

DEFINITION 2.4.2-8: Define conc+:
$$\mathcal{O}(L1)+...+\mathcal{O}(Ln) \rightarrow \mathcal{O}(L1+...+Ln)$$
 by canc+(m) =
$$\begin{cases} \emptyset & \text{if } m=\bot \\ \{ \text{ li inL}1+...+Ln \mid \text{ li} \in \bot i \} \\ L1+...+Ln & \text{if } m=\tau \end{cases}$$
 Define uabs+ by

LEMMA 2.4.2-9: <uabs+,conc+> is a pair of adjoined functions. []
Proof is shown in appendix 2.

Similarly to Ci we introduce Si:

DEFINITION 2.4.2-10: If f:Li->Mi then (Si f):L1+...+Ln -> L1+...+Mi+...+Ln is defined by

Si f (l) =
$$\begin{cases} T & \text{if } l = T \\ lj & \text{inL1}+...+Mi+...+Ln } & \text{if } l = lj & \text{inL1}+...+Ln } \\ f(li) & \text{inL1}+...+Mi+...+Ln } & \text{if } l = li & \text{inL1}+...+Ln } \\ L & \text{if } l = L \end{cases}$$

LEMMA 2.4.2-11: If <uabs,conc> is a pair of semi-adjoined functions between Li and Mi then <Si uabs, Si conc> is a pair of semi-adjoined functions between L1+...+Ln and L1+...+Mi+...+Ln. If <uabs,conc> is a pair of adjoined functions then so is <Si uabs, Si conc>.

Proof is shown in appendix 2.

<u>Lists</u>

To transform between relational and independent attribute formulation:

DEFINITION 2.4.2-12: Define conc*:
$$(\mathcal{O}(L))^* \rightarrow \mathcal{O}(L^*)$$
 by if $m = \bot$ conc*(m) =
$$\begin{cases} \emptyset & \text{if } m = \bot \\ \{ < l1, \ldots, ln > \mid \forall i \in \{1, \ldots, n\} : \mid i \in m \forall i \} \text{ if } \# \text{ m is the integer n if } m = \top \end{cases}$$
 Define uabs* by uabs*(\underline{L}) =
$$\begin{cases} \bot & \text{if } \underline{L} = \emptyset \\ < \ldots, \{l \forall i \mid l \in \underline{L}\} & \text{if } \exists n \forall l \in \underline{L} \exists l1, \ldots, ln : l = < l1, \ldots, ln > \\ & \text{and } \underline{L} \neq \emptyset \\ & \text{otherwise} \end{cases}$$

LEMMA 2.4.2-13: <uabs*,conc*> is a pair of adjoined functions. []
Proof is similar to the proof of 2.4.2-9. []

Similarly to Ci we introduce S*:

DEFINITION 2.4.2-14: If f is a function L->M then
$$(S^* f) : L^* -> M^*$$
 is defined by $S^* f \perp \perp \perp \perp S^* f r = r$ and $S^* f < \lfloor 1 \rfloor = -1 \rfloor = \langle f(\lfloor 1 \rfloor) \rangle = \langle f(\lfloor 1 \rfloor) \rangle$

LEMMA 2.4.2-15: If <uabs,conc> is a pair of semi-adjoined functions between L and M then <S* uabs, S* conc> is a pair of semi-adjoined functions between L* and M*. If uabs and conc are adjoined then so are S*uabs and S*conc. [] Proof is similar to the proof of 2.4.2-11.

Functions

To transform between relational and independent attribute formulation:

DEFINITION 2.4.2-16: Define conc-c>: (L-t>P(M)) -> P(L-c>M) by conc-c>(g) = {f \in L-c>M | \forall l \in L: f(l) \in g(l)} and uabs-c>(\underline{f}) = λ l.{f(l) | f \in \underline{f} }[]

LEMMA 2.4.2-17: <uabs-c>,conc-c>> is a pair of adjoined functions.

Note that conc-c> maps from L-t> $\mathcal{P}(M)$ and not L-c> $\mathcal{P}(M)$. Similar definitions can be made for conc-i> and conc-t>.

DEFINITION 2.4.2-18: If f:M1->M2 then (R f):(L-t>M1)->(L-t>M2) is defined by R f g = λ L.f(g(L)), i.e. R f g = f o g.

LEMMA 2.4.2-19: If <uabs,conc> is a pair of semi-adjoined (adjoined) functions between M1 and M2 then <R uabs, R conc> is a pair of semi-adjoined (adjoined) functions between L-t>M1 and L-t>M2.

In the above definitions some of the functions ought to have been indexed, e.g. R should be indexed by the complete lattice L. Hopefully this and other omissions do not lead to confusion.

None of $\langle uabs X, conc X \rangle$, $\langle uabs +, conc + \rangle$, $\langle uabs *, conc * \rangle$ or $\langle uabs - c \rangle$, $\langle conc - c \rangle$ is (in general) exact. It would of course be possible to obtain this. But we feel that it is not worth the effort to obtain this: To obtain exactness we would have to introduce new domain constructors, one for each of X, +, * and -c >. To do so would only complicate our notation. Furthermore, we do not need exactness in our later example.

2-4-3 Detailed Development

In subsection 2.4.1 we explained why it was reasonable to require <uabs,conc> to be a pair of semi-adjoined functions and we stated the definition of a pair of adjoined functions. In this subsection we motivate why it is often natural to require that uabs and conc are adjoined.

As in 2.4.1 let L and M be complete lattices. We do not investigate whether weaker conditions are sufficient. In the discussion, but not the formal development, we assume $L=\mathcal{P}(\operatorname{Sta})$ where Sta is the set of program states.

Let <uabs,conc> be a pair of semi-adjoined functions between L and M. This ensures that uabs(l) \in M is a "safe" representation of l: conc(uabs(l)) \in lp => l \in lp. Here we think of l as the set of states occurring at some arc and lp as the set of states for which some program transformation is meaning-preserving.

It may be that the representation uabs(l) of l is coarser than necessary, i.e., conc(uabs(l)) f p even though there is $m \in M$ such that $l \subseteq conc(m) \subseteq lp$. This means that using uabs with uabs (l)=m would enable the application of an otherwise rejected program transformation.

EXAMPLE 2.4.3-1(a): Define L=({l1,l2,l3,l4}, \S) with l1 \S l2 \S l3 \S l4 and M=({m1,m2,m3,m4}, \S) with m1 \S m2 \S m3 \S m4. Define conc:M->L by conc(m4) = l4, conc(m3) = conc(m2) = l3 and conc(m1) = l1. Also l = l2 and lp = l3 and uabs = λ l'.m4. Then <uabs,conc> is a pair of semi-adjoined functions, but conc(uabs(l)) \$\mathbf{l}\$ p even though l \$\Sigma\$ conc(m3) \$\Sigma\$ lp so that e.g. uabs' = (λ l'. l'=l1 -> m1, l' \S l3 -> m3, m4) is preferable to uabs.

In many situations this phenomenon is undesirable. To avoid it we need $(conc \circ uabs)(l) \subseteq \{conc(m) \mid conc(m) \supseteq l\}$ because when $lp = conc(m) \supseteq l$ we want to avoid $(conc \circ uabs)(l) \not\subseteq lp$. (A "realistic" example along these lines is $[coc79_Example 5_1_0_1]$). Since $conc \circ uabs$ is extensive the above condition is equivalent to $conc(uabs(l)) = \Pi\{conc(m) \mid conc(m) \supseteq l\}$. This motivates

DEFINITION 2.4.3-2: <uabs,conc> is a pair of $\underline{\text{guasi-adjoined}}$ functions between L and M iff <uabs,conc> is a pair of semi-adjoined functions between L and M and $\forall l \in L$: $\text{conc}(\text{uabs}(l)) = \Pi\{\text{conc}(m) \mid \text{conc}(m) \ni l\}$.

EXAMPLE 2.4.3-1(b): The pair <uabs,conc> is a pair of semi-adjoined functions that is not quasi-adjoined. The pair <uabs',conc> is a pair of quasi-adjoined functions. Note that uabs' and conc are not adjoined.

To relate the concepts introduced we state:

LEMMA 2.4.3-3: If <uabs,conc> is a pair of adjoined functions then <uabs,conc> is a pair of quasi-adjoined functions and uabs = λ l. Π {m| conc(m)3l} and is a complete-u-morphism and conc = λ m. L{l'| uabs(l') ξ m} and is a complete-n-morphism. [] Proof is shown in appendix 2.

To motivate the definition of adjoined we first consider how to transform the test $l \in l$ to a test in M. It is desirable to find a "safe" test in M, since during data flow analysis we only have M available. We imagine the test in M to be of the form uabs(l) \subseteq dabs(lp) for some function dabs: $l \rightarrow M$. We cannot use dabs = uabs because uabs(l) \subseteq uabs(lp) $\neq > l \in l$ p. Below we

investigate the natural requirements upon dabs; these are dual to the requirements upon uabs.

Since uabs(l) \(\subseteq \text{dabs(lp)} => \text{conc(dabs(lp))} => \text{l \subseteq conc(dabs(lp))} \text{ whenever \subseteq conc\text{ is a pair of semi-adjoined functions it is natural to impose:} \]

ASSUMPTION 2.4.3-4: concodabs is reductive.

and similarly to 2.4.1-3:

ASSUMPTION 2.4.3-5: dabs is isotone.

 \Box

DEFINITION 2.4.3-6: <dabs,conc> is a pair of semi-down-adjoined functions
between L and M iff dabs:L->M is isotone and conc:M->L is isotone and
concodabs is reductive.

OBSERVATION 2.4.3-7: If uabs and conc are semi-adjoined and dabs and conc are semi-down-adjoined then ∀l∀lp: uabs(l) ⊆ dabs(lp) => l⊆lp. []

EXAMPLE 2.4.3-1(c): Define dabs:L->M by dabs = λ l'.m1. Then <dabs,conc> is a pair of semi-down-adjoined functions. Note that uabs(l)#dabs(lp).

Perhaps <uabs,conc> should be called a pair of (semi-,quasi-) up-adjoined functions, but we do not because we only use dabs in this subsection.

Suppose that uabs and conc are semi-adjoined and dabs and conc are semi-down-adjoined. It then may be true that uabs(l) \sharp dabs(lp) even though conc(uabs(l)) \equiv conc(dabs(lp)). Intuitively this means that we cannot exploit in M all the information of uabs(l) and dabs(lp). An example of this is given in 2.4.3-1(d) below. Also it may be that uabs(l) \sharp dabs(lp) even though $\exists m_{\mu} m_{\mu} \in \mathbb{M}$: $m \in m_{\mu} \cap \mathbb{M}$ $\subseteq m_{\mu} \cap \mathbb{M}$ is suggests that using uabs" with uabs"(l)=m and dabs" with dabs"(lp)=mp would be preferable to using uabs and dabs. An example of this is given in 2.4.3-1(d) below.

Often these two possibilities are undesirable. To avoid them we need:

DEFINITION 2.4.3-8: <dabs,conc> is a pair of quasi-down-adjoined functions
between L and M iff <dabs,conc> is a pair of semi-down-adjoined functions and
conc o dabs = \(\lambdall. \L\lambdall. \text{ conc(m) | conc(m)} \) []

DEFINITION 2.4.3-9: <dabs,conc> is a pair of <u>down-adjoined</u> functions between L and M iff dabs:L->M and conc:M->L and ∀l∀m: dabs(l)∃ m <=> l∃ conc(m). []

LEMMA 2.4.3-10: If <dabs,conc> is a pair of down-adjoined functions then <dabs,conc> is a pair of quasi-down-adjoined functions and dabs = λ l'. \square {m| conc(m) \le l'} and is a complete- $_n$ -morphism and conc = λ m. Π {l'| dabs(l') \supseteq m} and is a complete- $_
u$ -morphism. [] Proof is shown in appendix 2.

EXAMPLE 2.4.3-1(d): As an example undesirable property we have uabs(l) \(\frac{1}{2} \) dabs(lp) even though (for m=m2 and mp=m3): \(m \frac{1}{2} \) mp \(\lambda \) leconc(m) \(\lambda \) conc(mp) \(\frac{1}{2} \) leconc(m) \(\lambda \)

Define dabs':L->M by dabs'(l4)=m4, dabs'(l3)=m2, dabs'(l2)=dabs'(l1)=m1. Then $\langle dabs', conc \rangle$ is a pair of quasi-down-adjoined functions that is not also down-adjoined. But even though uabs' and conc are quasi-adjoined we have uabs'(l) $\not\equiv$ dabs'(lp), conc(uabs'(l)) $\not\equiv$ conc(dabs'(lp)) and

 $m = mp \land l = conc(m) \land conc(mp) = lp$. So the undesirable properties are not avoided by requiring both pairs to be "quasi" rather than "semi".

Finally define uabs" by uabs"((1)=m4, uabs"((13)=uabs"((12)=m2, uabs"((11)=m1) and define dabs" by dabs"((14)=m4, dabs"((13)=m2, dabs"((12)=dabs"((11)=m1). Then uabs" and conc are adjoined and dabs" and conc are down-adjoined. Furthermore, uabs'((11)=m1) and uabs"((11)=m1) and uabs"((11)=m1) and uabs"((11)=m1).

Based on the above example it seems natural to require that uabs and conc must be quasi-adjoined and dabs and conc be down-adjoined; or that uabs and conc be adjoined and dabs and conc quasi-down-adjoined. That this works in general follows from:

LEMMA 2.4.3-11: If uabs and conc are adjoined and dabs and conc are quasi-down-adjoined or if uabs and conc are quasi-adjoined and dabs and conc are down-adjoined then for all l, lp:
uabs(l) \(\frac{1}{2} \) dabs(lp) <=> (\frac{1}{2} m, mp: m\text{Emp \(\lambda \) \(\text{E conc(m) \(\lambda \) conc(mp) \(\text{E lp} \)} \)
<=> conc(uabs(l)) \(\frac{1}{2} \) conc(dabs(lp))

Proof is shown in appendix 2.

In appendix 1 we show how dabs can sometimes be defined from uabs.

Discussion

Our definition of a "pair of adjoined functions" (Definition 2.4.1-6) is equivalent to the "pair of adjoined functions" of [CoC79,definition5.3.0.1]. This follows from Lemma 2.4.3-3 which shows that it is not necessary to explicitly require uabs and conc to be isotone. The definitions of semi- and quasi-adjoined as well as (semi-,quasi-) down-adjoined are new.

Below we further compare our development with the literature. The motivation leading to introducing "pair of semi-adjoined functions" is straight-forward. To motivate stronger requirements we considered the phenomenon that conc(uabs(l)) plp even though 3m: L conc(m) clp. We showed that this phenomenon cannot occur when uabs and conc are quasi-adjoined.

The motivation leading to quasi-adjoined has been adapted from [CoC79], section 5.1]. There $M' \subseteq L$ is assumed so that conc: $M' \longrightarrow L$ is $\lambda m.m.$ The motivation of [CoC79] leads to:

ASSUMPTION [Coc79,5.1.0.2]: ∀l∈L: {m'∈M' | | Em'} must have a least element[]

DEFINITION [Coc79,5.2.0.1]: The approximation operator is uco:L->M' defined by uco(l) = η { m' ϵ M' | [ϵ m'}.

That the functionality is right is from the above assumption. Note that uco:L->M' is the approximation operator iff $<uco,\lambda_m.m>$ is a pair of quasi-adjoined functions between L and M'. This remark shows that EcoC79, Theorem 5.2.0.21 is a special case of the more generally applicable:

When [CoC79] considers the connection between uabs and conc (Section 5.3) it is required that <uabs,conc> must be a pair of adjoined functions. In fact, the accompanying explanation argues in favour of <uabs,conc> being an

exact pair of adjoined functions. In other work ([CoC77a], [Cou79]) only exact pairs of adjoined functions are defined (the words "exact" and "adjoined" are not used).

In our view the motivation of <code>[CoC79]</code> only suffices to require that <code><uabs,conc></code> must be a pair of quasi-adjoined functions. To find a satisfactory motivation for the adjoined condition we introduced the dual concepts (semi-, quasi-) down-adjoined. We believe that these concepts are interesting in their own right. Finally, a nice thing about "exact" is that when <code><uabs,conc></code> is an exact pair of adjoined functions then <code>{conc(uabs(l)) | L∈L}</code> and <code>M</code> are isomorphic.

By way of digression we note:

LEMMA 2.4.3-13: An upper closure operator need not be continuous.

Proof is shown in appendix 2.

This shows that we cannot prove [CoC77b, Corollary 4.1.3.2] in our setting.

CHAPTER 3

History-Insensitive Analyses

In section 3.1 we develop a framework that enables us to define a non-standard semantics that specifies data flow information to be associated with a program. The key ingredients in developing this framework are Denotational Semantics and Abstract Interpretation. The framework is applicable to "history-insensitive" analyses. An example is the "constant propagation" analysis formulated in section 3.2. We also compare our formulation of "constant propagation" to other formulations, including that of traditional data flow analysis.

3.1 The General Framework

Intuitively, IstdIprolinp is the result of executing the program pro with input inp. History-insensitive data flow analysis consists in computing properties of the set of states that are possible at some point (of pro) during an execution where inp is any one element of inp, for some subset inp of Inp. Our approach is to consider an interpretation apr such that PaprIprolinp specifies these properties. - As mentioned in section 2.2 we identify a point by a place, i.e. an occurrence and text-string pair.

In this section we define interpretations col, sts and ind. We now briefly relate these to each other and std. Interpretation sts is used to map places to the set of states that are possible there. It thus bears a strong relationship to the static semantics of Floyd (section 2.4.1).

To relate a description of the set of states possible at some place (specified by means of apr) to the actual set of states possible at that place (specified by means of sts) we use the approach of Abstract Interpretation. That is we specify a pair of semi-adjoined functions. Interpretation apr is often defined in terms of sts and the pair of semi-adjoined functions; it is then denoted ind. Interpretation apr or ind used together with the semantic functions is called an approximate semantics (in contrast to the static semantics). We use an approximate semantics to specify the data flow analysis information to be associated with a program.

The connection between sts and ind implies that we can formally relate \mathscr{P} sts \mathbb{F} pro \mathbb{I} and \mathscr{P} ind \mathbb{F} pro \mathbb{I} (Theorem 3.1-10 and Lemma 3.1-12). In contrast, we cannot find a similar formal relationship between \mathscr{P} sts \mathbb{F} pro \mathbb{I} and \mathscr{P} std \mathbb{F} pro \mathbb{I} . To reduce this gap we introduce col: Now \mathscr{P} sts \mathbb{F} pro \mathbb{I} and \mathscr{P} col \mathbb{F} pro \mathbb{I} can be formally related and the connection between col and std is "intuitively clear". The results of chapter 5 and 6 can be viewed as supporting these intuitions.

The "Collecting" Interpretation

We cannot formally prove the correctness of a claim: " \underline{sta} is the set of states that are possible at pla during an execution of pro with input inp ". The claim is operational in nature: we observe an interpreter executing pro and collect the set of states that reach pla. On the other hand \mathcal{P} std \mathbb{E} pro \mathbb{I} is simply a mathematical function so it is meaningless to consider how it is "executed".

We must therefore define what we mean by "the states that reach pla during an execution of pro with input inp ". We <u>define</u> this information to be <code>PcolEproI(inp)(pla)</code> where col is specified in Table 3.1-A. Hopefully, this definition captures the intuitive concept: It is upon this definition we develop our framework for describing data flow analyses, and it is with respect to this definition that we characterize the data flow information specified by ind.

Intuitively, col is only a small extension of std. Domain A is defined as Pla -c> $\mathcal{P}(Sta)$ and the function attach is now given a non-trivial meaning. Thus $\mathcal{P}col\mathbb{E}pro\mathbb{I}(inp)(pla)$ is a set of states.

LEMMA 3.1-1: Table 3.1-A specifies an interpretation.

Proof is essentially the same as that of Lemma 2.2-5.

Technically, all constants, auxiliary functions and primitive functions have been changed as well as domains A and C. Neither continuations (elements of C) nor the function setup can be continuous $\{a\}$. Strictly speaking, the notation col-g=std-g is nonsense because $col-A\neq std-A$. But we will tolerate this loose notation since the same λ -expression may be used to define both.

The central ingredient of col is attach(pla)(c)(sta), that records the fact that the point pla of the program is reached with the state sta. The function records this information by joining it with the result of (c sta). Another possibility would be to use $S = Sta \ X \ (Pla - c> P(Sta))$ as the state and let attach(pla)(c)(s) collect information in s before supplying it to c. An advantage of our approach is that we may obtain data flow information that is not \bot , even for looping programs. This need not be the case in the other approach (because $FIX(g) = \bot <=> g_\bot = \bot$). Unlike the case in section 2.2 it is important to obtain data flow information which is not \bot , even for looping programs.

Data flow information (pertaining to some program pro) is often used to guarantee that applying some program transformation to pro yields an equivalent program. To be useful data flow information therefore must be related to the semantics of pro. When we specify data flow information (by PindIproIinp) we do relate it to PcolIproI. It is therefore undesirable that we cannot characterize PcolIproI in terms of PstdIproI. But even then it is possible to formally prove that the specified data flow information can be used to guarantee that the program transformation applied to pro yields an equivalent program. The results of chapter 6 are useful for doing this. We regard it a major positive virtue of our approach that it can be used to prove program transformations correct with respect to a denotational

[{]a} A reason is that sta1\sta2 ≠> {sta1}\sta2\}; that is: the orderings of Sta and P(Sta) bear little relationship to one another. This is further discussed later in this section and in chapter 7.

```
TABLE 3.1-A --- INTERPRETATION col
  Domains (of col)
    c ∈ C = Sta -t> A
inp ∈ I = Inp
a ∈ A = Pla -c> P(Sta)
sta ∈ S = Sta
      (See Table 2.2-B for) (Pla, Inp, Sta, ...)
 Constants
    col-wrong ∈ C
col-wrong = ⊥
    col-finish ∈ C
col-finish = ⊥
Pseudo-Semantic Functions
    col-\mathcal{B} \in Bas^{\circ} -c> Val

col-\mathcal{B} = std-\mathcal{B}
    col-Ø € Ope o -c>(ValXVal -c>Val)
    col-0 = std-0
Auxiliary Functions
    col-setup € C -c> I -t> A
    col-setup = std-setup
    col-cond € C X C -c> C
       col-Vconc € Sta -c> T
col-Scond € Sta -c> T
col-Bcond € Sta -c> Sta
   col-cond = std-cond
col-Vcond = std-Vcond
col-Scond = std-Scond
col-Bcond = std-Bcond
   col-attach € Pla -c> C -c> C
col-attach(pla)(c)(s) =
(c s) ⊔ _L[{s}/pla]
Primitive Functions
   col-g € Par -t> C -c> C
col-Vg € Par -t> Sta -c> T
col-Bg € Par -t> Sta -c> Sta
   col-g = std-g
col-Vg = std-Vg
col-Bg = std-Bg
```

semantics.

The "Static" Interpretation

Some notion of static semantics is important for formulating an approximate semantics by means of abstract interpretation (e.g. [CoC77a]). Given a set \underline{inp} of inputs the static semantics determines the set of states that are possible at some place during any one execution of the program pro with input \underline{inp} .

We define the static semantics to be $\mathcal{P}_{sts\mathbb{F}pro}\mathbb{I}_{\underline{inp}}$ where sts is specified in Table 3.1-B.

```
TABLE 3.1-B --- INTERPRETATION sts
Domains (of sts)
   c \epsilon C = \rho(Sta) -c> A

inp \epsilon I = \rho(Inp)

a \epsilon A = Pla -c> \rho(Sta)
   sta \in S = P(Sta)
Constants
   sts-wrong € C
   sts-wrong = 1
   sts-finish € C
   sts-finish = 1
Pseudo-Semantic Functions
   sts-B € Bas o -c> Val
   sts-B = std-B
   sts-\mathscr{O} \epsilon Ope ^{\circ} -c> (Val X Val -c> Val) sts-\mathscr{O} = std-\mathscr{O}
Auxiliary Functions
   sts-setup € C -c> I -c> A
   sts-setup c inp = c {<\lambda ide "'nīt" inVal, inp, <>, <>> | inp\elimp}
   sts-cond € C X C -c> C

sts-Dt-cond € S -c> S

sts-Df-cond € S -c> S
   sts-cond(c1,c2) sta = c1(sts-Dt-cond(sta)) u c2(sts-Dt-cond(sta))
   sts-Dt-cond(sta) = {std-Bcond(sta) = std-Scond(sta) = true}

sts-Df-cond(sta) = {std-Vcond(sta) = true}
      \{\text{std-Bcond}(\overline{s}\overline{t}a) \mid \text{sta}\underline{\epsilon}\underline{s}\underline{t}\underline{a} \land \text{std-Vcond}(sta)=\text{true} \land \text{std-Scond}(sta)=\text{false}\}
   sts-attach € Pla-c>C-c>C
   sts-attach(pla)(c)(sta)
      (c sta) u (L[sta/p[a])
Primitive Functions
   sts-g € Par -t> C -c> C
  sts-Dg ∈ Par -t> S -c> S

sts-Dg(c)(sta) =

c(sts-Dg(par)(sta))
  sts-Dg(par)(sta) = (std-Bg(par)(sta) = true)
```

```
LEMMA 3.1-2: Table 3.1-B specifies an interpretation.

Proof is shown in appendix 3.
```

In Table 3.1-B functions Dg (for "do") intuitively correspond to the Bf<arc1, arc2> of sections 2.3 and 2.4. Because of our previous discussion of col it appears reasonable to require that \mathfrak{P} sts \mathbb{E} pro \mathbb{E} inp = \mathbb{E} fcol \mathbb{E} pro \mathbb{E} inp |inp \in inp}. Unfortunately, this is not always the case. By Theorem 3.1-6 below the result does hold if \mathbb{E} inp \in inp: topfree \mathbb{E} Inp \mathbb{E} (inp). Here topfree is defined as follows:

```
DEFINITION 3.1-3:
```

1) If L is flat then topfree[L]:L->B is topfree[L](l) = $(l \neq \tau)$

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- 2) topfree[L1+...+Ln] : L1+...+Ln->B is topfree[L1+...+Ln](l) = $(l \neq \tau \land [l = (li inL1+...+Ln) = topfree[Li](li)])$
- 3) topfree[L1X...XLn] : L1X...XLn→B is topfree[L1X...XLn]<l1,...,ln> =
 (∀i∈{1,...,n}: topfree[Li](li))
- 4) topfree[L*]: L*->B is topfree[L*](l) = (l≠ ¬ [l=<l1,...,ln> => ∀i∈{1,...,n}: topfree[L](li)])

We do not believe it is restrictive only to consider \underline{inp} such that $\forall inp \in \underline{inp}$: topfree[Inp](inp). One reason is that many programs pro have \mathcal{P} colEproIinp = λ pla.Sta whenever topfree[Inp](inp) = false. An example is pro = BEG DCL x:=0 IN READ x END for inp = τ (see col-read). When inp $\in \underline{inp}$ this implies $\mathbb{L}\{\mathcal{P}$ colEproI inp $|inp \in \underline{inp}\} = \lambda pla.Sta$ so that we cannot use the data flow information for anything. In fact an intuitively desirable choice of \underline{inp} seems to be $\{inp \mid inp \in \underline{Inp} \land pure[Inp](inp)\}$.

Before we show the connection between interpretations col and sts we need to impose some assumptions that will be needed in the proof.

ASSUMPTION 3.1-4: \(\forall \text{baseBas: topfree[Val](std-\(\mathbelde{B}\)\) and \(\forall \text{ope}\)\(\epsilon \text{opfree[Val](val2)} => \)\(\text{topfree[Val](std-\(\sigma\)\)\(\text{ope}\)\(\forall \text{opfree[Val](val2)}) \(\text{Infinity} \)

OBSERVATION 3.1-5: For oo:LXL->M any one of ++, ^^, vv, << we have topfree[L](l1) ^ topfree[L](l2) => topfree[M](l1 oo l2) for suitable L and M.

THEOREM 3.1-6: If \(\forall \text{inp} \in \text{inp} \text{inp} \text{inp} \text{topfree[Inp](inp) then} \)

\$Psts\(\text{Eprolinp} = \text{U} \in \text{Ptol}\(\text{Eprolinp} \) | in \(\text{p} \in \text{inp}\)

Proof is shown in appendix 3.

This theorem may be compared with [CoC77a,p.240] where a static semantics (corresponding to sts) is related to an operational semantics ("corresponding" to col): see conditions (α) and (β) in that paper.

Part of the proof of Theorem 3.1-6 is to show that "r cannot occur". One could as in [Sto77,p.203] state a lemma saying so, but we believe that our formulation is precise.

<u>Store Semantics versus Standard Semantics</u>: In section 2.2 we chose to use a kind of store semantics. This is because the obvious analogue of sts as a standard semantics does not fulfil Theorem 3.1-6. This "obvious analogue" would have $\mathcal{P}(\text{EnvXInpXOut})$ and (indirectly) ($\mathcal{P}(\text{Val})$)* rather than $\mathcal{P}(\text{EnvXInpXOutXVal}^*)$ which is more relational. It is easy to give example programs such that Theorem 3.1-6 would not hold for this version of sts.

The "Induced" Interpretation

For the same reasons as in section 2.4.1 it is for computational purposes desirable to replace the use of sts by some interpretation apr that does not use $\mathcal{P}(Sta)$. We require apr to be an approximate interpretation:

DEFINITION 3.1-7: An <u>approximate interpretation</u> is an interpretation having I=P(Inp), A=PIa-c>S and $C \le S-i>A$.

OBSERVATION 3.1-8: sts is an approximate interpretation.

Let apr1 (e.g. sts) and apr2 be two approximate interpretations. Assume that <uabs,conc> is a pair of semi-adjoined functions between apr1-S and apr2-S. If we want to use apr2 instead of apr1 then, much as in section 2.4, we want \(\forall \text{inp} \in \mathbb{R}(\text{Inp}): \mathbb{Papr1}\text{Eproling} \overline (R conc) (\mathbb{Papr2}\text{Eproline}) \(\text{where } R \) is as in 2.4.2-18. An alternative would be (R uabs) (\mathbb{Papr1}\text{Eproline}) \(\varphi\)

Papr2\text{Eproline}, but our choice is preferable because it is immune to a bad choice of uabs.

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It is convenient to find a "local test" apr1 ⊆<uabs,conc> apr2 implying ∀inp: Papr1 EproIinp ⊆ (R conc) (Papr2 EproIinp) but easier to apply:

DEFINITION 3.1-9: Let apr1 and apr2 be approximate interpretations and <uabs,conc> a pair of semi-adjoined functions between apr1-S and apr2-S. Define P-C: (apr1-C X apr2-C) ->B by P-C(apr1-c, apr2-c) = (apr1-c o conc S (R conc) o apr2-c). Then we write apr1 5<uabs,conc> apr2 iff

- a) P-C(apr1-wrong, apr2-wrong) and P-C(apr1-finish, apr2-finish)
- b) P-C(apr1-c1,apr2-c1) A P-C(apr1-c2,apr2-c2) => P-C(apr1-cond(apr1-c1,apr1-c2), apr2-cond(apr2-c1,apr2-c2))
- c) P-C(apr1-c,apr2-c) =>
 P-C(apr1-attach(pla)(apr1-c), apr2-attach(pla)(apr2-c))
- d) P-C(apr1-c,apr2-c) => $\forall inp \in \mathcal{O}(Inp)$: apr1-setup(apr1-c) $\underline{inp} \in (R \text{ conc}) (apr2-setup(apr2-c) <math>\underline{inp}$)
- e) For all primitive functions g ∈ Par -t> C -c> C that P-C(apr1-c,apr2-c) => P-C(apr1-g(par)(apr1-c), apr2-g(par)(apr2-c)) []

We have chosen to let all approximate interpretations have $I = \mathcal{P}(Inp)$ rather than assuming the existence of a pair of semi-adjoined functions between apr1-I and apr2-I. This makes the notation less involved.

THEOREM 3.1-10: If <uabs,conc> is a pair of semi-adjoined functions and apr1 F<uabs,conc> apr2 then
\finp \int P(\text{Inp}): \forall pro\int Pro\int Papr1 \text{Ipro} \forall inp \int (R conc) (Papr2 \text{Ipro} \forall inp) []
Proof is shown in appendix 3.

This theorem only assumes that <uabs,conc> is a pair of semi-adjoined functions. Related theorems, with more or less the same underlying motivation, are given in [CoC79, section7.1] but there <uabs,conc> is assumed to fulfil the stronger condition of being a pair of adjoined functions, although the proofs seem only to use properties of semi-adjoined functions.

Let S be a complete lattice and <uabs,conc> a pair of semi-adjoined functions between $\mathcal{P}(Sta)$ and S. It is useful to define an approximate interpretation that is "induced by" <uabs,conc> from sts. Table 3.1-C defines this interpretation ind, called the <u>induced interpretation</u>. We sometimes write ind<uabs,conc> to be precise about the pair of semi-adjoined functions used. - This notion of induced is similar to the one mentioned in section 2.4.1.

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LEMMA 3.1-11: Table 3.1-C specifies an approximate interpretation.
   Proof is similar to the proof of Lemma 3.1-2.
   The usefulness of ind is guaranteed by
LEMMA 3.1-12: sts =<uabs,conc> (ind<uabs,conc>)
   Proof is shown in appendix 3.
                                                    TABLE 3.1-C --- INTERPRETATION ind
                                                    THE COLUMN TWO COLUMN 
                                                    Domains (of ind)
                                                           c & C = S - i > A

inp & I = P(Inp)

a & A = Pla - c > S

s & S
                                                                                                                        uabs: P(Sta) -> S conc: S -> P(Sta)
                                                   Constants
                                                           ind-wrong € C
ind-wrong = 1
                                                            ind-finish € C
                                                           ind-finish = 1
                                                   Pseudo-Semantic Functions
                                                            ind-B € Basº -c> Val
                                                           ind-B = std-B
                                                           ind-∅ € Ope° -c> (Val X Val -c> Val)
                                                           ind-0 = std-0
                                                   Auxiliary Functions
                                                          ind-setup € C -c> I -i> A
ind-setup c inp =
c( uabs {<$\overline{\chi}$ind="nil"inVal, inp, <>, <>> |inpeinp})
                                                          ind-cond € C X C -c> C
ind-Dt-cond € S -i> S
ind-Df-cond € S -i> S
                                                          ind-cond(c1,c2) s =
c1(ind-Dt-cond(s)) \( \text{c2}(ind-Dt-cond(s)) \)
ind-Dt-cond =
                                                                  uabs • sts-Dt-cond • conc
                                                           ind-Df-cond =
                                                                  uabs osts-Df-condoconc
                                                          ind-attach @ Pla -c> C -c> C
ind-attach(pla)(c)(s) =
  (c s) u (u[s/pla])
                                                  Primitive Functions
                                                         ind-g & Par -t> ( -c> (
ind-Dg & Par -t> S -i> S
ind-g(par)(c)(s) =
c(ind-Dg(par)(s))
ind-Dg(par)(s) =
```

One nice property of ind is the following. Suppose apr is any approximate interpretation with apr-S = (ind<uabs,conc>)-S. Then $<\lambda$ s.s, λ s.s> is a pair of adjoined functions between S and S, and

uabsosts-Dg(par)oconc

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LEMMA 3.1-13:

- 1) ind<uabs,conc> 5<\lambdas.s,\lambdas.s> apr => sts 5<uabs,conc> apr
- 2) If <uabs,conc> is an exact pair of adjoined functions then ind<uabs,conc> 5<\lambdas.s>\lambdas.s> apr <=> sts 5<\uabs,conc> apr.
 Proof is shown in appendix 3.

The Lemma states that whenever <uabs,conc> is an exact pair of adjoined functions then ind<uabs,conc> is, in some sense, "the best upper approximation to sts". This may be compared with <code>[CoC79, section7.2]</code> where <uabs,conc> only needs to be a pair of adjoined functions. By a slight change of Table <code>3.1-C</code> (e.g. ind-g(par)(ind-c) = R(uabs o conc) o ind-c o ind-Dg(par) instead of the earlier ind-c o ind-Dg(par)) it appears that we can weaken "exact" to "uabs o conc is continuous" (for Lemma <code>3.1-11</code> to hold). However, we choose not to do this.

Properties of approximate and induced interpretations

The definition of ... \(\subseteq\) conc>... is not the only possible one. Three other ways of defining P-C (and thereby ... \(\subseteq\) conc>...) are

P-C1(apr1-c,apr2-c) = [(R uabs) o apr1-c o conc = apr2-c]

 $P-C2(apr1-c,apr2-c) = E(R uabs) \circ apr1-c = apr2-c \circ uabs]$

P-C3(apr1-c,apr2-c) = Eapr1-c 5 (R conc) • apr2-c • uabs]
Let P-C be the predicate used in 3.1-9. For <uabs,conc> a pair of adjoined functions all of P-C, P-C1, P-C2 and P-C3 are equivalent, whereas for <uabs,conc> a pair of semi-adjoined functions they can be different.
Predicates P-C1 and P-C2 are not desirable because then we cannot show sts 5<uabs,conc> ind. Predicate P-C implies P-C3 so we have chosen the stronger predicate. We regard it desirable that P-C does not depend on uabs.

Theorem 3.1-10 assures us that the "local test" apr1 \le <uabs,conc> apr2 implies the "global test" \forall pro \forall inp: \mathcal{P} apr1 \mathbf{F} pro \mathbf{I} inp \mathbf{S} (R conc)(\mathcal{P} apr2 \mathbf{F} pro \mathbf{I} inp). We do not have the converse result, contrary to the situation in \mathbf{I} CoC79, section7.1]. We now intuitively explain why this is so. Suppose apr1 \mathbf{Y} <uabs,conc> apr2 because some primitive function g does not fulfil condition "e)" of Definition 3.1-9. Then we want to find pro and inp such that \mathbf{P} apr1 \mathbf{F} pro \mathbf{I} inp \mathbf{Y} (R conc)(\mathbf{P} apr2 \mathbf{F} pro \mathbf{I} inp). Intuitively we want pro to supply g with some c and s that make "e)" of 3.1-9 fail. But it may be that such a program pro does not exist, because the semantic equations impose restrictions upon the parameters that g can possibly get.

We do not regard it as a disadvantage of our approach that the converse result of 3.1-10 does not hold. Indeed, one of the motivations behind introducing "interpretation" was to avoid that our development depends strongly on one particular language. There are, however, methods that may be used to avoid apr1 \$\frac{\pi}{\text{uabs,conc}}\$ apr2 when \$\frac{\pi}{\text{proVing:}}\$ Papr1 \$\text{EproVing}\$ (R conc)(Papr2 \$\text{EproVing}\$). One method is to replace C and S by smaller domains. As an example, C of sts may be replaced by the set of complete——morphisms from S to A. If this method is not sufficient then one may restrict the continuations (c) and states (s) to be considered in "e)" of 3.1-9.

One way to compare approximate interpretations is apr1 $\stackrel{=}{\sim}$ (uabs,conc) apr2. Below we restrict ourselves to induced interpretations ind $\stackrel{<}{\sim}$ uabs,conc) where $\stackrel{<}{\sim}$ (uabs,conc) is a pair of adjoined functions (between $\stackrel{\sim}{\sim}$ (Sta) and a complete lattice S) with uabs(τ)= τ . Then we can give results corresponding to the "hierarchy of program analysis frameworks" of ECoC79,section 8].

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For any two induced interpretations ind1=ind<uabs1,conc1> and ind2=ind<uabs2,conc2> we may want to find a "local test" that implies \forovinp: (R conc1)(\mathcal{P}ind1\text{Eprolinp}) \subseteq (R conc2)(\mathcal{P}ind2\text{Eprolinp}). The test ind1 \forall \text{-uabs,conc} ind2 depends on the choice of \forall \text{-uabs,conc} and we want to avoid having to choose \forall \text{-uabs,conc}. That this is possible follows from Lemma 3.1-15 below. The proof uses the following lemma that shows that conc \circ \text{-uabs} essentially determines how approximate ind<uabs,conc> is.

- LEMMA 3.1-14: Let <uabs,conc> be a pair of adjoined functions between $\mathcal{O}(Sta)$ and some complete lattice S such that uabs(τ)= τ . Then <conc uabs, $\lambda \underline{sta} \underline{sta}$ is a pair of semi-adjoined functions and $\forall pro \forall \underline{inp}$:

 (R uabs)($\mathcal{P}(ind < conc uabs, \lambda \underline{sta} \underline{sta} >) \mathbb{E}pro \mathbb{I}\underline{inp}) = \mathcal{P}(ind < uabs, conc >) \mathbb{E}pro \mathbb{I}\underline{inp}$ [] Proof is shown in appendix 3.
- LEMMA 3.1-15: Let <uabs1,conc1> and <uabs2,conc2> be pairs of adjoined functions (between $\mathcal{P}(Sta)$ and complete lattices S1 and S2, respectively) such that uabs1(τ)= τ and uabs2(τ)= τ . If conc1o uabs1 \subseteq conc2o uabs2 then \forall pro \forall inp: (R conc1)(\mathcal{P} ind<uabs1,conc1> \exists pro \exists inp) \subseteq (R conc2)(\mathcal{P} ind<uabs2,conc2> \exists pro \exists inp) \subseteq Proof is shown in appendix 3.

One can view ind<conc • uabs, $\lambda \underline{sta} \cdot \underline{sta}$ as a representative of a set of induced interpretations {ind<uabs',conc'>| conc' • uabs' = conc • uabs}. With a slight change of our definition of induced interpretation we can show that these representatives form a complete lattice.

LEMMA 3-1-16:

Proof is shown in appendix 3.

{uco | uco: $\theta(\text{Sta}) \rightarrow \theta(\text{Sta})$ is an upper closure operator} = {conc • uabs| <uabs, conc> is a pair of adjoined functions between $\theta(\text{Sta})$ and some complete lattice S, and such that uabs(τ)= τ }. Proof is shown in appendix 3.

LEMMA 3.1-17: Abbreviate $id=\lambda_{\underline{sta}.\underline{sta}}$ and assume ind<uabs,conc> also contains a primitive function dummy = $\lambda_{c.c} \circ \text{conc} \circ \text{uabs}$. Let uco1 and uco2 be upper closure operators on $\mathcal{O}(\text{Sta})$. Then uco1 \subseteq uco2 <=> (ind<uco1,id>) \subseteq <id,id> (ind<uco2,id>)

- LEMMA 3.1-18 [CoC79,Th.8.0.1][War42,Th.5.3]: The set of upper closure operators on a complete lattice is a complete lattice.
- COROLLARY 3.1-19: If ind<uabs,conc> also contains a primitive function dummy = $\lambda c.c \circ conc \circ uabs$ then {ind<conc $\circ uabs$, $\lambda \underline{sta}.\underline{sta}$ | <uabs,conc> is a pair of adjoined functions between $\mathcal{P}(Sta)$ and some complete lattice S such that $uabs(\tau) = \tau$ } is a complete lattice ordered by $... \le \langle \lambda \underline{sta}.\underline{sta} \rangle \lambda \underline{sta}.\underline{sta} \rangle ...$

We have used "pair <uabs,conc> of adjoined functions with uabs(τ)= τ " rather than "exact pair <uabs,conc> of adjoined functions". This is because the pairs of adjoined functions <uabs λ , conc λ , <uabs+,conc+>, <uabs*,conc*> and <uabs-c>,conc-c>> are not exact but do have uabs...(τ)= τ .

Discussion

In developing the preceeding framework we have chosen one particular route of development. This is not the only one. One of the "arbitrary" decisions was to make a collecting interpretation (col) before we considered interpretations involving sets of states (sts and ind). Consider developing directly from std an interpretation int involving sets of states. Then int and std would be related as are sts and col. Some problems then would occur: The std interpretation has std-C = Sta -c> A whereas presumably int-C = $\theta(\text{Sta})$ -c> $\theta(\text{A})$. The proof of the analogue of Theorem 3.1-6 probably would involve P-C:(std-CXint-C)->B defined by P-C(std-c,int-c) = $\forall \text{sta}$: {std-c(sta) | staesta} = int-c(sta). Unfortunately, P-C(1,1)=false which causes problems in the structural induction (the WHILE loop). A possible remedy is int-C = $\theta(\text{Sta})$ -c> { $a \in \theta(\text{A})$ | $a \in \theta(\text{A})$ | $a \in \theta(\text{Sta})$ -c> { $a \in \theta(\text{A})$ | $a \in$

We have found it convenient to use $\mathcal{O}(Sta)$ in order to employ the framework of P.Cousot&R.Cousot. Since it is not obvious how to define reflexive domains involving powersets we have avoided reflexive domains. This implies that we are unable to handle language constructs like procedures, jumps, VALOF..., RESULTIS....

Since these restrictions are severe we informally explain why we have been unable to find a LAMBDA-definable domain ("Scott domain") that may be used instead of $\mathcal{P}(\operatorname{Sta})$.

Let T"=({yes,no}, \subseteq) where t1 \subseteq t2 <=> (t1 \neq yes \vee t2 \neq no). Then $\mathcal{P}(Sta)$ and Sta -t> T" are lattice isomorphic (see EGr#73] for definitions). But Sta -t> T" is not LAMBDA definable and we would have to use Sta -c> T". We discuss some drawbacks of Sta -c> T" (actually of Sta -i> T" \supseteq Sta -c> T") below:

- a) Suppose pro at occ is an expression with constant value val such that pure[Val](val). A possible program transformation would replace the expression by a constant evaluating to val. But r≥val implies that there is no a ∈ Pla -c> Sta -c> T" such that a<occ,"exp)"> <env,inp,out,wit> = yes => wit ∀1 = val. To be able to represent the desired information we probably would have to work with {sta∈Sta| topfree[Sta](sta)} (which is not a complete lattice) rather than Sta. We prefer, however, to stay within the more or less standard framework of [Sto77], i.e. to use complete lattices.
- b) Suppose we have storable continuations. From an informal sketch of the std ==> col ==> sts development we are lead to believe that the problems will be even more severe than in the above case. When a stored continuation is applied (in sts) the resulting data flow information is likely to be >pla.Sta, i.e. completely useless. It appears that the problems are not remedied by using {sta \in Sta | topfree[Sta](sta)}.

Some alternatives to Sta -c> T" are Sta -c> T or Sta -c> T', where T' is the dual lattice of T"[MiS76]. But this does not seem to be appropriate either.

For some simple languages we probably could introduce procedures, labels and VALOF..., RESULTIS... if we had worked from a standard semantics employing a two-stage mapping: [Nie79] gives an example showing that the standard semantics needs not contain reflexive domains even if the store semantics does. But if we work from a standard semantics then Theorem 3.1-6 will not hold.

3.2 Example and Comparison with other Approaches

In this section we show how the general framework of section 3.1 can be used to derive a formulation of the data flow analysis "constant propagation". We then compare our method (as exemplified by the constant propagation example) to methods described in the literature. These are the "traditional data flow analysis" concept of constant propagation, the methods of Donzeau-Gouge and the method of Cousot&Cousot.

It is convenient to specify our constant propagation example as an instance of a class of data flow analyses, which we shall call "value subset analysis". Let Val be the complete lattice of Table 2.2-B. Then a "value subset analysis" is specified by a pair $\langle uabsVa, concVa \rangle$ of semi-adjoined functions between $\mathcal{P}(Val)$ and a complete lattice Va. This pair is used to define the pair $\langle uabs, conc \rangle$ of semi-adjoined functions (explained below): $uabs = \langle uabs:no2 \rangle$ \circ $\langle uabs:no3 \rangle$

C4E(S* uabsVa) o uabs*] o

C1[(R uabsVa) • uabs-c>] •

uabsX

conc = concXº

C1 [conc-c> o (R concVa)] o

C4Econc* • (S* concVa)] •

(conc:no3) o (conc:no2)

Functions C1, uabs*, ... are defined in section 2.4.2. By Lemma 2.4.2-1:

OBSERVATION 3.2-1: If <uabsva, concva> is a pair of semi-adjoined (adjoined) functions between $\mathcal{P}(Val)$ and Va then <uabs, conc> is a pair of semi-adjoined (adjoined) functions between $\mathcal{P}(Sta)$ and (Ide $^{\circ}$ -t> Va) X Va*.

The first task of uabs is to bring $\mathcal{P}(\text{EnvXInpXOutXWit})$ to independent attribute form $\mathcal{P}(\text{Env}) \times \mathcal{P}(\text{Inp}) \times \mathcal{P}(\text{Out}) \times \mathcal{P}(\text{Wit})$. Then the environment $\mathcal{P}(\text{Ide}^{\circ}-c>\text{Val})$ is changed to $\text{Ide}^{\circ}-t>\mathcal{P}(\text{Val})$ and then to $\text{Ide}^{\circ}-t>\text{Va}$ by use of uabsVa. The witnessed stack is changed from $\mathcal{P}(\text{Val}^{*})$ to $(\mathcal{P}(\text{Val}))^{*}$ and then to Va^{*} by use of uabsVa. Finally the input and output are removed. Note that the order of uabs:no2 and uabs:no3 is crucial.

Several data flow analyses are special kinds of value subset analyses. They include type-determination, constant propagation and the analysis of signs of numerical values. In the formulation of <uabsVa,concVa> it may be useful to employ <uabs+,conc+> and S[i] of section 2.4.2.

Below we specify a constant propagation example because this data flow analysis is found in both "traditional data flow analysis" and [Don79]. We do this by specifying Va and <uabsVa,concVa>.

We define Va = Valv{all,none} with partial order Ξ such that val Ξ va2 <=> (va1=none V va1=va2 V va2=all); hence (Va, Ξ) is a flat lattice. We define concVa:Va->P(Val) by concVa(all) = Val, concVa(none) = \emptyset and concVa(val) = {val} otherwise. Also uabsVa(\underline{val}) = Π {va | concVa(va) \exists \underline{val} }. Clearly <uabsVa,concVa> is an exact pair of adjoined functions.

Comparison with traditional data flow analysis

The traditional notion of constant propagation was reviewed in section 2.3. To develop a more or less similar constant propagation example in our framework we use <uabsVa, concVa> and <uabs, conc> as specified above. Since traditional constant propagation associates information only with exits of

basic blocks we redefine:

ind-attach pla c s =

 $(plaV2=="cmd)" \rightarrow (c s) u \perp [s/pla], (c s))$

Hence, information is only associated with exits of commands. Although exits of commands only roughly correspond to exits of basic blocks we regard the relationship as reasonable. An advantage of our approach is that it unifies global and local analysis because it treats commands and expressions in the same way.

Since \mathcal{P} ind \mathbb{E} proling \in Pla -c> ((\mathbb{I} de° -t> Va) \mathbb{X} Va*) we can construct a "constant pool" at pla by: {(\mathbb{I} de, va) | va=(\mathcal{P} ind \mathbb{E} proling pla) \mathbb{Y} 1 \mathbb{E} ide \mathbb{X} va* {all, none}. This shows a rather close correspondence between the form of the answer expected in traditional data flow analysis and the one we specify. One minor difference is that we work with complete lattices (hence \mathbb{X} , \mathbb{Y} , none, all) whereas traditional data flow analysis only considers sets and therefore does not consider \mathbb{Y} and \mathbb{X} elements.

This correspondence between traditional data flow analysis and our method only considers the form of the solution. It must be complemented by the results of chapter 5 where we show that $\mathcal{P}ind\mathbb{E}pro\mathbb{I}\underline{inp}$ is the MOP solution to a certain (traditional) data flow analysis problem. This MOP solution might not be computable.

Comparison with [Don79]

Since [Don79] is not widely available we briefly overview it below. Sections 1 to 4 of that paper define a toy language, which extends our language to contain VALOF... and RESULTIS... constructs. The semantics is a standard semantics (not store semantics) that employs a 1-stage mapping between identifiers and values (i.e. no locations). The meaning function $\mathcal P$ for programs is of functionality Pro -c> Inp -c> Out where $\mathcal P$ Ipro $\mathcal I$ inp is the result of "executing" pro with input inp. The "domains" are restricted to be the partially ordered sets that can be defined in DSL[Mos79]. One consequence is that almost no "domain" contains top-elements; thus virtually no complete lattices can be defined.

Sections 5, 6 and 7.1 develop her method and apply it to a constant propagation example. Her notion of constant propagation is slightly different from the traditional concept: she directly associates expresions with their possible values. In the traditional approach one performs global analysis to obtain a pool at each command—exit, and assumes that an unspecified local analysis from these pools associates expressions with values.

The non-standard semantics of sections 5, 6 and 7.1 has $\mathcal{P} \in \text{Pro} - c > \text{Inp'} - c > 0cc - c > \text{Prop.}$ For the purposes of this presentation one can think of Inp' as $\mathcal{P}(\text{Inp})$. Domain 0cc is used in the same way as we use Pla. Domain Prop is essentially $\{x \mid x \in \mathbb{N} + T + \{\text{"var"}\}_{\Lambda} \text{topfree}[\mathbb{N} + T + \{\text{"var"}\}_{\Gamma}(x)\}$ that plays the role of Val. A subtle difference that we ignore is that + is a kind of coalesced sum. To explain in our notation the intention of Prop we define V= $\{x \in \mathbb{N} + T \mid \text{topfree}[\mathbb{N} + T](x)\}$ and the function conc': $\text{Prop} > \mathcal{P}(V)$ by

conc'("var") = V

conc'(t inProp) = { t inN+T, \bot }

conc'(n inProp) = { n inN+T, $_{\perp}$ }

 $conc'(\bot) = \{\bot\}$

It is somewhat unclear to us whether { t inN+T} or { t inN+T, \bot } should be used above. We suspect it is { t inN+T, \bot }.

This connection between $\mathcal{P}(V)$ and Prop cannot be described by a pair of semi-adjoined functions, because uabs'(V) = "var" implies that uabs' cannot

be isotone. If Prop had been Vu{"var"} with "var" as the top-element then this complication would not arise; but this domain is <u>not</u> definable in DSL.

The non-standard semantics of [Don79] contains attach functions in the semantic equations for expressions only. Essentially their purpose is as in our approach. The non-standard semantics has Sta = Exp - c > Prop rather than Sta = Ide - c > Prop. Also several "update" functions (to update the state) are placed in conjunction with the attach function: This appears to be necessary for her "common subexpression elimination" example (section 7.2), but unimportant for the constant propagation example. In our formulation (Table 2.2-C) we have no function that is used as [Don79] uses update.

To develop a more or less similar constant propagation example we use ind<uabs,conc> where <uabsVa,concVa> is as earlier (and determines <uabs,conc>). Since we have placed an attach function in all semantic equations, not only those pertaining to expressions, we redefine ind-attach to:

ind-attach pla c s = $(pla\psi2=="exp)" \rightarrow (c s) = [s/pla], (c s))$

The functionality of \mathcal{P} ind \mathbb{E} prod \mathbb{E} is Pla -c> ((Ide -t> Va) \mathbb{X} Va \mathbb{X}). To obtain a result on the same form as that of \mathbb{E} Don79] we write

When we proved ind correct we showed (Theorems 3.1-6 and 3.1-10 and Lemma 3.1-12) that for $inp \le \{inp \in Inp \mid topfree \in Inp \}$:

 $\mathbb{I}\{\mathcal{P}_{col}[proling] | inp \in inp\} \subseteq (R conc)(\mathcal{P}_{ind}[proling))$

A proof of correctness is also given in [Don79]. To explain this proof we informally sketch how to conduct a similar proof in our setting.

First define a "trace"-interpretation tra that mostly is the same as col. Some changes are

tra-A = {0,1,2,...} -t> (PlaXSta)

tra-attach pla c sta =

pla \forall 2="exp)"->(λ n. n=0-> <pla,sta> in(PlaXSta)°, c(sta)(n-1)), c(sta) It seems plausible to conjecture that \mathcal{P} colEprolinp = build(\mathcal{P} traEprolinp) where build:tra-A -> col-A is

build(tra-a)pla = {sta |∃n: tra-a(n) = <pla,sta> in(PlaXSta)°}

Let \underline{inp} be as above and $\underline{inp} \in \underline{inp}$, n and pla arbitrary. Then we must show that $\mathbb{E} < \underline{pla}$, sta> $\underline{in}(\underline{PlaXSta})^\circ = \mathcal{P}tra\mathbb{E}pro\mathbb{E}(\underline{inp})(\underline{n})$ $\underline{implies}$ sta $\in conc(\mathcal{P}ind\mathbb{E}pro\mathbb{E}|\underline{inp}|\underline{pla})$. By the above conjecture this is essentially what we have proven.

In summary, there appears to be a close connection between the effects of our ind interpretation and the method of [Don79] (ignoring sections 7.2 and 7.3). Donzeau-Gouge has been careful to make her correctness proofs modular, so that little is to be proven for each data flow analysis. We do believe that specifying a data flow analysis by a pair of semi-adjoined functions allows for even more modularity. Also we believe that this is a more systematic approach than that of [Don79]. Our approach is more general because [Don79] has no analogue of sts, i.e. an interpretation that may fulfil Theorem 3.1-6. The main reason for this is that we work from a store semantics contrary to her standard semantics: As was discussed in section 3.1 it is unlikely that Theorem 3.1-6 would hold for any approach based on a

standard semantics.

Comparison with [Don78]

The approach of [Don78] differs from the approach of [Don79] in a number of ways.

Sections 1 and 2 of [Don78] define a toy language, which is like ours except that it includes a data structure "tables". The semantics is a standard semantics (not a store semantics) and the association of identifiers to values is by means of a 2-stage mapping, i.e. there are locations. The meaning function $\mathcal P$ for programs is of functionality $\operatorname{Pro-c>}$ Inp $\operatorname{-c>}$ StaXOut where $\operatorname{PFproIinp}1$ is the final state and $\operatorname{PFproIinp}2$ is the output resulting from "executing" pro with input inp. The domains are partially ordered sets but they are not restricted to being definable in DSL.

Sections 3 and 4 are not relevant for this comparison. Sections 5 and 6 contain a non-standard semantics performing a kind of "value subset analysis". The main difference from [Don79] and our approach is that no notion of occurrences is present. The functionality of $\mathcal P$ of this semantics is Pro -c> Inp' -c> Sta'XOut' where Inp', Sta', and Out' specify properties of the input, final state and output. So $\mathcal P$ Epro $\mathbb I$ inp' does not associate (a description of) states with places. The result from this semantics appears less usable than the results specified in our and [Don79]'s approach.

The non-standard interpretation cannot be described satisfactorily in our framework. One reason is the different functionalities of \mathcal{P}_{\bullet} Another reason is, that <code>[Don78]</code> works with a 2-stage mapping and locations are not approximated: no representation of sets of locations is considered.

The way that values is approximated can roughly be described by concVa. Some conditions are imposed on concVa; one implies that $\forall va \in Va : \bot \varepsilon$ concVa(va). This appears to be needed in the proof of Lemma 20 (a correctness proof).

To some extent the non-standard interpretation bears the same relationship to std as ind does to col. I.e. it is more or less the same development that has been performed. In section 3.1 we mentioned some difficulties in basing sts upon std. One proposal was to define a domain sts-A so that $\iota \in \text{sts-a}$ for any sts-a $\in \text{sts-A}$. Hence $\iota \in \text{conc}(\text{ind-a})$ for any ind-a $\in \text{ind-A}$. This is related to the condition of [Don78] mentioned above.

In summary, [Don78] seems to be a forerunner for [Don79] and less adequate in spite of the wider class of ("history-insensitive") data flow analyses considered.

Comparison with [CoC77a] and [CoC79]

Since we have used the ideas of Cousot&Cousot there is much similarity in approaches. The main differences are the perception of programs and the semantic foundations.

Our view, and that of [Don79], of a program is high-level in the sense of [Ros77]: we view a program as a parse-tree. In contrast, [CoC79], [CoC77a] and the traditional data flow analysis view a program as a graph. Arguments in favour of a high-level view can be found in [Ros77].

[Ch.3] History-Insensitive Analyses

In our approach we have worked from a denotational definition of the language. The approach of [CoC77a] and [CoC79] is different: In [CoC77a] a static semantics is developed from an operational semantics. In [CoC79] the static semantics is merely stated (and it is mentioned that a MOP solution is wanted). We believe that a denotational semantics is a more satisfactory starting point than an operational semantics. See [Sto77] for a discussion.

CHAPTER 4

History-Sensitive Analyses

In this chapter we consider "available expressions" analysis as an example of a forward, history-sensitive data flow analysis. This data flow analysis was reviewed in section 2.3. We do not consider other forward data flow analyses.

For lack of time we do not sketch an approach to "live variables", which is a backward "history-sensitive" analysis.

In section 4.1 we consider interpretations that record the computational history. For these history-interpretations we reformulate the general framework of section 3.1. In section 4.2 we develop our notion of available expressions interpretation. This is compared with the literature in section 4.3.

4.1 Reformulating the Framework

According to our approach any data flow interpretation must be related to a static semantics by means of a pair of semi-adjoined functions, as we did for the constant propagation interpretation of section 3.2. When we come to the available expression interpretation (ae) in section 4.2 it seems impossible to do so, when the static semantics is sts. Intuitively, sts contains too little information about the computational history.

In this section we consider interpretations that record the computational history. It is convenient to do so by re-developing the framework of section 3.1, i.e. to specify interpretations his-std, his-col, his-sts and his-ind. To aid the readability of the definitions we introduce the shorthands: When staeSta then sta.env means $sta\psi1$, sta.inp means $sta\psi2$, sta.out means $sta\psi3$ and sta.wit means $sta\psi4$. When sta*eSta* we let $sta**_last$ mean $sta*\psi**_sta*$ and feel free to write e.g. $sta**_last.env$ meaning $(sta*\psi**_sta*)$.

The "Standard" Interpretation

We pattern his-std closely after std. The main difference is that his-std-S is not Sta but Sta*. The intention is that sta*eSta* records the sequence of states that have previously been computed. There are more complicated alternatives to using Sta*, but the his-sts developed using Sta* is adequate for giving a semantic characterization of ae. Table 4.1-A specifies his-std.

LEMMA 4.1-1: Table 4.1-A specifies an interpretation.

Proof is similar to that of Lemma 2.2-5.

To aid the intuition we state:

```
TABLE 4-1-A --- INTERPRETATION his-std
 Domains (of his-std)
     c \in C = Sta* -c> A
inp ∈ I = Inp
A = Out + {"wrong"}
sta* ∈ S = Sta*
               ( See Table 2.2-B for ) ( Pla, Inp, Sta ... )
Constants
   his-std-wrong \in C
his-std-wrong = \lambdasta*. "wrong" inA
   his-std-finish \in C
his-std-finish = \lambdasta*. (sta*.last.out) inA
Pseudo-Semantic Functions
   his-std-\mathcal{B} \in \mathsf{Bas}^{\circ} -c> Val
his-std-\mathcal{B} = \mathsf{std-}\mathcal{B}
   his-std-\theta \in Ope^{\bullet} -c> (Val X Val -c> Val) his-std-\theta = std-\theta
Auxiliary Functions
    his-std-setup € C -c> I -c> A
   his-std-setup c inp = c < <\aidea 'nil' inVal, inp, <>, <>> >
   his-std-cond € C X C -c> C
his-std-Vcond € Sta* -c> T
his-std-Scond € Sta* -c> T
his-std-Bcond € Sta* -c> Sta*
   his-std-wrong(sta*)
his-std-Vcond sta* =
   std-Vcond (sta*.last)
his-std-Scond sta* =
std-Scond (sta*.last)
his-std-Bcond sta* =
sta* $\int < \text{std-Bcond(sta*.last)} >
   his-std-attach € Pla -c> C -c> C
his-std-attach pla c sta* =
c(sta*)
Primitive Functions
   his-std-g € Par -t> C -c> C
his-std-Vg € Par -t> Sta* -c> T
his-std-Bg € Par -t> Sta* -c> Sta*
   his-std-g(par)(c)(sta*) =
  his-std-Vg(par)(sta*) ->
    c(his-std-Bg(par)(sta*))
  his-std-wrong(sta*)
his-std-Vg(par)(sta*) =
  std-Vg(par)(sta*.last)
his-std-Bg(par)(sta*) =
  sta* < std-Bg(par)(sta*.last) >
```

Cch.4] History-Sensitive Analyses

LEMMA 4.1-2: \forall inpeInp \forall proePro: \mathcal{P} stdEproIinp = \mathcal{P} his-stdEproIinp. Proof is by structural induction and is omitted.	[] []
The above Lemma says that his-std and std are "congruent" [Sto77], i.e. used with the semantic functions they associate the same denotation with program. This relationship between his-std and std parallels the relation between the standard, store and stack semantics of [MiS76]. There the formulation of the semantics is gradually transformed to a machine-like formulation. In our case we changed the formulation so as to incorporate "history"-information. As will be shown below there are no similar relationship between col his-col, etc Intuitively, this is because we record the "internals" of semantics in the result of the semantic functions.	n a onship e more and
The "Collecting" Interpretation	
As in section 3.1 we must define what we mean by "the set of state sequences that are possible at pla during an execution of program pro winput inp ". We define this to be \mathcal{P} his-colEproI(inp)(pla), where his-coldefined in Table 4.1-B.	ith . is
LEMMA 4.1-3: Table 4.1-B specifies an interpretation. Proof is similar to that of Lemma 3.1-1.	[]
Similarly to the case with std and col we cannot characterize \mathcal{P} his-col \mathbb{F} pro \mathbb{I} in terms of \mathcal{P} his-std \mathbb{F} pro \mathbb{I} . We can, however, relate his-colcol:	. to
LEMMA 4.1-4: \forall pro \forall inp \forall pla: \mathscr{P} col \mathbb{E} pro \mathbb{I} inp pla = {sta * .last sta * e \mathscr{P} his-col \mathbb{E} pro \mathbb{I} inp pla} Proof is as the proof of Lemma 4.1-2.	C3
Interpretation his-col has been obtained from his-std in the same way as was obtained from std. An alternative is to obtain his-col by modifying But our choice emphasizes the systematic nature of the development Si remarks apply to his-sts and his-ind below.	col.
The "Static" Interpretation	
We then develop a static semantics by defining his-sts (Table 4.1-C) in section 3.1 his-sts is fundamental for abstract interpretation to be applicable. It is also with respect to his-sts that we give a semantic characterization of the ae-interpretation.	As
LEMMA 4.1-5: Table 4.1-C specifies an approximate interpretation. Proof is similar to those of $3.1-2$ and $3.1-8$.	[]
The connection between his-sts and his-col is of course similar to the connection between sts and col:	
LEMMA 4.1-6: If ∀inp∉ <u>inp</u> : topfree[Inp](inp) then Phis-stsEpro <u>linp</u> = U{Phis-colEprol inp inp∉ <u>inp</u> } Proof is shown in appendix 4.	[]
Lemmas 4.1-6, 4.1-4 and Theorem 3.1-6 show a certain relationship betwee	en

his-sts and sts. Another formulation of essentially the same relationship is

```
TABLE 4.1-B --- INTERPRETATION his-col
 Domains (of his-col)
c e C = Sta*-t> A
inp e I = Inp
a e A = Pla -c> P(Sta*)
sta* e S = Sta*
Constants
   his-col-wrong € C
his-col-wrong = 1
    his-col-finish € C
    his-col-finish = 1
Pseudo-Semantic Functions
   his-col-B ∈ Bas° -c> Val
his-col-B = std-B
    his-col-\theta \in Ope^{\circ} -c> (Val X Val -c> Val)
his-col-\theta = std-\theta
Auxiliary Functions
    his-col-setup € C -c> I -t> A
    his-col-setup = his-std-setup
   his-col-cond \epsilon C X C -c> C
his-col-Vcond \epsilon Sta *-c> T
his-col-Scond \epsilon Sta *-c> T
his-col-Bcond \epsilon Sta *-c> Sta *
   his-col-cond = his-std-cond
his-col-Vcond = his-std-Vcond
his-col-Scond = his-std-Scond
his-col-Bcond = his-std-Bcond
   his-col-attach € Pla -c> C -c> C
his-col-attach pla c sta* =
(c sta*) ⊔ ⊥[ {sta*} / pla ]
Primitive Functions
   his-col-g ∈ Par -t> C -c> C
his-col-Vg ∈ Par -t> Sta* -c> T
his-col-Bg ∈ Par -t> Sta* -c> Sta*
   his-col-g = his-std-g
his-col-Vg = his-std-Vg
his-col-Bg = his-std-Bg
```

Lemma 4.1-10 below.

The "Induced" Interpretation

As in section 3.1 it is possible to consider an induced interpretation. Let S be a complete lattice and $\langle uabs, conc \rangle$ a pair of semi-adjoined functions between $\mathcal{P}(Sta^*)$ and S. Then his-ind (or his-ind $\langle uabs, conc \rangle$) of Table 4.1-D is said to be induced from his-sts by $\langle uabs, conc \rangle$.

LEMMA 4.1-7: Table 4.1-D specifies an approximate interpretation. [] Proof is similar to the proof of Lemma 3.1-11.

```
TABLE 4.1-C --- INTERPRETATION his-sts
 Domains (of his-sts)
     c e C = P(Sta*) -c> A

inp e I = P(Inp)

a e A = Pla -c> P(Sta*)

s e S = P(Sta*)
 Constants
           his-sts-wrong € C
           his-sts-wrong = 1
           his-sts-finish € C
           his-sts-finish = 1
 Pseudo-Semantic Functions
          his-sts-B & Bas -c> Val
his-sts-B = std-B
          his-sts-∅ € Ope° -c> (Val X Val -c> Val)
his-sts-∅ = std-∅
Auxiliary Functions
           his-sts-setup € C -c> I -c> A
          his-sts-setup c inp = c { < \lambda inp = inval, inp, <>, <>> > | inpeinp}
        his-sts-cond & C \( \) ( -c> (
    his-sts-Dt-cond & S -c> S
    his-sts-Df-cond & S -c> S
his-sts-cond(c1,c2) s =
    c1(his-sts-Dt-cond(s)) \( \tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\tilde{\til
          his-sts-attach ∈ Pla -c> C -c> C
his-sts-attach(pla)(c)(s) =
(c s) ⊔ ⊥[s/pla]
Primitive Functions
          his-sts-g & Par -t> C -c> C
his-sts-Dg & Par -t> S -c> S
his-sts-g(par)(c)(s) =
          c( his-sts-Dg(par)(s))
his-sts-Dg(par)(s) =
{ his-std-Bg(par)(sta*) | sta* & s \
his-std-Vg(par)(sta*) = true }
```

LEMMA 4.1-8: his-sts \(\frac{1}{2}\) conc> (his-ind\(\text{uabs}\), conc>)

Proof is similar to the proof of Lemma 3.1-12.

The following shows that the static interpretation (sts) can be seen as an induced interpretation of the static "history" interpretation (his-sts). Define uabs: $\mathcal{P}(\text{Sta*}) \rightarrow \mathcal{P}(\text{Sta})$ by uabs(s) = $\{\text{sta*.last } | \text{sta*.es} \}$ and conc: $\mathcal{P}(\text{Sta}) \rightarrow \mathcal{P}(\text{Sta*})$ by conc($\underline{\text{sta}}$) = $\{\text{sta*.last} \in \underline{\text{sta}} \}$.

```
TABLE 4.1-D --- INTERPRETATION his-ind
                 Domains (of his-ind)
                  c \( \in C = S - i \) A

inp \( \in I = \theta(Inp) \)
a \( \in A = Pla - c \) S

s \( \in S \) [ uabs: \( \theta(Sta^*) - \) S ]

[ conc: S - \( \theta(Sta^*) \) ]
                 Constants
                    his-ind-wrong € C
                    his-ind-wrong = 1
                    his-ind-finish € C
                    his-ind-finish = 1
                 Pseudo-Semantic Functions
                    his-ind-\mathcal{B} \in \mathsf{Bas}^{\,o}-c> Val
his-ind-\mathcal{B}= std-\mathcal{B}
                    his-ind-\theta \in \text{Ope}^{\sigma} -c> (Val X Val -c> Val) his-ind-\theta = \text{std}-\theta
                 Auxiliary Functions
                    his-ind-setup & C -c> I -i> A
his-ind-setup c inp =
c( uabs{< \lambdaide."nil" inVal, inp, <>, <>> > |inpeinp} )
                   his-ind-cond & C % C -c> C
his-ind-Dt-cond & S -i> S
his-ind-Dt-cond & S -i> S
his-ind-cond(c1,c2) s =
c1(his-ind-Dt-cond(s)) \( \times \) c2(his-ind-Dt-cond(s))
his-ind-Dt-cond(s) =
uabs( his-sts-Dt-cond( conc(s)))
his-ind-Df-cond(s) =
uabs( his-sts-Df-cond( conc(s)))
                    his-ind-attach & Pla -c> C -c> C
his-ind-attach pla c s =
(c s) u (1[s/pla])
                Primitive Functions
                    his-ind-g \epsilon Par -t> C -c> C
his-ind-Dg \epsilon Par -t> S -i> S
                   his-ind-g par c s =
    c( his-ind-Dg(par)(s))
his-ind-Dg par s =
                       uabs( his-sts-Dg(par)( conc(s)))
LEMMA 4.1-9: <uabs,conc> is an exact pair of adjoined functions.
                                                                                                                                 Г٦
 Proof is shown in appendix 4.
                                                                                                                                 LEMMA 4.1-10: his-ind<uabs,conc> equals sts
 Eand sts ≤<λsta.sta.λsta.sta> (his-ind<uabs,conc>)
   and (his-ind<uabs,conc>) Ε<λsta.sta,λsta.sta> sts ]
                                                                                                                                 Proof is shown in appendix 4.
                                                                                                                                 Г٦
```

We believe that the above lemma very nicely shows the power of the the method of Abstract Interpretation. We dispense with a formal definition of when two interpretations are equal.

4.2 Available Expressions

In this section we develop an "available expressions" analysis in our framework. In subsection 4.2.1 we perform continuation removal (ESto77], [MiS76]) for expressions. Thereby it is possible to denote the value computed by some expression. This is used in subsection 4.2.2 where we develop pairs of adjoined functions that relate sets of sequences of states to sets of available expressions. In subsection 4.2.3 we formulate interpretation ae and it is given a semantic characterization in terms of his-sts.

4.2.1 Continuation Removal

Intuitively, a semantic characterization of "exp is available at pla" amounts to relating the value of exp when "evaluated at pla" to its value when previously evaluated. It is therefore necessary to be able to denote the value to which exp evaluates. The functionality of a makes at the exp inadequate for this. Instead we define the continuation removed function Pastd exp such that at the exp (occ)(c)(sta) = c(sta') whenever Pastd exp (occ)(sta) = ...sta'....

For technical reasons it is convenient later in this section to use a more or less similar function Pchis-sts.

In Table 4.2-A we have defined the function P€ that will be used with both std and his-sts.

TABLE 4.2-A --- CONTINUATION REMOVAL FOR &

Semantic Functions

P € € Exp -t> Occ -c> S -c> R

P&F exp1 ope exp2 I occ =
Pattach<occ, "exp)"> *
PapplyFopeI *
P&Fexp2I occ\$<3> *
P&Fexp1I occ\$<1> *
Pattach<occ, "(exp">

P&F ide I occ =
Pattach<occ,"exp)"> *
PcontentFideI *
Pattach<occ,"(exp">

P&F bas I occ =
Pattach<occ,"exp)"> *
PpushFbasI *
Pattach<occ,"(exp">

To be able to use P₺ with std we augment std as shown in Table 4.2-B. Here we define domain std-R and combinators std-* and std-⊕ as well as functions std-Pattach and std-Pg (for g any primitive function) {a}. Similarly, Table 4.2-D contains the augmentations to his-sts {b}.

Both std-* and his-sts-* (and sts-*) are associative so no parentheses are

[{]a} Pcond is not used until chapter 6.

needed in the definition of P& in Table 4.2-A:

LEMMA 4.2.1-1: Tables 4.2-A, 2.2-D and 4.2-B define P&std that is of functionality as shown. Similarly, Tables 4.2-A, 4.1-C and 4.2-D define P&his-sts that is of functionality as shown. In the definitions of P&std and P&his-sts no function is supplied with an argument of the wrong type.

The intention with combinators * and θ is that $c\theta(ss1*ss2) = (c\theta ss1)\theta ss2$. We often omit prefixes std- and his-sts- when it may be deduced from context which * or θ is meant. Hence the relationship between θ and θ can be stated as:

```
TABLE 4.2-B --- ADDITIONS TO std
```

```
Domains (of std)
```

S = Sta R = Sta + {"wrong"}

Combinators (of std)

* • [S -c> R] X [S -c> R] -c> [S -c> R] ss1 * ss2 = λs. ss2(s) E Sta -> ss1(ss2(s) | Sta), ss2(s)

Auxiliary Functions

std-Pattach & Pla -c> S -c> R
std-Pattach(pla)(s) =
 s inR

Primitive Functions

We need the above result for his-sts in the proof of Lemma 4.2.3-5. The result for std supports the intuition that P&stdlexpl describes the effect of exp. In the proof of Lemma 4.2.3-5 we will also need the following two lemmas:

LEMMA 4.2.1-3: For any expression exp and state <env,inp,out,wit> and occurrence occ:

wit∉{⊥, T} => [∃valeVal:

Proof is by structural induction.

```
TABLE 4.2-C --- ADDITIONS TO sts
Domains (of sts)
    A = Pla -c > P(Sta)
    S = P(Sta)
    R = S X A
Combinators (of sts)
   * € [S -c> R] X [S -c> R] -c> [S -c> R]
ss1 * ss2 = As. < ss1(ss2(s)\\\1)\\\2
, ss1(ss2(s)\\\1)\\\2 \mu ss2(s)\\2>
   \theta \in C \times [S -c > R] -c > C

c \theta ss = \lambda s. c(ss(s) \psi 1) u (ss(s) \psi 2)
Auxiliary Functions
   sts-Pcond € [S -c> R] X [S -c> R] -c> [S -c> R] sts-Pcond(ss1,ss2) sta = ss1(sts-Dt-cond(sta)) → ss2(sts-Df-cond(sta))
   sts-Pattach € Pla -c> S -c> R
   sts-Pattach pla sta = <sta, *[sta/pla] >
Primitive Functions
   sts-Pg € Par -t> S -c> R
  sts-Pg par sta = < sts-Dg(par)(sta), 1 >
```

```
LEMMA 4.2.1-4: \forall s \in P(Sta^*): If \forall sta^* \in s: sta^* \cdot last \cdot wit \notin \{\bot, \tau\} then \{sta^* \cdot last \mid sta^* \in (P \circ his - sts \mathbb{E} exp \mathbb{I} occ s) \neq 1\}
= \{P \circ std \mathbb{E} exp \mathbb{I} occ (sta^* \cdot last) \mid Sta \mid sta^* \in s\}

Proof is shown in appendix 4.
```

It is easy to show that PostdFexpIocc is independent of occ. We therefore take the notational liberty of eliding occ in the sequel, because it complicates the exposition to state "where exp and occ are such that exp = pro at occ" whenever PostdFexpI(occ) is used.

Our notion of continuation removal is similar to that of [Sto77] and [MiS76] although the details and motivations differ.

4.2.2 Pairs of adjoined functions for available expressions

We now informally explain a semantic notion of available expressions. Suppose pro is a program and pla a place such that pla designates a point immediately preceding an evaluation of expression exp. Intuitively, (the value of) this expression is available at pla iff in every computation some expression (e.g. exp itself) has previously been evaluated to the same value to which exp now evaluates. More formally this means (by Lemma 4.2.1-2 and 4.2.1-3 and by tacitly ignoring some special cases) that for any input inp and $sta^* \in \mathcal{P}$ nis-colEproI(inp)(pla) there is an $ie\{1,...,\#sta^*\}$ such that $(sta^* \psi i).wit \psi 1$ equals (P2stdIexpI(sta*.last)|Sta).wit $\psi 1$. This notion is semantic, in contrast to the traditional definition of available expressions,

TABLE 4.2-D --- ADDITIONS TO his-sts

Domains (of his-sts)

A = Pla -c > P(Sta*)

S = P(Sta*)R = S X A

Combinators (of his-sts)

* • [S -c> R] X [S -c> R] -c> [S -c> R] ss1 * ss2 = λ s. < ss1(ss2(s) ψ 1) ψ 1 , ss1(ss2(s) ψ 1) ψ 2 ω ss2(s) ψ 2 >

 $\theta \in C \times ES - c > R = -c > C$ $c \theta ss = \lambda s \cdot c(ss(s) \psi 1) \rightarrow (ss(s) \psi 2)$

Auxiliary Functions

Primitive Functions

his-sts-Pg & Par -t> S -c> R his-sts-Pg par s = < his-sts-Dg par s, \(\mu\) >

which is syntactic: the manipulation of sets of expressions is given no semantic characterization.

In this subsection we formalize the above description of (semantically) available expressions. In subsection 4.2.3 we formulate an interpretation (ae) that computes available expressions according to the usual (syntactic) definition. The purpose of the present subsection is to define a pair of adjoined functions such that ae can be given a semantic characterization (in subsection 4.2.3). This amounts to giving a semantic characterization of an apparently syntactic [CoC77a,p.242] data flow analysis.

Recall that ρ (...) is dual to ρ (...), i.e. with \geq as ordering (2.1.3-10):

DEFINITION 4.2.2-1: Let $r:Sta^* \to \mathcal{P}^*(Exp)$ be any function. Define uabs- $r:\mathcal{P}(Sta^*) \to \mathcal{P}^*(Exp)$ and $conc-r:\mathcal{P}^*(Exp) \to \mathcal{P}(Sta^*)$ by uabs- $r(s) = \mathcal{N}\{r(sta^*) \mid sta^* \in s\}$ and $conc-r(exp) = \{sta^* \mid r(sta^*) \geq exp\}$

LEMMA 4.2.2-2: <uabs-r,conc-r> is a pair of adjoined functions.

The intention with r(sta*) is that it is a set of expressions exp such that there is an $i\in\{1,\dots,\#$ sta*} so that (sta* ψ i).wit ψ 1 equals (P\$std \mathbb{E} exp \mathbb{I} (sta*.last)|Sta).wit ψ 1. To make this precise we need:

DEFINITION 4.2.2-3: Define sametop: (Sta+{"wrong"}) X (Sta+{"wrong"}) -> B by sametop(a1,a2) =

(a1\in Sta)=true \(\lambda\) (a2\in Sta)=true \(\lambda\) \(\lamb

 $sta^* \notin \{\bot, \tau\}$ implies r1(sta*) = {exp | \exists j \in {1,...,#sta*}}:

DEFINITION 4.2.2-4: Define r1:Sta * -> ρ '(Exp) to be doubly strict so that

sametop(sta*\vj in(Sta+{"wrong"}), P&stdFexpI(sta*.last))}

[]

Function r1 formalizes a semantic notion of availability: his-ind induced by $\arrowvert \arrowvert \arrowver$

We now set forth to develop the function r3 that will be used in subsection 4.2.3 to show the correctness of ae. As an intermediate step we develop r2:

DEFINITION 4.2.2-5: Define r2:Sta*->P'(Exp) to be doubly strict so that sta* $\notin \{\bot_r \tau\}$ implies r2(sta*) =

 $\{\exp \mid \exists j \in \{1,...,\#sta^*\}: gen2(sta^* \forall j,exp) \land \}$

 $\forall k \in \{j+1,...,\#sta^*\}: \text{pre2}(\text{sta}^*\psi(k-1),\text{sta}^*\psi(k,\exp)\}$ where gen2(sta,exp) = sametop(sta in(Sta+{"wrong"}), PfstdFexpIsta) and pre2(sta1,sta2,exp) = sametop(PfstdFexpIsta1, PfstdFexpIsta2).

The intention is that gen2 is true for those expressions that have been semantically "generated", and that pre2 is true for the expressions that have been semantically "preserved".

OBSERVATION 4.2.2-6: uabs-r1 = uabs-r2

An important feature of r2 (which is shared by r3 below) is that its definition can be expressed inductively. This is adequate when $\frac{1}{2}$ conc-r3> is used to give a semantic characterization of ae. For the inductive definition (assuming sta* $\{1,7\}$):

r2(sta*{<sta>)

- = {exp | Lexp∈r2(sta*) ∧ pre2(sta*.last,sta,exp)] ∨ gen2(sta,exp)} = Lr2(sta*) ∧ {exp|pre2(sta*.last,sta,exp)}] ∨ {exp|gen2(sta,exp)} Note the resemblance of the above definition to the transfer function for available expressions (section 2.3).

In the description of available expressions (section 2.3) we cited from ERos793: "...where an expression is considered to have changed in value whenever any one of the Eidentifiers] involved in it has changed". To capture this notion we define r3.

DEFINITION 4.2.2-7: Define #:Exp->P(Ide) by #Fexp1 ope exp2 = #Fexp1 I J #Fexp2 I #Fide I = {ide}
#Fbas I = 0

DEFINITION 4.2.2-8: Define r3:Sta*-> ρ '(Exp) to be doubly strict so that sta* $\notin \{1,7\}$ implies r3(sta*) =

 $\{\exp \mid \exists j \in \{1,..., \#sta *\} : gen3(sta * \psi j, exp) \land \}$

∀k€{j+1,..., #sta*}: pre3(sta*\(k-1), sta*\(k, exp)

where gen3(sta,exp) = gen2(sta,exp) and

pre3(sta1,sta2,exp) = (sta1.wit\(\psi\) \(\lambda\) (sta2.wit\(\psi\) \(\lambda\)
\(\psi\) ide\(\psi\) Exp1: sta1.env\(\psi\) ide\(\psi\)

Of course also r3 can be defined inductively: r3(sta* $\frac{1}{2}$ <sta>) = [r3(sta*) \cap {exp| pre3(sta*_last_sta_exp)}] \cup {exp|gen3(sta_exp)} where we have assumed sta* $\frac{1}{2}$

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LEMMA 4.2.2-9: uabs-r2 \leq uabs-r3

Proof is shown in appendix 4.

For later usage it is convenient to extract the following lemma used in the proof of Lemma 4.2.2-9: LEMMA 4.2.2-10: ∀sta1,sta2∈Sta ∀exp∈Exp: pre3(sta1,sta2,exp) => pre2(sta1,sta2,exp) Proof is shown in appendix 4. 4.2.3 Available Expression Interpretation Table 4.2-E contains the ae-interpretation. It has $S = \mathcal{O}(Exp)$ and exp is intended to describe a set of available expressions. We explain the primitive functions below. Combinators * and * and functions Pattach and Pg are used when we perform continuation removal for ae (Lemma 4.2.3-4). The effect of g upon exp is described by a transfer function (λexp.GENg(par) υ [PREg(par) α exp]) applied to exp. Here GENg(par) is the set of expressions generated and PREg(par) is the set of expressions preserved. Mostly PREq(par) = Exp and GENq(par) = 0. One exception is that \forall ide \in is, we only preserve the expressions that we know to be unaffected by the value of ide. The other exception is that $\forall exp \in Exp$: GENapply $Exp = \{exp\}$. We expect any application applyFope to generate the expression exp = exp1 ope exp2 "corresponding to" operator ope in the parse-tree. What this expression is cannot be deduced from ope. The solution we have chosen is to supply ae-apply and GENapply with an extra parameter being that expression. To do so the semantic function & (and P&) must be changed as shown in Table 4.2-F. We would like to know that ae is an interpretation because then Theorem 2.2-4 assures that ae can be used together with the semantic functions of Table 2.2-C. However, ae-apply has an extra parameter (in Exp), so strictly speaking ae is not an interpretation; further, Table 4.2-F modifies Table 2.2-C so that the proof of Theorem 2.2-4 no longer pertains. It is straightforward, but tedious, to be precise and correct these minor deviations. We choose to ignore these issues and state: LEMMA 4.2.3-1: Table 4.2-E specifies an approximate interpretation. ГЛ Also note that the use of a continuation style semantics is advantageous to a direct style semantics because there is an "implicit ordering" upon the evaluation of subexpressions. This is not necessarily the case for a direct style semantics. Even when subexpressions "have no side-effects" this is desirable for "available expressions" analysis. Semantic Characterization of ae We then give a semantic characterization of ae. Because of the extra parameter to apply we cannot show his-sts ≤uabs-r3,conc-r3> ae. Instead we prove: THEOREM 4.2.3-2: \forall pro \forall inp: Phis-sts \mathbb{E} pro \mathbb{I} inp \mathbb{E} (R conc-r3)(Pae \mathbb{E} pro \mathbb{I} inp) ГТ Proof is shown in appendix 4.

```
TABLE 4.2-E(a) --- INTERPRETATION ae
Domains (of ae)
 \begin{array}{c} c & \boldsymbol{\epsilon} & \boldsymbol{C} = S - c > A \\ \underline{inp} & \boldsymbol{\epsilon} & \boldsymbol{I} = \boldsymbol{\mathcal{P}}(Inp) \\ a & \boldsymbol{\epsilon} & A = Pla - c > S \\ \underline{exp} & \boldsymbol{\epsilon} & S = \boldsymbol{\mathcal{P}}^{\text{T}}(Exp) \\ R = S & \boldsymbol{\lambda} & A \end{array}
Constants
   ae-wrong \in C ae-wrong = \bot = \lambda exp.\lambdapla.Exp
   ae-finish € C
   ae-finish = \bot = \lambda exp\lambda pla_Exp
Combinators (of ae)
   \star \epsilon [S -c> R] \star [S -c> R] -c> [S -c> R]
   ss1 * ss2 = \lambda exp < ss1(ss2(exp)\psi1)\psi1 
, ss1(ss2(exp)\psi1)\psi2 u ss2(exp)\psi2 >
    ⊕ € C X [S -c> R] -c> C
    c \oplus ss = \lambda exp. c(ss(exp)\psi1) \perp (ss exp)\psi2
Pseudo-Semantic Functions
    ae-B € Bas° -c> Val
   ae-B=std-B
   ae-\theta \in \text{Ope}^{\circ} -c> (Val X Val -c> Val) ae-\theta = \text{std}-\theta
Auxiliary Functions
   ae-setup € C -c> I -c> A
ae-setup c inp =
    c ∅
    ae-cond € C X C -c> C
      ae-Dt-cond ∈ S -c> S
ae-Df-cond ∈ S -c> S
   ae-cond(c1,c2) exp = c1(ae-Dt-cond(exp)) c2(ae-Df-cond(exp)) ae-Dt-cond(exp) = c2(ae-Df-cond(exp))
   \underbrace{exp}_{ae-Df-cond}(\underbrace{exp}) =
       exp
   ae-attach ε Pla -c> C -c> C
ae-Pattach ε Pla -c> S -c> R
ae-attach(pla)(c)(exp) =
   (c exp) u Texp/ptal
ae-Pattach(pta)(exp) =
<exp, rtexp/ptal>
```

To conduct this proof it is convenient to perform continuation removal for fae, thus defining P_{ae} . As a companion to Lemmas 4.2.1-1 and 4.2.1-2 we have:

LEMMA 4.2.3-3: Tables 4.2-A (modified by Table 4.2-F) and 4.2-E define a function Page. It is of functionality as shown and no functions is supplied with an argument of the wrong type.

TABLE 4.2-E(b) --- INTERPRETATION ae

Primitive Functions ae-g @ Par -t> C -c> C ae-Dg @ Par -t> S -c> S ae-Pg @ Par -t> S -c> R PREg @ Par -t> S GENg @ Par -t> S ae-g par c exp = c(ae-Dg(par)(exp)) ae-Dg par exp = GENg(par) U L PREg(par) c exp] ae-Pg par exp = < ae-Dg(par)(exp), _ > PREapplyFopeIFexpI = Exp GENapplyFopelFexpl = {exp} PREassignFideI = {exp | ide \(\mathref{F}\) FexpI } GENassignFideI = \(0 \) PREcontentFide = Exp $GENcontentFideI = \emptyset$ PREpushIbasI = Exp GENpushIbasI = 0 PREread = Exp GENread = Ø PREwrite = Exp GENwrite = 0 TABLE 4.2-F --- CHANGES TO Lae AND Plae P&F exp1 ope exp2 I occ = Pattach<occ,"exp)"> * PapplyFopeIFexp1 ope exp2I * P&Fexp2I occ <3> * P&Fexp1I occ <1> * Pattach<occ,"(exp"> LEMMA 4.2.3-4: Caelexplocc c = c @ Pcaelexplocc Proof is similar to that of Lemma 4.2.1-2. We need the following predicates: P-S:(his-sts-S X ae-S) -> B defined by P-S(his-sts-s,ae-s) = his-sts-s ⊆ conc-r3(ae-s) ∧ ∀sta*∈his-sts-s: sta*.last.wite{1,7} P-C:(his-sts-C X ae-C) -> B defined by P-C(his-sts-c, ae-c) = P-S(his-sts-s,ae-s) => his-sts-c(his-sts-s) \((R \) conc-r3)(ae-c(ae-s)) The key ingredient in the proof of Theorem 4.2.3-2 is LEMMA 4.2.3-5: P-C(his-sts-c,ae-c) =>P-C(Chis-stsTexpTocc his-sts-c, CaeTexpTocc ae-c) Proof is shown in appendix 4.

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LEMMA 4.2.3-6: For any primitive funcion g (except apply) we have P-C(his-sts-c,ae-c) => P-C(his-sts-g(par)(his-sts-c), ae-g(par)(ae-c)) [] Proof is shown in appendix 4.

Since <uabs-r3,conc-r3> is a pair of adjoined functions and uabs-r1 = uabs-r2 = uabs-r3 a corollary to Theorem 4.2.3-2 is:

COROLLARY 4.2.3-7: ∀pro ∀inp:
(R uabs-r1) (Phis-stsFproIinp) ⊆
(R uabs-r2) (Phis-stsFproIinp) ⊆
(R uabs-r3) (Phis-stsFproIinp) ⊆
PaeFproIinp

4.3 Comparison with other Approaches

In this section we compare our development of available expressions with the literature. We compare it with the traditional formulation of available expressions, with the common subexpression elimination of [Don79], and with work by Cousot&Cousot [CoC77a], [CoC79] and Wegbreit [Weg75].

Traditional formulation of available expressions

Our ae-interpretation computes available expressions by means of a transfer function of the form λexp -generated σ (preserved σ exp), which is as in the traditional formulation of available expressions. This indicates that the concepts underlying our formulation of available expressions closely match the traditional concepts.

This must be complemented by the results of chapter 5 which show a connection between the "solutions".

The semantic characterization of available expressions is not found in the traditional method. Also, our approach unites local and global analysis.

"Common subexpression elimination" of [Don79]

In section 7.2 of [Don79] Donzeau-Gouge applies her framework to the "common subexpression elimination" of [Kil73]. This data flow analysis is different from available expressions, but there is some similarity in purpose: "determination of common subexpressions ... includes the determination of available expressions..."[Don79].

Global common subexpression elimination [Kil73] associates partitioned sets of expressions with arcs. For any two expressions to occur in the same partition the following must hold: It must be known that the values they evaluated to at their latest computation are the same; and after their latest computation their values must not have changed. See [Kil73] for details and how to compute this information.

In the discussion of [Don79] below we use our notation. When performing common subexpression elimination in the framework of [Don79] it is natural to map a place (<occ, "exp)">) to the set of expressions that are in the same partition (at this place) as pro at occ. We believe that the non-standard semantics of [Don79, section 7.2] does perform this task. This belief is supported by (parts of) the motivation presented in [Don79]. But [Don79], probably by mistake, does not prove this. Her theorem asserts something different, but (the proof of) Lemma 8 appears to be in error [Nie80]. The

possible remedies do not appear to be immediate.

The non-standard semantics of <code>[Don79,7.2]</code> does not use the concepts "generate" or "preserve", nor does it compute common subexpressions by a method akin to that of <code>[Kil73]</code>. Instead she gives a Herbrand interpretation: the state maps expressions of the program to symbolic trees. The place <code><occ,"exp)"></code> is mapped to the set of expressions such that the current state maps each expression (of that set) to the symbolic tree that pro <code>at</code> occ is mapped to.

Because [Don79] uses concepts different from those of [Kil73] it is not obvious how the concepts are related. This is contrary to our ae that does use the traditional concepts. We therefore feel that our development gives a semantic characterization better than [Don79, section7.2] of the traditional data flow analysis which it intends to model.

Comparison with Cousot Cousot and Wegbreit

Both CCoC77a,p.241] and CCoC79,p.278] formulate abstract interpretations for "available expressions". Also EWeg75,p.276] formulates "available expressions". All three formulations use the notions of "preserve" and "generate".

None of the three papers give a semantic characterization of the formulation. Wegbreit [Weg75] does not even mention the issue. In [Coc77a,p.242] there is the following discussion: "One can distinguish between syntactic and semantic abstract interpretations of a program. Syntactic interpretations are proved to be correct by reference to the program syntax (e.g. ... available expressions ...). By contrast semantic abstract interpretations must be proved to be consistent with the formal semantics of the language (e.g. constant propagation)" [Coc77a]. We do not consider it reasonable to characterize "available expressions" as "syntactic", because then the information hardly can be used for anything. From our experience we may suggest that one cannot prove "available expressions" correct with respect to the usual semantics, but that one has to use a more "concrete" semantics that records the computational history.

In [CoC79,p.278] the "available expressions" interpretation is developed from a "set of traces" semantics. However, the transfer function, essentially λexp -generated σ 0 (preserved σ 0 exp), is not justified: the definitions of preserved and generated are neither given nor related to the semantics.

It appears that our treatment of available expressions is the first to give <u>some</u> semantic characterization of "available expressions analysis". It is not crucial that we work from a denotational semantics.

CHAPTER 5

The MOP Solution

The purpose of this chapter is to relate the data flow information specified by Table 2.2-C together with an induced interpretation (ind) to the solutions considered in traditional data flow analysis. In section 5.1 we define semantic functions $A\mathcal{P}$, $A\mathcal{D}$, $A\mathcal{E}$ and $A\mathcal{E}$ such that $A\mathcal{P}$ indEproI specifies the transfer functions of program pro. These functions were called Bf<...> in section 2.3. We also state some properties fulfilled by the semantic functions.

In section 5.2 we show a certain relationship between PindEproI and APindEproI. This relationship can be formulated as: PindEproI specifies the MOP solution of traditional data flow analysis. One possible conclusion is that our approach is valid because it specifies the MOP solution. We believe that this is not a reasonable conclusion because the fact that the MOP solution is wanted is only based on intuitive arguments. The converse conclusion is that it is correct to want the MOP solution because it agrees with the information specified by our approach. This is also not a reasonable conclusion, e.g. because there is a certain arbitrariness in going from std to col. The reasonable conclusion probably is that two different approaches, both intuitively correct, turn out to give the same result, thus raising our confidence in both of them.

In this chapter we only consider interpretation ind and especially in proofs we often omit the prefix ind—. The same development can be performed for his—ind and ae with only occasional changes in the notation. Also recall that sts and his—sts are special cases of ind and his—ind (respectively).

5.1 The Transfer Functions

One way to obtain the transfer functions pertaining to some program pro is to do as in "traditional" data flow analysis: First the program is syntactically transformed into a graph, where nodes are sequences of simple assignment statements and arcs represent flow of control (as mentioned in section 2.3). Transfer functions are then constructed and associated with the nodes. These two stages are usually not justified semantically: the syntactic transformation is considered intuitively obvious and the construction of the transfer functions is done without reference to any formal semantics. An exception is <code>[CoC77a]</code> where the transfer functions are justified with respect to an operational semantics.

For our purposes it is simpler to define one non-standard semantics (Table 5.1-A and an induced interpretation ind) that traverses the program and constructs the transfer functions. Hopefully, it is intuitively clear that the transfer functions constructed by A \mathcal{P} indEpro \mathbb{I} essentially correspond to those usually constructed in traditional data flow analysis; because only

```
TABLE 5.1-A(a) --- SEMANTIC FUNCTIONS COLLECTING ARCS
 THE OWN COLUMN C
Domains
                                                                                      specified by the interpretation
    D = S -i> S
U = Pla X D
Trans = (Pla X Pla) X D
F = U -t> U X P(Trans)
Auxiliary Functions
         Arecord & D -t> F
Arecord(d-new)<pla,d-old> =
<<pre><<pla,d-new.d-old>,Ø>
          Aattach € Pla -t> F
         Aattach(pla-new)<pla-old,d> =
  <<pla-new,λs.s>, {<<pla-old,pla-new>,d>}>
         * \epsilon F \chi F -t> F (f * g) u = < f(g(u)\psi1)\psi1, f(g(u)\psi1)\psi2 \square g(u)\psi2>
        WITH \epsilon F \chi F -t> F (f WITH g) u = \langle g(u)\psi 1, f(u)\psi 2 \cup g(u)\psi 2 \rangle
         ALSO \epsilon F \lambda P(Trans) -t > F
(f ALSO \underline{trans}) u = \langle f(u)\psi 1, f(u)\psi 2 \underline{u} \underline{trans} \rangle
Semantic Functions
AP € Pro -t> P(Trans)
         A\mathcal{A} \in Dcl -t > Occ -t > F
         ADE dcl1; dcl2 I occ =
Aattach<occ,"dcl)"> *
ADEdcl2I occ <<2> *
ADEdcl1I occ <<1> *
Aattach<occ,"(dcl">
         ADF DCL ide := bas I occ =
Aattach<occ,"dcl)"> *
Arecord(DassignFideI) *
Arecord(DpushFbasI) *
Aattach<occ,"(dcl">
A& € Exp -t> Occ -t> F
         A&F exp1 ope exp2 I occ =
Aattach<occ,"exp)"> *
Arecord(DappLyFopeI) *
                   AcTexp21 occ$<3> *
AcTexp11 occ$<1> *
Actexp11 occ$<1> *
Actexp11 occ$<10 *
          ACE ide I occ =
                  Aattach<occ,"exp)"> *
Arecord(DcontentFide1) *
Aattach<occ,"(exp">
         AZF bas I occ =
Aattach<occ,"exp)"> *
Arecord(DpushFbasI) *
Aattach<occ,"(exp">
```

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then Theorem 5.2-12 can be interpreted to say: \mathcal{P} ind \mathbb{E} pro \mathbb{I} specifies the MOP solution. We ignore the fact that $\mathbb{A}\mathcal{P}$ ind \mathbb{E} pro \mathbb{I} considers smaller basic blocks than is usually done $\{a\}$.

TABLE 5.1-A(b) --- SEMANTIC FUNCTIONS COLLECTING ARCS

In the sequel we explain the non-standard semantics as specified by Table 5.1-A and some interpretation ind.

To understand Table 5.1-A it may be helpful to mentally view a program pro as a graph (see section 2.3). This amounts to identifying arcs with places and letting a node be represented by a pair of places. The start arc corresponds to < <>,"(pro">. This leads to one way of understanding the semantics, even if this view sometimes may appear artificial.

[{]a} One way to remedy this is to remove some attach functions from Table 2.2-C and the corresponding Aattach functions from Table 5.1-A. A disadvantage of this is that approximations are then performed inside basic blocks. This can be avoided by using ind' instead of ind where ind' is mainly as sts but where attach (and similarly Aattach) is changed so as to apply the abstraction and concretization functions.

The intention with APind \mathbb{E} pro \mathbb{I} then is to specify {<<pla1,pla2>,Bf<pla1,pla2>> | <pla1,pla2> is a path in progoing through one node}

A tuple <<pla1,pla2>,Bf<pla1,pla2>> will be called a transition and is an element of Trans = (Pla X Pla) X (S -i> S) = (Pla X Pla) X D where D = S -i> S is the domain of transfer functions. Thus the functionality of A \mathcal{P} ind is Pro -t> \mathcal{P} (Trans).

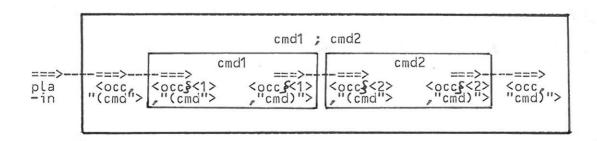
More or Less the intentions with AlindFcmdI, AlindFdclI and AlindFexpI are as above. In the sequel we consider only AlindFcmdI.

We supply AfindEcmdI with an occurrence because places are defined in terms of occurrences and because we want distinct syntactic constructs to generate distinct places. The functionality of AfindEcmdI(occ) is more complicated than might have been expected:

A \mathcal{E} ind \mathbb{E} cmd \mathbb{I} occ \mathcal{E} F where $F = U - t > U \times \mathcal{P}(Trans)$ and $U = Pla \times D$

Below we informally explain why we supply A \mathcal{E} indEcmd $\mathcal{I}(occ)$ with an argument ≤ 1

The need for A@indEcmd1(occ)<pla,d> to produce an element of U is best illustrated when cmd is cmd1;cmd2. The clause for A@indEcmd1;cmd2 I can be depicted as shown on the figure below. Here ===> represents an arc (place) and ---- can be thought of as a node. The element of U to be supplied to A@indEcmd21(occ§<2>) must be produced by A@indEcmd11(occ§<1>).



The transitions generated by AfindEcmdI(occ)<pla-in,d-in> include:

< <pla-in, <occ, "(cmd">> ,d-in>

Afind Fcmd1 I occ $\leq 1 > < cc$, "(cmd">, $\lambda s.s > \sqrt{2}$

AfindFcmd21 occ\$<2> < <occ<math>\$<1>,"cmd)">, \$a.s> \$v2

< < <occ§<2>,"cmd)">, <occ,"cmd)"> > , As.s>

That this is so follows from Lemma 5.1-4.

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To understand the clause for A%indF WHILE exp D0 cmd OD I(occ) it may be helpful to consider the figure below. The abbreviations of places used will also be used in the proofs of Lemmas 5.2-8 and 5.2-11. Abbreviate

```
pla-begin = <occ \( \) ("Repeat")

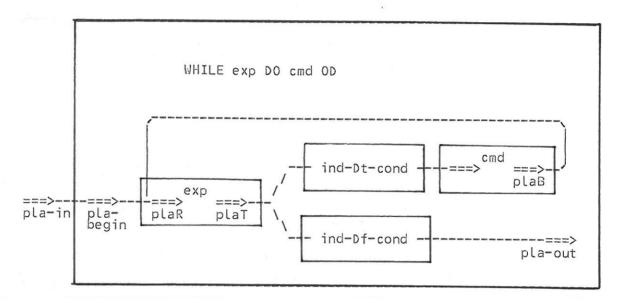
plaR = <occ \( \) ("Exp")

plaT = <occ \( \) ("Exp")

plaB = <occ \( \) ("Exp")

plaB = <occ \( \) ("Exp")

plaF = <occ \( \) ("Exp")
```



The boxes labelled ind-Df-cond and ind-Dt-cond represent the effect of these functions, i.e. to choose the false or true branch {a}.

The transitions generated by

A Find F WHILE exp DO cmd OD 1(occ) < pla-in, d-in > include:

< <pla-in,pla-begin>, d-in>

AZindFexpI occ <1> <pla-begin, \(\frac{1}{2}\)s.s> \(\frac{1}{2}\)

Afind Fcmd I occ << 2> <plaT, ind-Dt-cond> \v2

< <plaB,plaR>, \(\lambda s.s\)

< <plaT,pla-out>, ind-Df-cond>

This follows from Lemma 5.1-4. As will become clear in section 5.2 it is the transition < <plap>, λ s.s> which accounts for the "iterative" nature of a WHILE construct.

Similarly to the situation in section 2.2 we have:

LEMMA 5.1-1: Table 5.1-A and interpretation ind define functions APind, ADind, ACind and ACind. They are of functionalities as shown and no function is supplied with an argument of the wrong type.

We now state some properties of the non-standard semantics (Lemmas 5.1-4 and 5.1-5). We first define some concepts which are explained afterwards.

[{]a} In data flow analysis it is often assumed that Dt-cond = Df-cond = D

```
DEFINITION 5.1-2:
        Define xpld: Occ -> P(Pla) (for "explode") by
  xpld(occ) = {<occ',q'> | occ' = occ§<...>}.
  Here occ' = occ\{<...> is a shorthand for \existsocc"\in0cc-\{\bot_{r}\tau\}: occ' = occ\{occ".
        Define out: F -> Pla by out(Ag) = Ag< <<,"?"> \lambdas.s> \forall1 \forall1.
        Define local: F -> P(Pla) by
  local(Ag) = {pla2 \mid \langle\langle pla1, pla2\rangle, d\rangle \in Ag\langle \langle\langle\rangle, "?"\rangle \lambda s.s\rangle \ \forall 2}.
                                                                                                                                                  ГЛ
DEFINITION 5.1-3:
        Define the predicate P-F: F -> B by P-F(Ag) =
           ∃pla-out ∀<pla-in,d-in>€U: Ag<pla-in,d-in>ψ1 = <pla-out,\(\frac{1}{2}\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s\sigma_s
  ii) ∃pla∈P(Pla) ∀<pla-in,d-in>∈U:
        out(Ag) € pla ^
        \{pla1 \mid \langle pla1, pla2\rangle, d \in Ag\langle pla-in, d-in\rangle \}  \{pla1 \mid \langle pla-\{out(Ag)\}\} \} 
        \{pla2 \mid \langle\langle pla1, pla2\rangle, d\rangle \in Ag\langle pla-in, d-in\rangle \ = pla
  iii) ∀pla-in1¢local(Ag) ∀pla-in2€Pla ∀d-in1,d-in2€D:
       LET trans1 = Ag<pla-in1,d-in1>\v2 IN
       LET trans2 = Ag<pla-in2,d-in10 d-in2>\frac{1}{2} IN
        \underline{\text{trans2}} = \{ \langle \text{pla-in2,pla} \rangle, \text{dod-in2} \mid \langle \text{pla-in1,pla} \rangle, \text{dod-in2} \}
                      υ {<<pla1,pla2>,d> | pla1≠pla-in1 Λ <<pla1,pla2>,d> ε trans1}
       Let Ag = AbindFcmdI(occ) and assume P-F(Ag). Condition "i)" intuitively
 says that regardless from where (pla-in) cmd is entered it must be left by
  the arc pla-out. Clearly pla-out = out(Ag).
       Condition "ii)" intuitively says that there is a set <u>pla</u> of places that
 "occur in cmd", one of which is out(Ag). When cmd is entered from pla-in any
 transition <pla1,pla2>,d> generated has pla1\epsilon(pla-{out(Ag)})\nu{pla-in} and
 pla2\epsilon pla. Clearly pla = local(Ag).
        Condition "iii)" says what use cmd makes of the place and partial transfer
 function it is entered with. When d-in2 = \lambdas.s the condition expresses what
 difference it makes to come from pla-in2 rather than pla-in1. When pla-in1 =
 pla-in2 it expresses how the partial transfer function influences the set of
 transitions produced.
       We use xpld to express conditions like local(Ag) ≤ xpld(occ). Intuitively
 this says that any place occurring in cmd has play1 to be an extension of
       Lemmas 5.1-4 and 5.1-5 state properties of the non-standard semantics.
LEMMA 5.1-4:
 a) \text{\text{Vcmd: P-F(A&indEcmdlocc)}}
                ~ Local(AgindEcmdIocc) ≤ xpld(occ)
                ^ out(AgindEcmdIocc) = <occ,"cmd)">
 b) \texp: P-F(Acindlexplocc)
               A local(A%indTexpTocc) ⊆ xpld(occ)
               ^ out(AfindTexpTocc) = <occ, "exp)">
 c) ∀exp: ∀pla-in¢local(AfindFexpIocc): ∀d-in∈D:
               {<<pla1,pla2>,d> | pla1=pla-in ^
                                                    <<pre><<pla>,pla2>,d>∈ [A&indFexpI(occ)<pla-in,d-in>ψ2]}
               = {<<plan=in, <occ, "(exp">>, d-in>}
 d) \dcl: P-F(ADindEdcl Tocc)
               ∧ local(ADindEdclHocc) ⊆ xpld(occ)
               a out(ADindEdcLTocc) = <occ, "dcl)">
 Proof is by an (omitted) structural induction that uses the results of Lemma
```

5.1-5.

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Analogues of "c)" also hold for commands and declarations but this will not be needed. We explain the results of Lemma 5.1-5 below.

LEMMA 5.1-5:

- 1) P-F(Aattach pla) \(\) local(Aattach pla) = \{\pla} \(\) out(Aattach pla) = \pla
- 2) P-F(Ag) =>
 P-F(Ag*Arecord(d)) \(\lambda \) local(Ag*Arecord(d)) = local(Ag) \(\lambda \)
 out(Ag*Arecord(d)) = out(Ag)
- 3) P-F(Ag1) \(\text{P-F(Ag2)} \) \(\text{out(Ag2)} \) \(\text{local(Ag1)} = \text{P-F(Ag2*Ag1)} \) \(\text{local(Ag2*Ag1)} = \text{local(Ag2)} \(\text{\text{\text{\$\ext{\$\text{\$\$\text{\$\text{\$\text{\$\text{\$\text{\$\text{\$\text{\$\text{\$\text{\$\
- 4) P-F(Ag1) ∧ P-F(Ag2) ∧ out(Ag2) ∉ Elocal(Ag1)-{out(Ag1)}] =>
 P-F(Ag1 WITH Ag2) ∧ local(Ag1 WITH Ag2) = local(Ag1) ∪ local(Ag2)
 ∧ out(Ag1 WITH Ag2) = out(Ag2)
- 5) P-F(Ag) \(\text{pla1} \in \text{Llocal(Ag)}-\text{out(Ag)}\] =>
 P-F(Ag ALSO \(\left< \text{pla1}, \text{pla2} \right) \(\left\)
 \(\left\) \(\left(\text{Ag ALSO } \left< \left< \text{pla1}, \text{pla2} \right) = \text{local(Ag)} \(\text{out(Ag)} \)
 \(\left\) \(\left(\text{Ag ALSO } \left< \left< \text{pla1}, \text{pla2} \right) = \text{out(Ag)} \)
 \(\text{Proof is omitted.} \)

The intuitive content of "3)" is that P-F is "preserved under sequencing". The condition out(Ag2) \notin local(Ag1) is fulfilled when local(Ag1) \cap local(Ag2) = 0 as is usually the case. Combinator * is as in Table 5.1-A.

One way that out(Ag2) \notin [local(Ag1)-{out(Ag1)}] may hold in "4)" is when out(Ag2) = out(Ag1) as is the case for the conditional. Case "5)" is only needed when considering the WHILE loop.

5.2 Equivalence of the Solutions

In this section we show the desired connection between the data flow information specified by our approach (findEpro1) and the MOP solution. To do so we specify what we understand by the MOP solution. For this we need the function Close:

OBSERVATION 5.2-2: \footnote{ \footnote{ trans, pla, s} is isotone. []

Recall that R(f)(g) = λ l.f(g(l)) (subsection 2.4.2) and let start = <<>,"(pro"> and init (S. Note that (R U) (Close(A)PindEpro (I), start, {init})) closely corresponds to the formulation of the MOP solution in section 2.3: λ arc.U{Bf<start,...,arc> init | <start,...,arc> is a path }. This is because Bf and APindEpro (I) are related as stated in section 5.1. A difference that we will ignore throughout is that the two formulations disagree on start.

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To prove (and state) the relationship between \mathcal{P} ind \mathbb{F} pro \mathbb{I} and A \mathcal{P} ind \mathbb{F} pro \mathbb{I} we define the predicate P-G (explained below):

DEFINITION 5.2-3:

The use of EQ instead of = is motivated later (in the proof of Lemma 5.2-5). Note that the first two \square in P-G are joins of Pla -t> S whereas the third is the join of S.

Suppose $c = ind-finish = \bot$ and $\underline{s} = \{init\}$ in the definition of P-G. Then P-G(g,Ag) says that (g;c)init equals the MOP solution (R \sqcup)(cl). When $c \neq \bot$ the expression $\sqcup \{c(s) \mid s \neq c \mid (out(Ag))\}$ is needed to represent the effect of "the rest of the program". To understand it note that $c \mid (out(Ag))$ is intended to be (when $\underline{s} = \{init\}$):

{Bf<pla-in,...,out(Ag)> init | <pla-in,...,out(Ag)> is a path } We need to write $U(c(s) \mid secl(out(Ag)))$ rather than c(U(cl(out(Ag)))) because we do not assume that ind is a "distributive framework".

A partial result in showing that \mathcal{P} ind \mathbb{E} pro \mathbb{I} is the MOP solution is:

LEMMA 5.2-4:

pure[Occ](occ) => P-G(DindEdclIocc, ADindEdclIocc)
pure[Occ](occ) => P-G(ZindEexpIocc, AZindEexpIocc)
Proof We omit the proof, which is by structural induction. Use is made of Lemmas 5.2-5, 5.2-6 and 5.2-7.

The proof of the following lemma shows why we use EQ rather than =.

LEMMA 5.2-5: pure[Pla](pla) => P-G(ind-attach pla, ind-Aattach pla) []
Proof is shown in appendix 5.

LEMMA 5.2-6: $P-G(g2,Ag2) \wedge g1 = \lambda c.c \cdot Dg1 \Rightarrow P-G(\lambda c.g1;g2;c,Ag2*Arecord(Dg1))$

LEMMA 5.2-7: $P-G(g1,Ag1) \wedge P-G(g2,Ag2) \wedge local(Ag1) \wedge local(Ag2) = 0 => P-G(\lambda c.g1;g2;c, Ag2*Ag1)$ Proof is shown in appendix 5.

One way to paraphrase the condition local(Ag1) alocal(Ag2) = 0 is: "the set of places occurring in g1 is disjoint from the set of places occurring in g2".

To intuitively and informally explain how this condition is used in the proof one may perceive $f \in F$ as a "flowchart". One traces through f by (non-deterministically) following a path $\langle pla0,...,pla[n] \rangle$ where $\forall i \in \{1,...,n\} \exists di: \langle pla[i-1],pla[i] \rangle, di \rangle \in f\langle pla0,\lambda s.s \rangle \ \forall 2.$

Then the condition local(Ag1) $_{n}$ local(Ag2) = 0 is used in the proof to express the situation in which g2 may be "entered" from g1 and to assert that once g2 has "been entered" from g1 it is impossible to "enter" g1 again.

Another partial result in showing that \mathcal{F} ind \mathbb{F} pro \mathbb{I} is the MOP solution is:

LEMMA 5.2-8: pure[Occ](occ) => P-G(&indFcmdlocc, A&indFcmdlocc) []

Proof is shown in appendix 5.

```
It is more difficult to establish this lemma than Lemma 5.2-4. The proof uses
 Lemmas 5.2-9 and 5.2-11 below. Lemma 5.2-9 is useful for handling the
 conditional.
LEMMA 5.2-9: P-G(g1,Ag1) A P-G(g2,Ag2) A out(Ag1)=out(Ag2) A
 local(Ag1)nlocal(Ag2)={out(Ag2)} =>
 P-G(\(\frac{\c.}{\c.}\)c.cond(g1;c, g2;c),

EAg1*Arecord(ind-Dt-cond)] WITH EAg2*Arecord(ind-Df-cond)])
                                                                                      \Gamma \gamma
 Proof is shown in appendix 5.
                                                                                      The condition local(Ag1) \( \text{Ag2} \) = \( \text{Lout(Ag2)} \) = \( \text{Lout(Ag1)} \) is used in the
 proof to assert that once g1 has been "entered" it is impossible to "enter"
 g2, and vice versa.
    To factor out the complexities of handling the WHILE construct we state
 the "technical" Lemma 5.2-11. It employs the function Luk which essentially
 is as Close but constrains the use of some transitions.
DEFINITION 5.2-10: Define
 Luk: P(Trans) \ X \ Pla \ X \ P(S) \ X \ Integer \ X \ P(Trans) -> ( Pla -t> P(S) ) by
 Luk( <u>trans1</u>, pla-in, <u>s</u>, k, <u>trans2</u>) pla-out =
 \{dn(...(d1(s))) \mid s \in s \land n \geq 1 \land
          ∃ <<pla[0],pla[1]>,d1>,...,<<pla[n-1],pla[n]>,dn>etrans1otrans2
          so that pla[0]=pla-in ^ pla[n]=pla-out
          and \{i \mid \langle pla[i-1], pla[i] \rangle, di \rangle \in trans2\} | = k \}
                                                                                      Here |\{...\}| is the cardinality of the set \{...\}.
LEMMA 5.2-11:
 Abbreviate:
    pla-begin = <occ,"(cmd">
                                                plaR = <occ§<1>,"(exp">
    plaT = <occ <<1>, "exp)">
pla-out = <occ, "cmd)">
                                                 plaB = <occ§<2>,"cmd)">
    (A)g1 = (A)  find E exp I occ <math>  <1>
    (A)g2 = (A) & ind E cmdI occS<2>
    g[c]c' = g1; cond(g2;c', attach(pla-out);c)
    Aq = (EAq2*Arecord(Dt-cond)]
           WITH [Aattach(pla-out) * Arecord(Df-cond)])
          * Aq1
    a[k+1] = Luk(Ag < pla-begin, \lambda s.s > \psi 2, pla-begin, s, k, {<< plaB, plaR>, \lambda s.s > \rangle)
 Assume:
    pure[Occ](occ) \wedge P-G(g1,Ag1) \wedge P-G(g2,Ag2)
 Then \forall k > 1:
    U\{(g[c])^{\kappa}(\bot)(s) \mid ses\} = U\{c(s) \mid se([aku...ua1] pla-out)\}
                                   (R U) [aku...ua1]
                                                                                      Proof is shown in appendix 5.
                                                                                      The abbreviations of places are in accordance with the figure for the WHILE
 loop in section 5.1. Lemma 5.2-11 intuitively says that
U(g[c])^{\kappa}(1)(s) \mid s \in S approximates the effect of the WHILE construct (and
```

the rest of the program) by allowing the WHILE loop to be iterated at most k-1 times. Here one iteration means to "follow" the <<plaB,plaR> λ s.s>

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transition once.

From Lemmas 5.2-4, 5.2-7 and 5.2-8 it is quite easy to show that \mathcal{P} ind \mathbb{E} pro \mathbb{I} specifies the MOP solution:

THEOREM 5.2-12: \(\forall \text{pro}\epsilon \text{Pro}\epsilon \text{Vinp}\epsilon(\text{Inp}\epsilon): \(\text{PindEpro}\text{Inp} \text{EQ}\)
\(\lambda \text{Lond}\text{(d1(uabs{ <\lambda}ide."nil" inVal, inp, <>, <>> | inp\epsilon \text{inp}\))) |
\(\text{n\gamma} \tau \frac{3}{\text{cond}} \text{plaO,pla1>,d1>,...,<\lambda \text{plaEn]=pla}}\)
\(\text{Proof is shown in appendix 5.}\)

As mentioned earlier this development also holds for his-ind and ae as well as for sts and his-sts.

CHAPTER 6

Program Transformations

In this chapter (section 6.1) we investigate how data flow information specified by our approach can be used to validate a class of program transformations that includes a "constant folding" example [AhU78,p.409]. In section 6.2 we briefly relate our approach to other work.

A property of a denotational semantics is that it is always possible to replace one syntactic construct with another that has the same denotation {a}. But this is not sufficient to validate the program transformations considered e.g. in optimizing compilers. Consider constant folding that replaces an expression (e.g. i+3) by a constant (e.g. 5) provided the expression can only be "reached" with a constant value of the identifiers occurring in it (e.g. i=2). But the denotations of the expression (i+3) and the constant (5) are usually not the same.

By a "computational context" we understand a set of states that are possible at some place, i.e. \mathcal{S} sts \mathbb{E} pro \mathbb{I} inp<occ,"(...">. To be able to validate program transformations it is necessary only to require that the two syntactic constructs produce the same result in the computational context in which they occur. In the example above it is sufficient that any state in the computational context maps i to 2. Our method is one way of validating program transformations by taking computational contexts into account.

6.1 The Method

We formalize (in subsection 6.1.1) the notion of "a labelled parsetree" and formally define some operations upon labelled parsetrees; these operations are not considered in Denotational Semantics. Then (in subsection 6.1.2) we formulate the semantic functions in the new notation and prove some properties of continuation removal. Our subsequent development is mostly in terms of the continuation removed functions.

In subsection 6.1.3 we prove some "intuitively obvious" properties about the data flow information specified. The properties are needed in subsection 6.1.4 where we prove sufficient "local" conditions for when a program is semantically equivalent to a transformed program. These conditions take the computational context into account and are adequate to give an easily tested condition for the validity of "constant folding" as well as many other program transformations.

[{]a} When talking about "denotation" and "semantically equivalent" we assume this is with respect to interpretation std.

6.1.1 Labelled Parse-trees

```
In this subsection we give a formal definition of a labelled parse-tree. We do so in order to give formal definitions of "the subtree at occurrence lab" and "the tree obtained by replacing the subtree at lab by ...". The definitions are adapted from [Ros73].
```

We assume that no two elements of Prod have the same second component. It is convenient to define "names" for the syntactic categories by Cat = $\{prod \psi 1 \mid prod \varepsilon Prod\}$ and similarly "names" for the right-hand sides by Str = $\{prod \psi 2 \mid prod \varepsilon Prod\}$. Finally, we need a set of labels. We use Lab = $\{occ \varepsilon Occ \mid pure [Occ](occ)\}$ rather than Occ to avoid some special cases below (e.g. so that root below is always defined).

We now define the labelled parse trees by defining $\forall lab \in Lab$: $\forall cat \in Cat$: the sets $Tree(lab, cat) \subseteq \mathcal{P}(Lab \land Prod)$. Intuitively, $t \in Tree(lab, cat)$ is a labelled parse—tree of category cat whose root is labelled lab. Formally, it is a set containing for each node a tuple (label and production). The trees are defined inductively as shown by Table 6.1-A, where we "imitate" the productions of Table 2.2-A. It is convenient to define $Tree = U\{Tree(lab, cat) \mid lab \in Lab \land cat \in Cat\}$.

Below we state some properties fulfilled by the trees. They are intuitively obvious and we omit the proofs. We also define some notation.

OBSERVATION 6.1.1-1:

```
teTree(lab,cat) => ∃!str: <lab,<cat,str>>et ∧ ∀lab',cat',str':
  [ <lab',<cat',str'>> € t-{<lab,<cat,str>>} => lab≠lab' ∧ lab'=lab{<...>]
teTree => ∃!<lab,<cat,str>>: <lab,<cat,str>>et ∧ teTree(lab,cat)
```

Similarly to the abbreviations made in chapter 4 we let (for $x \in Lab \times Prod$) x_lab mean $x \notin 1$, x_cat mean $x \notin 2 \notin 1$ and x_str mean $x \notin 2 \notin 2$...> means $\forall lab : lab :$

DEFINITION 6.1.1-2:

```
root: Tree -> Lab%Prod is defined by root(t) = <lab,<cat,str>>et]
```

```
<u>at</u>: TreeXLab -> \theta(LabXProd) is defined by t <u>at</u> lab = {<lab', <cat, str>> | lab'=lab<-...> \wedge <lab', <cat, str>>\epsilont}
```

dom: Tree \rightarrow P(Lab) is defined by dom(t) = {lab | <lab, <cat, str>> ϵ t}

```
TABLE 6.1-A --- DEFINITION OF PARSE-TREES
Made with state and with place with their time with state with time with time with their time with their time with t
t1eTree(lab <1>,"ide") => {<lab,<"cmd","READ ide">>} t1 e Tree(lab,"cmd")
t1eTree(labs<1>, "exp") ~ t2eTree(labs<2>, "ope") ~ t3eTree(labs<3>, "exp") => {<lab,<"exp", "exp1 ope exp2">>}, t1ut2ut3 e Tree(lab, "exp")
t1eTree(lab $<1>, "ide") => {<lab,<"exp", "ide">>}vt1 & Tree(lab, "exp")
t1∈Tree(lab§<1>,"bas") =>
{<lab,<"exp","bas">>}₀t1 ∈ Tree(lab,"exp")
ide&Ide =>
       {<lab,<"ide",ide>>} € Tree(lab,"ide")
       {<lab,<"bas",bas>>} & Tree(lab,"bas")
opeeOpe =>
       {<lab,<"ope",ope>>} & Tree(lab, "ope")
   ...(...<-...): TreeXLabXTree -> P(LabXProd) is subtree replacement and is
  defined by
   t1(lab<-t2) = {<lab', <cat', str'>>et1 | lab'#lab$<...>}
                              U {<\lab\{\lab\;\cat\'\str\'>> | <\lab\'\\cat\'\str\'>>€t2}
   soni: Tree→>P(LabXProd) is defined by
  soni(t) = t at (root(t).lab < i>)
                                                                                                                                                                         OBSERVATION 6.1.1-3:
   tree €Tree ∧ lab €dom(tree) => tree at lab € Tree
  tree1eTree ^ (3str: <lab, <cat, str>>etree1) ^ tree2eTree(<>,cat) =>
                tree1(lab<-tree2) Tree
```

TABLE 6.1-B --- SEMANTIC FUNCTIONS ${\cal P}$ and ${\cal T}$

```
T € Tree -t> C -c> C
                                                                                                                                                                                                                P ← Tree(<>,"pro") -t> I -t> A
f(tree)(c) =
                                                                                                                                                                                                             P(tree) =
          CASE root(tree).str OF
"BEG dcl IN cmd END":
attach<root(tree).lab,"(">;
                                                                                                                                                                                                                         setup( T(tree); finish )
                    T(son1(tree));
T(son2(tree));
         attach<root(tree).lab,")">;c
"DCL ide:=bas":
      "DCL ide:=bas":
   attach<root(tree).lab,"(">;
   push( root(son2(tree)).str );
   assign( root(son1(tree)).str );
   attach<root(tree).lab,")">;
   "exp1 ope exp2":
   attach<root(tree).lab,"(">;
    f(son1(tree));
   f(son3(tree));
   apply( root(son2(tree)).str );
   attach<root(tree).lab,")">;
   "ide":
   attach<root(tree).lab,")">;
   attach<root(tree).lab,")">;
   "ide":
   attach<root(tree).lab,")">;
   attach<root(tree).lab,")">;
   "ide":
       attach<root(tree).lab,"(">;
content( root(son1(tree)).str );
attach<root(tree).lab,")">;c
     T(son1(tree));
cond( T(son2(tree));
attach<root(tree).lab,")">;c
, T(son3(tree));
   "WHILE exp D0 cmd OD":
attach<root(tree).lab,")">;c)
"tach<root(tree).lab,"(">;
FIX( \( \lambda c' \) \( \tau 
                                                                                        , attach<root(tree).lab,")">;c))
     "WRITE exp":
               attach<root(tree).lab,"(">;
               J(son1(tree));
    write;
attach<root(tree).lab,")">;c
"READ ide":
               attach<root(tree).lab,"(">;
               read;
              assign( root(son1(tree)).str );
attach<root(tree).lab,")">;c
    OTHERWISE:
   ESAC
```

TABLE 6.1-C --- SEMANTIC FUNCTION P

```
PJ € Tree -t> S -c> R
Pf(tree) =
    CASE root(tree).str OF "BEG dcl IN cmd END";
         Pattach<root(tree).lab,")"> *
Pπ(son2(tree)) *
Pπ(son1(tree)) *
    Pattach<root(tree).lab,"(">
"dcl1; dcl2":
        Pattach<root(tree).lab,")"> *
PJ(son2(tree)) *
PJ(son1(tree)) *
    Pattach<root(tree).lab,"(">
"DCL ide:=bas":
   "DCL ide:=bas":
   Pattach<root(tree).lab,")"> *
   Passign( root(son1(tree)).str ) *
   Ppush( root(son2(tree)).str ) *
   Pattach<root(tree).lab,"(">
"exp1 ope exp2":
   Pattach<root(tree).lab,")"> *
   Papply( root(son2(tree)).str ) *
   PJ(son3(tree)) *
   PJ(son1(tree)) *
   Pattach<root(tree) lab "(")
    Pattach<root(tree).lab,"(">
"ide":
         Pattach<root(tree).lab,")"> *
Pcontent( root(son1(tree)).str ) *
Pattach<root(tree).lab,"(">
    "bas"
    Pattach<root(tree).lab,")"> *
Ppush( root(son1(tree)).str) :
Pattach<root(tree).lab,"(">
"cmd1; cmd2":
         Pattach<root(tree).lab,")"> *
PJ(son2(tree)) *
PJ(son1(tree)) *
    Pattach<root(tree).lab,"(">
"ide := exp":
         Pattach<root(tree) lab,")"> *
Passign( root(son1(tree)) str ) *
P$(son2(tree)) *
    Pattach<root(tree).lab,"(">
"IF exp THEN cmd1 ELSE cmd2 FI":
Pcond( Pattach<root(tree).lab,")">
Pf(son2(tree))
Pattach<root(tree).lab,")">
Pf(son3(tree)) *
         Pf(son1(tree)) *
    Pattach<root(tree).lab,"(">
"WHILE exp DO cmd OD":
FIXE \( \rangle \ss. \) P \( \forall \) (son2(tree))
    Pattach<root(tree).lab,")">) *
Pattach<root(tree).lab,")">) *
Pattach<root(tree).lab,"(">
"WRITE exp":
Pattach<root(
         Pattach<root(tree).lab,")"> *
         Pwrite *
Pf(son1(tree)) *
    Pattach<root(tree).lab,"(">
"READ ide":
         Pattach<root(tree).lab,")"> *
Passign( root(son1(tree)).str ) *
          Pread
    Pattach<root(tree).lab,"(">OTHERWISE:
     ESAC
```

6.1.2 Semantic Functions

In this subsection we formulate the semantic functions with respect to the new "notation" (Table 6.1-B). Also we perform continuation removal for the entire language (Table 6.1-C).

There is a close correspondence between Tables 6.1-B and 2.2-C as well as some minor differences. One is that we have combined \mathcal{J} , \mathcal{E} and \mathcal{E} into the single function \mathcal{T} . Also (in attach) we elide the "dcl", "cmd" and "exp" parts of the places. The changes have been performed to simplify later formulations but are otherwise unimportant. In the definition of \mathcal{T} we use a CASE construct that is hopefully self-explanatory.

Similarly to Theorem 2.2-4 and Lemma 4.2.1-1 we have (omitting the proofs):

LEMMA 6.1.2-1: Table 6.1-B and an interpretation int define functions \mathcal{P} int and \mathcal{F} int. They are of functionalities as shown and no function is supplied with an argument of the wrong type.

LEMMA 6.1.2-2: Table 6.1-C and std (as augmented by 4.2-B) define a function P \mathcal{I} std. Similarly, Table 6.1-C and sts (as augmented by 4.2-C) define a function P \mathcal{I} sts. They are of functionalities as shown and no function is supplied with an argument of the wrong type.

We now prove the "correctness" of our formulation of continuation removal, i.e. we relate \mathcal{T} and $P\mathcal{T}$.

LEMMA 6.1.2-3:

LEMMA 6.1.2-4: \text{\tree}\text{Tree: \text{\tree}}\text{\tree}\t

6.1.3 Properties of the Data-Flow Information

We now prove some properties of PT(tree) that will be needed to validate the program transformation in subsection 6.1.4. The properties are expressed by Lemmas 6.1.3-2, 6.1.3-5 and 6.1.3-7 below.

We first show a relationship between $\lambda \underline{sta}$ -Pfsts(tree) \underline{sta} \forall 1 and Pfstd(tree). The result bears some relationship to Lemma 4.2.1-4.

DEFINITION 6.1.3-1: Define P-G : $[(std-S-c) \times (sts-S-c) \times (sts-S-c)] \rightarrow B$ by P-G(std-ss,sts-ss) = $\forall sta \in P(Sta)$:

LEMMA 6.1.3-2: ∀tree ←Tree: P-G(P√std(tree), P√sts(tree)) []
Proof is shown in appendix 6. []

COROLLARY 6.1.3-3: Asta. PJsts(tree)sta V1 is a complete-u-morphism.

We now show some simple properties of PTsts(tree).

```
DEFINITION 6.1.3-4: Define predicates Pa:Tree->B, Pb:Tree->B and Pc:Tree->B
 Pa(tree) = \forall sta \in P(Sta): (P\mathcal{I}sts(tree)sta \forall 2)<root(tree).lab,"("> = sta
 Pb(tree) = \forall sta: (P\int sts(tree) sta \forall 2) < root(tree) . lab,")"> = P\int sts(tree) sta \forall 1
 Pc(tree) = \forall sta\epsilon P(Sta): \forall lab\epsilon Lab: \forall q\epsilon Q:
              E pure[Pla]<lab,q> \( \) lab (dom(tree) =>
                Predicates Pa, Pb and Pc are used to prove predicates Pd and Pe below.
 Predicate Pc constrains the places for which Psts(tree) can specify non-
 empty data flow information; this is needed when we perform proofs by
 structural induction.
LEMMA 6.1.3-5: ∀tree∈Tree: Pa(tree) ∧ Pb(tree) ∧ Pc(tree)
                                                                                       Proof is shown in appendix 6.
                                                                                       ГЛ
    We now consider some interesting properties of P\mathcal{I}sts(tree). Together with
 Lemma 6.1.3-2 they are the fundament for validating program transformations
 (Theorem 6.1.4-2).
DEFINITION 6.1.3-6: Define predicates Pd: TreeXLab -> B and Pe: TreeXLab -> B
 by
 Pd(tree, lab) = \forall \underline{sta} \in P(Sta):
                  LET a = P√sts(tree)sta √2 IN
                  a < lab,")" > = (P \mathcal{F} sts(tree at lab) (a < lab,"(">)) \forall 1
 Pe(tree, lab) = \forall \underline{sta} \in P(Sta):
                  LET a = PTsts(tree)sta \psi 2 IN
                  LET str = root(tree at lab).str IN str e {"dcl1 ; dcl2", "cmd1 ; cmd2", "BEG dcl IN cmd END"} =>
             i)
                  a<lab <<1>,"("> = a<lab,"("> ^
                  a < lab < < 2 >,"("> = a < lab < < 1 >,")">
                  str = "exp1 ope exp2" =>
                  a<lab <<1>,"("> = a<lab,"("> ^
                  a<lab{\( \frac{3}{3} \),"("> = a<lab{\( \frac{5}{1} \),")">
            iii) stre{"ide := exp", "WRITE exp"} =>
                  a<lab <<1>,"("> = a<lab,"(">
             iv) str = "IF exp THEN cmd1 ELSE cmd2 FI" =>
                  a<lab << 1>,"("> = a<lab,"("> ^
                  a<lab <<2>,"("> = sts-Dt-cond( a<lab <<1>,")"> )
                  a<labs<3>,"("> = sts-Df-cond( a<labs<1>,")"> )
                  str = "WHILE exp DO cmd OD" =>
            V)
                  LET F = [\lambda \underline{sta}, PJ \underline{sts}(tree \underline{at} lab \underline{s} < 2) sta \( 1 \) ] \circ
                            sts-Dt-cond •
                            [Asta. PJsts( tree at labs<1> ) sta v1 ] IN
                  a < lab < 1 > ,"("> = U { F"( a < lab,"("> ) | n > 0 } 
                  a < lab < 2 > "(" > = sts-Dt-cond( a < lab < 1 > ")" > )
 Also define predicates Pd': Tree -> B and Pe': Tree -> B by
 Pd'(tree) = \lab\epsilondom(tree):
    [ root( tree at lab ).cat € {"dcl", "cmd", "exp", "pro"} => Pd(tree, lab) ]
 Pe'(tree) = ∀lab€dom(tree):
    [ root( tree at lab ).cat € {"dcl", "cmd", "exp", "pro"} => Pe(tree, lab) ]
```

In the sequel we do not consider parse-trees of category "ide", "ope" or "bas". This is expressed by the definitions of Pd" and Pe" above and simplifies the development.

LEMMA 6.1.3-7: ∀tree ←Tree: Pd'(tree) ∧ Pe'(tree)

Proof is shown in appendix 6.

[]

6.1.4 Validity of Program Transformations

The key result of this subsection is Theorem 6.1.4-2 that gives sufficient conditions for when tree1 and tree1(lab <- tree2) are semantically equivalent. The major positive virtue is that we do not need to require that tree1 at lab and tree2 are semantically equivalent, but only that they produce the same results in the computational contexts in which they occur. This is expressed by P2 below.

We now rephrase Theorem 6.1.4-2 so as to avoid continuation removal where possible:

THEOREM 6.1.4-3:

Proof is shown in appendix 6.

t1eTree \(\tau \) t2eTree \(\tau \) labeLab \(\tau \) inpeP(Inp) \(\tau \)

\(\tau \) t7ree(\(\tau \), "pro")

\(\tau \) t1', t2' \in Tree(\(\tau \), "pro") \(\tau \) t7ree(\(\tau \), "dcl") \(\tau \) Tree(\(\tau \), "cmd") \(\tau \) Tree(\(\tau \), "exp"):

\(\tau \) t1 = t(lab \(\tau \) t1') \(\tau \) t2 = t(lab \(\tau \) t2') \(\tau \)

\(\tau \) t3aePsts(t1) inp<\labelab, "(">:

\(\tau \) t3abe\(\tau \) inp

\(\tau \) inpeinp: \(\tau \) t3t(t1) inp = \(\tau \) t3t(t2) inp

\(\tau \) Proof is shown in appendix 6.

Below we formulate a special case of Theorem 6.1.4-3 that expresses sufficient conditions for constant folding to be valid. It has been formulated so as to make it clear that each test can be verified automatically; especially if the test concVa(...) ... is replaced by ... EdabsVa(...) for dabsVa and concVa semi-down-adjoined (2.4.3). The proof is tedious (and long) and is omitted because it gives no insight.

```
COROLLARY 6.1.4-4:
```

```
Let bas€Bas
```

treeeTree(<>,"pro")
labedom(tree) such that root(tree at lab).cat = "exp"
tree' = tree(lab <- { <<>,<"exp","bas">>, <<1>,<"bas",bas>>})
<uabs,conc> be the pair of semi-adjoined functions defined in section

3.2 in terms of the pair <uabsVa,concVa> of semi-adjoined functions If concVa(\mathcal{P} ind<uabs,conc>(tree)inp <lab,")"> ψ 2 ψ 1) \subseteq {std- \mathcal{B} Ebas}1} then \forall inp \in inp: \mathcal{P} std(tree)inp = \mathcal{P} std(tree')inp

When program transformations are performed in practice it is often important to know how the data flow information for the transformed program (tree') can be cheaply obtained from that of the original program (tree). Our approach makes it possible to show such relationships, e.g. (in the notation of Corollary 6.1.4-4) that $pla v1 \neq lab < ... >$ pure [Pla](pla) = plavaleta > plavaleta > pind(tree) plavaleta = pind(tree') plavaleta = plavaleta > plavaleta = p

6.2 Comparison with Other Approaches

Below, we briefly relate the approach of this chapter to other approaches considering the validity of program transformations [HuL78][Ger75]. The comments will be informal because both the aims and the semantic foundations of the papers differ from those of our development.

Comparison with [HuL78]

The aim of [HuL78] is to consider "[program] transformations based on control structure equivalence", e.g. recursion removal. The semantic foundation is different from Denotational Semantics as described in [Sto77] and [MiS76].

Consider programs t1 = t(lab <- t1') and t2 = t(lab <- t2'). The paper considers easily tested conditions for asserting that t1 and t2 are equivalent, i.e. PJstd(t1) = PJstd(t2). Clearly one can view t2 as obtained from t1 by a program transformation that replaces t1' by t2'. All the conditions are sufficient to deduce PJstd(t1') = PJstd(t2'), i.e. that the two syntactic constructs produce the same result for all states. Thus the paper does not consider the possibility of PJstd(t1) = PJstd(t2) when PJstd(t1')sta = PJstd(t2')sta only holds for the states (sta) of the computational context in which t1' and t2' occur. A consequence is that the method of [HuL78] is inadequate for validating program transformations like constant folding.

Comparison with [Ger75]

The aim of [Ger75] is to consider correctness of programs (and program transformations) with respect to an input predicate Pin and an output predicate Pout. That two programs t1 and t2 are both correct with respect to Pin and Pout does not, in general, imply that they produce the same results for inputs satisfying Pin. But in many situations (including our treatment of constant folding) it can be arranged that this is the case.

The semantic foundation is the "inductive assertions method" formulated using attribute grammars.

Assume that t1 = t(lab <- t1') and t2 = t(lab <- t2'). Programs must describe the predicates Pin and Pout as well one predicate for each WHILE loop. A predicate belonging to a WHILE loop specifies an approximate set of states expected to include the states possible at that point. Predicates Pin and Pout are denoted t1.Pin, etc. and we assume that t1.Pin = t2.Pin ^ t1.Pout = t2.Pout.

The approach of [Ger75] is to define (in effect) PSTa specifying "forward

attributes" and PIfvc specifying "forward verification conditions".

Essentially PJfa(t) is PJsts(t){sta|t.Pin(sta)} \forall 2 so that PJfa(t)<lab,"("> describes a set of states. But PJfa(t)(pla) exploits the predicates described in the WHILE loops of t in order to express an (approximate) set of states that includes those holding at pla. This is in contrast with our approach where abstract interpretation is powerful enough to express this set of states without exploiting such predicates.

That PJfa(t)(pla) exploits the predicates belonging to the WHILE loops of t has as a consequence that these predicates must be verified. The logical formula PJfvc(t) formulates a correctness condition in terms of PJfa(t). When PJfvc(t) is true it is said that t is correct. - Very roughly PJfvc(t) corresponds to our Pe'(t), but it is not always true (contrary to Pe'(t)) because the predicates in the program need not be satisfied.

The paper does not explicitly consider an analogue of PTstd. It is merely stated that PTstd must be so that PTtvc(t) \land t.Pin(sta) implies t.Pout(PTstd(t)sta) and that the predicates belonging to the WHILE loops are satisfied.

In [Ger75,p.64] there is a schematic transformation that includes constant folding. Sufficient conditions to deduce correctness of t2 are

a) t1 is correct, and

b) \forall sta \in P \mathcal{F} fa(t1)<\lab,"("> that P \mathcal{F} std(t1")(sta) = P \mathcal{F} std(t2")(sta) As mentioned earlier, correctness of t1 and t2 can be made to imply that P \mathcal{F} std(t1) and P \mathcal{F} std(t2) are equivalent for all states satisfying t1.Pin. Thus the approach of [Ger75] can be used to validate constant folding.

The main virtue of [Ger75] is that a notion of computational context is present (see "b)" above) so that e.g. constant folding can be validated. But it is difficult to automate the method. One reason is that $P\mathcal{T} + vc(t1)$ must be proven and that the formula often is "structurally complex, although not necessarily deep" [Ger75,p.55]. Another is that $P\mathcal{T}$ a requires that each WHILE loop contains a predicate in order to describe (approximately) the set of states possible inside WHILE loops.

We therefore feel that our approach is better suited to verify program transformations than that of EGer75].

CHAPTER 7

Conclusion

There are (at least) two ways of viewing the development of this paper. The first view emphasizes the <u>formulation</u> of data flow analyses: history-insensitive analyses (chapter 3) and history-sensitive analyses (chapter 4). This view corresponds to that of <code>[Don79]</code>. But the theorems stated do not formally relate the data flow information \mathcal{F} ind <code>FproI</code> to the semantic meaning \mathcal{F} std <code>FproI</code>. This is because of the loose connection between \mathcal{F} col and \mathcal{F} std (or \mathcal{F} tra and \mathcal{F} std). Similar remarks apply to \mathcal{F} his-ind and \mathcal{F} as

We have taken a second view that emphasizes the <u>formulation</u> of data flow analyses as well as a <u>relationship</u> between the data flow information and the semantics. An indication of the usefulness of \mathcal{P} ind even if it could not be related to \mathcal{P} std is achieved by relating the data flow information specified by our approach to the solutions considered in traditional data flow analysis (chapter 5). Similar remarks apply to \mathcal{P} his—ind and \mathcal{P} ae. The validation of program transformations is one way of relating \mathcal{P} ind to \mathcal{P} std (chapter 6). — We have been unable to think of others.

Our approach to formulating data flow analyses is based on expressing abstract interpretation in a denotational setting.

We hope that our motivation and analysis of the concepts from abstract interpretation gives more insight than previous motivations (section 2.4). In particular, the concept "semi-adjoined" is closer than "adjoined" to the informal approximation ideas that are considered in "traditional data flow analysis" {a}. We expect it to be possible to weaken our assumption that only complete lattices are considered. It is interesting if the isotony assumption of "semi-adjoined functions" can be weakened in such a way that Theorem 3.1-10 still holds.

The dual concepts "semi-down-adjoined" and "down-adjoined" are useful when considering program transformations, as indicated by the remarks leading up to Corollary 6.1.4-4.

The formulation of Abstract Interpretation within Denotational Semantics gives a more high-level formulation than the usual (chapter 3). That the entire development is based on semi-adjoined functions shows the usability of the concept "semi-adjoined".

From a practical point of view the material of sub-section 2.4.2 shows that pairs of semi-adjoined functions can be specified in a systematic way. This is useful because the concept of "induced interpretation" makes it

[{]a} Let uabs be an abstraction function and conc a concretization function. A consequence of requiring uabs and conc to be adjoined is that conc • uabs must be extensive, isotone and idempotent. When uabs and conc are semi-adjoined then conc • uabs need not be idempotent. The "informal approximation ideas" amount to conc • uabs being extensive.

[Ch₂7] Conclusion

possible to specify a data flow analysis simply by giving a pair of semi-adjoined functions (between $\mathcal{P}(Sta)$ and some complete lattice). This is demonstrated by the "constant propagation" example of section 3.2.

There is a problem inherent in our approach. The applicability is limited because we are unable to define reflexive powersets. Thereby language constructs as labels and procedures cannot be handled.

We hope to investigate whether the literature on power-domains contains tools that can extend the applicability of our method. Reflexive powersets amounts to defining a domain that contains its own powerset. Since this is impossible (Cantor's Theorem [Hal60]) we must exclude some elements similarly to Scott's exclusion of non-continuous functions when solving $X = X \rightarrow X$. In section 3.1 we mentioned that modelling the powerset by ...-c>T" excluded elements that we wanted to be there {a}.

Intuitively, in our approach we use two kinds of partial orders. Some are interpreted as in Denotational Semantics, i.e. $\[\]$ means "less defined than" in the sense of Scott [Sto77]. Others, e.g. those of $\mathcal{P}(\[\]$ can maybe more naturally be thought of as "logically implies", because $\mathcal{P}(X)$ is isomorphic to the set (X -t> T") of predicates on X. - These two ways of considering $\[\]$ are different. This gives an intuitive explanation for why e.g. the continuations of col are not continuous.

The development of this paper was based on a single table of semantic equations so that the entire development must be redone for another table of semantic equations. It should be possible to avoid this by specifying a class of semantic tables (e.g. by a grammar or an algebra) such that Theorems 3.1-6 and 3.1-10 hold in this more general case.

"Available expressions" is a forward, history-sensitive data flow analysis. We share with <code>[CoC77a]</code> the belief that it cannot be given any semantic characterization with respect to the static semantics (using sts). This is contrary to what holds for "constant folding". Instead we obtained a semantic characterization with respect to a more "concrete" static semantics (using his-sts in chapter 4). We believe that this extends the applicability of abstract interpretation, and that it is not crucial (but maybe helpful) that we work from a denotational semantics <code>{b}</code>.

Probably neither sts nor his-sts is adequate for giving a semantic characterization of the backward analysis "live variables". Presumably the role of \mathcal{P} his-sts will be played by a semantic function \mathcal{P} fut-sts that associates (sets of) continuations with places. Whether it is necessary to work with sets of continuations rather than just continuations is difficult to predict.

A set of live identifiers can be obtained from a continuation c by e.g. r(c) = { ide∈Ide | ∃<env,inp,out,wit>∈Sta ∃val1,val2∈Val:

c<env[val1/ide],inp,out,wit> # c<env[val2/ide],inp,out,wit> }
As in section 4.2 it probably is natural to develop a semantic notion of
liveness and approximate it by the syntactic notion.

[{]a} Recall that T" is the complete lattice ({yes,no},⊆) with no ⊆ yes.

[{]b} In the flow-chart view one would have to consider local analysis as well as global analysis. Alternatively, the basic blocks must contain only one operator (in one expression).

The constant propagation example of section 3.2 is similar to that of <code>EDon79</code>, <code>section 7.1]</code>. Two other data flow analyses formulated in <code>EDon79</code> are determination of common subexpressions <code>EDon79</code>, <code>section 7.2]</code> and determination of invariant expressions <code>EDon79</code>, <code>section 7.3]</code>. Our approach cannot directly model any of these. One reason is that both formulations have the domain of inputs to be Q^* where $q \in Q$ identifies a symbolic input value. It would be interesting to investigate how to model this by means of abstract interpretation.

We indicate the usefulness of our approach in two ways. One is to compare the information specified by our approach to the solutions of traditional data flow analysis. The other is to validate program transformations.

To relate our approach to that of traditional data flow analysis we constructed a "traditional" data flow analysis problem from a program (chapter 5). One shortcoming of this construction is that it considers smaller basic blocks than usual. We then showed that the MOP solution to the constructed problem equals the information specified by our approach. Informally stated: our approach specifies the MOP solution.

It would be interesting to obtain a formulation that specifies the MFP solution. This could be used to formulate the work of [Ros 80] in our approach, i.e. to specify elimination methods computing a solution between MFP and MOP. We conjecture that a kind of MFP solution is specified by (an augmented) interpretation ind and direct-style semantic functions corresponding to those of Table 6.1-C {a}. We expect the solution to correspond to Kildall's MFP solution [Hec77,p.173] rather than the MFP solution of section 2.3 (Kam&Ullman's MFP solution [Hec77,p.178]). If this conjecture holds it is an argument in favour of basing our approach upon continuation style semantics.

In chapters 4 and 6 we have performed continuation removal because of difficulties in conducting proofs without performing continuation removal. An exception is the use of P&std in chapter 4 which is probably necessary to consider a semantic notion of availability.

The need to perform continuation removal does not seem to limit the applicability of our approach. This is because language constructs that makes it difficult to perform continuation removal (e.g. jumps) probably also leads to reflexive domains involving powersets, which cannot be handled by our approach.

The main reason for validating program transformations (in chapter 6) has been to remedy the undesired loose connection between \mathcal{P} ind (as well as \mathcal{P} sts and \mathcal{P} col) and \mathcal{P} std. But program transformations are also important in their own right. – We believe that to formalize the notion of correctness of data flow information one has to consider program transformations.

Presumably the approach is of wide applicability: A sufficient condition for two syntactic constructs to be replacable by one another is that they produce the same results in the computational context in which they are

[{]a} It is crucial that ind is augmented in the same way as sts is, e.g. that we continue to use ind-S rather than $\mathcal{O}(\text{ind-S})$. If $\mathcal{O}(\text{ind-S})$ is used it is possible to obtain a direct style semantics that specifies the MOP solution. This remark relates to [CoC79,Theorem 9.2.0.1] and to some extent to the functionality of Close in chapter 5.

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placed. Constant folding is but one of the many program transformations that can be validated in this way.

We expect it to be considerably more difficult to validate program transformations exploiting "available expressions" information. It is probably reasonably straight-forward to exploit "live variables" information.

In summary, the main accomplishments of this paper are:

- To weaken some of the assumptions usually stated in abstract interpretation. To present a different motivation for the usual assumptions.
- To express abstract interpretation in a denotational setting. To show that
 a denotational semantics specifying a data flow analysis can be obtained by
 defining a pair of semi-adjoined functions in a rather systematic way.
- To show how "available expressions" can be characterized semantically by means of abstract interpretation. Previous treatments have only <u>formulated</u> "available expressions".
- To show that the information specified by our approach essentially is the MOP solution.
- To formulate correctness conditions for program transformations. These assert that for two syntactic constructs to be replacable by one another it is sufficient that they produce the same results in the computational context in which they are placed.

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APPENDIX 1

The development of subsection 2.4.3 is not the only way to move the test LSLp to M. Assume that L is a power-set, e.g. L = P(INT) where INT is the integers, and that COMP(l) = {i| idl}. Further assume that uabs and conc are semi-adjoined between L and M and that conc is a strict n-morphism. Then a different way of testing LSLp avoiding the use of dabs is to test uabs(l) n uabs(COMP(lp)) = n in M [Jon80]. To see this:

uabs(l) n uabs(COMP (lp)) = 1 =>
(conc ouabs)(l) n (conc ouabs)(COMP(lp)) = 0 =>
l n (COMP(lp)) = 0 =>
l E lp

But sometimes this method is too coarse as may be seen from the following example: Let $M = \mathcal{O}\{a,b\}$ and $\operatorname{conc}\{a,b\} = \operatorname{INT}$, $\operatorname{conc}\{a\} = \{0\}$, $\operatorname{conc}\{b\} = \{i \mid i > 0\}$ and $\operatorname{conc}(\emptyset) = \emptyset$. Also uabs = $\lambda l' \cdot \Pi \{m \mid \operatorname{conc}(m) \ni l'\}$ so that uabs and conc are adjoined. When $l = lp = \{i \mid i > 0\}$ then uabs(l) n uabs(COMP(lp)) $\neq \emptyset$. In our approach we could have used dabs(lp) = $\{b\}$ so that uabs(l) $\subseteq \{a,b\}$ dabs(lp).

To investigate the connection between our method and that of <code>[Jon80]</code> we assume that uabs and conc are adjoined and that <code>M</code> (as well as <code>L</code>) is a powerset and that conc is strict. It is easy to see that the method of <code>[Jon80]</code> amounts to dabs(<code>l') = COMP(uabs(COMP(l')))</code> and testing uabs(<code>l) \subseteq dabs(<code>lp)</code>. This is a safe test because <code>dabs,conc</code> is semi-down-adjoined: Clearly dabs is isotone and dabs(<code>l') \supseteq m <code>description of mathematical mathematical</code></code></code>

But <dabs,conc> need not be quasi-down-adjoined as follows from the previous example, where dabs(lp) = COMP(uabs(COMP(lp))) =0 even though conc{b} Elp. If we also assume that conc(COMP(m)) = COMP(conc(m)) then we can show that <dabs, conc> is a pair of down-adjoined functions:

dabs(l') = <=> COMP(uabs(COMP(l'))) = <=> uabs(COMP(l')) = COMP(m) <=> COMP(l') = conc(COMP(m)) <=> COMP(l') = COMP(conc(m)) <=> l' = conc(m)

By Lemma 2.4.3-11 this definition of dabs is "adequate" under the stated assumptions: L and M power-sets, uabs and conc adjoined,

\forall m: conc(COMP(m)) = COMP(conc(m)) (which implies that conc is strict).

APPENDIX 2

PROOF OF 2.1.2-4:

- 1) (f complete-u-morphism) => (f continuous) \wedge (f u-morphism) \wedge (f(t)=t) is obvious from the definitions.
- 2) If l1 = l2 then {l1, l2} is a directed, finite, and non-empty set. If f is continuous or a u-morphism then l1 = l2 implies f(l1) = f(l1)uf(l2) = f(l1 ul2) = f(l2) so f is isotone.
- 3) Define f:T->T by $f(\bot) = f(false) = f(true) = \bot$ and $f(\tau) = \tau$. Then f is continuous but not a \bigcup -morphism.
- 4) Define $[0,1]=\{x \mid x \text{ real } x \geq 0 \land x \leq 1\}$ and $[0,1]=\{x \in [0,1] \mid x \neq 1\}$. Then $([0,1],\leq)$ is a complete lattice and [0,1] is a directed set. Define $T''=(\{no,yes\},\Xi)$ with $t1\Xi t2 <=> (t1\neq yes \lor t2\neq no)$ and f:[0,1]->T'' by f(x)=(x<1->no,yes). Then f is a u-morphism but not continuous: u{ $f(x) \mid x \in [0,1]$ } = $no \neq yes = f(1) = f(u)$ }.
- 5) Assume f is continuous, a p-morphism and fr=1. Let Let. Define

 L' = {UL' | L'' \subseteq \times \text{L'' finite} so L' is a directed set (using Lemma 2.1.1-7)

 with UL' = UL (using Lemma 2.1.1-7). Then

 f(UL) = f(UL')

 = U{f(l) | L \subseteq L'' finite}

 = U{f(UL'') | L'' \subseteq L'' finite \text{L'' finite} \text{L''' finite} \text{L'''' finite} \text{L''' finite} \text{L'''' finite} \text{L''''' finite} \text{L''''' finite} \text{L'''' finite} \text{L'''' fini

PROOF OF 2.1.3-2:

<code>LSan73.p.27-28]</code> proves (for n=2) that L1 λ ... λ Ln is a complete lattice and that \square is as shown. Dual computations give the form of Π . To see that $\forall i$ is continuous: Let \underline{L} L1 λ ... λ Ln be directed. Then $(\square_{\underline{L}})$ $\forall i$ = $\langle ..., \square$ { \underline{L} ! $\forall i$ | \underline{L} ! \in \underline{L} }... $\forall i$ | \underline{L} ! \in \underline{L} }... \in \underline{L}

Many of the following Lemmas are (like this one) proved in the literature (e.g. [Sto77], [San73], [MiS76]). The proofs therefore are omitted.

PROOF OF 2.1.3-13:

To see that L-t>M, L-i>M and L-c>M are partially ordered sets is easy (for anti-symmetry use the axiom of extensionality [Sto77,p.56]). It is straight-forward to show that L-t>M and L-i>M are complete lattices with U and Π as shown. Also one can show that L-c>M is a complete lattice with U as shown (using Lemma 2.1.1-7 twice) and $\Pi = U\{g \mid g \in L-c>M \land \forall f \mid e f : f \mid g\}$.

PROOF OF 2.2-4:

The proof is by structural induction [Sto77]. Define the predicates:

P-Dcl:Dcl->B by P-Dcl(dcl) = 1 intEdcl is well-defined (and in the clause for 1 intEdcl no function is supplied with an argument of the wrong type) and 2 intEdcl is of functionality as shown.

P-Exp, P-Cmd and P-Pro are defined similarly.

Clearly the predicates are well-defined, since they are not defined recursively in terms of each other [Sto77]. We could be more precise about "argument of the wrong type" but there is little point in doing so.

Structural Induction on Dcl:

The case 'DCL ide := bas': First note that (the last) attach is supplied with arguments (<occ,"dcl)"> and c) of the right types and that attach<occ,"dcl)">;c is well-defined. Then note that assign is supplied with arguments of the right types and that assignFideI; attach<occ, "dcl)">;c is well-defined. Then note that push is supplied with arguments of the right types and that pushFbasI; assignFideI; attach<occ, "dcl)">;c is well-defined. Finally note that (the first) attach is supplied with arguments of the right types and that DintFDCL ide:=basI occ c is well-defined. Furthermore no function in the clause for DintFDCL ide:=basI occ c is supplied with an argument of the wrong type. Also Lemma 2.1.2-8 yields DintFDCL ide:=basI & Occ -c> C -c> C.

The case 'dcl1;dcl2' is similar.

Structural Induction on Exp: As for Dcl above.

Structural Induction on Cmd: The case 'IF exp THEN cmd1 ELSE cmd2 FI'. Let g1,g2 \in C-c>C and cond \in CXC-c>C. Then h= λ c. cond(g1;c, g2;c) is easily seen to be continuous. From this P-Cmd(IF exp THEN cmd1 ELSE cmd2 FI) follows. The case 'WHILE exp DO cmd OD': Let g \in C-c>C and cond \in CXC-c>C and h[n] = λ c.(λ c'. cond(g;c',c))"1. Then one can show \forall n \geq 0: h[n] \in C-c>C so that λ c.FIX(λ c'.cond(g;c',c)) = λ c.U \in h[n];c |n \geq 0} = U \in h[n] | n \geq 0} \in C-c>C because of Lemma 2.1.3-13(3). From this follows that P-Cmd(WHILE exp DO cmd OD).

The remaining cases are straight-forward.

<u>Structural Induction on Pro</u>: This is by hypothesis and requirements upon setup.

PROOF OF 2.2-5:

- a) As there are no reflexive domains in Tables 2.2-B and 2.2-D the domains (including C, I, A and S of Table 2.2-D) obviously exist and are complete lattices.
- b) Obviously wrong &C and finish &C.
- c&d) We only prove assign € Ide -t> C -c> C as the remaining proofs are more or less similar to this proof.
 - 1) We show Vassign € Ide -t> Sta -c> T. It is convenient to write Vassign Fide Ista = (#sta ¥4) << 1 -> false, true. By lemmas of section 2.1 and our assumption that << is continuous it easily follows that Vassign Fide I € Sta-c>T.

```
2) We can show Bassign \epsilon Ide -t> Sta -c> Sta similarly to above.
    3) We now show assign € Ide -t> C -c> C.
      Obviously assign ← Ide -t> C -t> Sta -t> A. It is easy to show
       assign € Ide -t> C -c> Sta -t> A and using "1)" and "2)" and results like
      2.1.2-8 it is straight-forward to show assign € Ide -t> C -c> Sta -c> A.
PROOF OF 2.4.2-1:
 Let <-> be => if "semi-adjoined" and <=> if "adjoined". Then
 ¥11€L1 ¥1[n+1]€L[n+1]:
      uabs[n](...(uabs1(l1)) [[n+1]
    <-> l1 £ conc1(...(conc[n](l[n+1])))
 In the case of "adjoined" the result obviously follows (by Definition
 2.4.1-6). In the case of "semi-adjoined" the result follows by Observation
 2.4.1-5 because uabs[n] ... ouabs1 and conc1 ... oconc[n] clearly are isotone.
PROOF OF 2.4.2-3:
 \forall L \in \mathcal{P}(L1X...XLn) \forall m \in \mathcal{P}(L1)X...X\mathcal{P}(Ln):
 uabsX(<u>l</u>) <u>E</u> m <=> ∀i∈{1,...,n}: {l\vi | | ∈ <u>l</u>} <u>S</u>m\vi
                 <=> <u>L</u> <u>E</u> {<l1,...,ln> |∀i∈{1,...,n}: li∈m∀i}
                 <=> <u>L</u> <u>E</u> concX(m)
                                                                                                   PROOF OF 2.4.2-9:
 We have \forall \underline{\mathsf{L}} \in \mathcal{P}(\mathsf{L}1 + \ldots + \mathsf{L}n) \forall \mathsf{m} \in \mathcal{P}(\mathsf{L}1) + \ldots + \mathcal{P}(\mathsf{L}n):
 1) If l = \emptyset:
     uabs+(\underline{l}) \subseteq m \iff 1 \subseteq m \iff true \iff \emptyset \subseteq conc+(m) \iff l \subseteq conc+(m)
 2) If \forall l \in \underline{l} \exists li \in Li: l = li inL1 + ... + Ln and <math>\underline{l} \neq \emptyset then:
     uabs+(\underline{L}) \underline{c} m <=> { li | li inL1+...+Ln \underline{c} \underline{L} } in\mathcal{P}(L1)+...+\mathcal{P}(Ln) \underline{c} m
                      <=> (m=τ) ν (mψ1=i Λ {li | li inL1+...+Ln € <u>L</u>} ⊆ mψ2)
                                                  (this was by Definition 2.1.3-4)
                      if m= \tau then <=> true <=> \underline{\underline{l}} \subseteq L1+...+Ln <=> \underline{\underline{l}} \subseteq conc+(m)
     if m=1 then \langle = \rangle false\langle = \rangle \underline{L} \subseteq \emptyset \langle = \rangle \underline{L} \subseteq conc+(m) (as \underline{L} \neq \emptyset)
     if m = \underline{l}j in P(\underline{l}1) + \dots + P(\underline{l}n) where \underline{l}j \subseteq \underline{l}j then
                      <=> j=i \ Leconc+(m) <=> Leconc+(m) (as L#0)
 3) Otherwise:
     uabs+(<u>l</u>) ξ m <=> τ ξ m
     if m= r then <=> true <=> Lsconc+(m)
     if m=1 then <=> false<=> L5conc+(m)
                                                       (as L≠0)
     if m = lj in (L1) + ... + P(Ln) then \langle - \rangle false \langle - \rangle \underline{l} \subseteq conc + (m)
         since NON(∃i∀l∈L∃lieLi: l= li inL1+...+Ln)
                \forall l \in conc+(m) \exists lj \in Lj : l = lj : inL1+...+Ln
                                                                                                   PROOF OF 2.4.2-11:
Let <-> be <=> if <uabs, conc> is a pair of adjoined functions and => if
 <uabs,conc> is a pair of semi-adjoined functions. Then for
 l \in L1+...+Li+...+Ln and m \in L1+...+Mi+...+Ln:
 If L=1:
     (Si uabs L) = m <=> 1 = m <=> 1 = (Si conc m) <=> L = (Si conc m)
 If l = lj inL1+...+Ln and j \neq i:
     (Si uabs L) 5 m
     <=> lj inL1+...+Ni+...+Ln 5 m
     <=> (m=7) v (∃lj': m = lj' inL1+...+Mi+...+Ln ∧ lj⊆lj')
```

[Appendix 2]

```
<=> L \( \text{Si conc m} \( \nabla \) \( \frac{1}{3} \) \( \text{I} \) \( \text{Si conc m} \) \( \text{Si conc m} \)
           <=> L E (Si conc m)
  If l = li in L1+...+Ln:
            (Si uabs l) 5 m <=> ( uabs(li) inL1+...+Mi+...+Ln ) 5 m
                                                    <=> (m=τ) v (∃mi: m = mi inL1+...+Mi+...+Ln \uabs(li)Emi)
                                                    <-> (m=r) v (∃mi: m = mi inL1+...+Mi+...+Ln ∧ Li Econc(mi)
                                                    <=> (l E (Si conc m)) < (3mi: m = mi inL1+...+Mi+...+Ln A
                                                                                                                                  L = (Si conc m))
                                                    <=> L = (Si conc m)
  If L=r:
            (Si uabs L) 5 m <=> r5 m <=> r5 (Si conc m) <=> L5 (Si conc m)
  In the case of "adjoined" the result obviously follows (by 2.4.1-6). In the
  case of "semi-adjoined" the result follows by 2.4.1-5 because (Si uabs) and
  (Si conc) clearly are isotone.
                                                                                                                                                                                                                          PROOF OF 2.4.3-3:
  Suppose <uabs, conc> is a pair of adjoined functions between L and M.
  Clearly uabs = \lambda \ln m = \lambda \ln m
  Now uabs(UL) = \Pi{m| VL=conc(m)} = \Pi{m| \foralllel: l=conc(m))}
     = \Pi\{m \mid \forall l \in \underline{l}: uabs(l) \in m\} = \Pi\{m \mid \underline{l} \{uabs(l) \mid l \in \underline{l}\} \in m\}
     = U{uabs(l) | l∈l}
  so that uabs is a complete-_-morphism and hence isotone (2.1.2-4).
           Similarly, conc=\lambda m. I\{l \mid uabs(l) \le m\} is a complete-n-morphism. It is easy
  to see that conc is isotone.
           So <uabs,conc> is pair of semi-adjoined functions. To see that it is a
  pair of quasi-adjoined functions: conc • uabs = \lambda l \cdot \Pi conc(\{m\} L \subseteq conc(m)\}) =
  AL. Π{conc(m)| L=conc(m)}.
                                                                                                                                                                                                                          PROOF OF 2.4.3-10:
  Since (semi-,quasi-) down-adjoined is the dual concept of (semi-,quasi-)
  adjoined the proof is dual to that of 2.4.3-3.
                                                                                                                                                                                                                          PROOF OF 2.4.3-11:
  1) We show: (\exists m, mp: m \neq n \land l \neq conc(m) \land conc(mp) \neq lp) <=> uabs(l) \neq dabs(lp)
        <=: Obvious with m = uabs(l) \( \text{mp} = \text{dabs(lp)} \)
        => : Assume m=mp \( L=\) t=conc(m) \( \sigma\) conc(mp) \( \sigma\) Since uabs and conc are
              quasi-adjoined we get
                       conc(uabs(l)) = \Pi\{conc(m') | conc(m') = l\} \in conc(m)
              and from dabs and conc quasi-down-adjoined we get
                       conc(dabs(lp)) = U{conc(m') | conc(m') \in lp} = conc(mp)
                       l \leq conc(uabs(l)) \leq conc(m) \leq conc(mp) \leq conc(dabs(lp)) \leq lp
              If uabs and conc are adjoined then L ⊆ conc(dabs(lp)) gives
              uabs(l) 5 dabs(lp). If dabs and conc are down-adjoined then
              conc(uabs(l)) = lp gives uabs(l) = dabs(lp).
  2) We show conc(uabs(l)) \( \) conc(dabs(lp)) \( <=> \) uabs(l) \( \) dabs(lp).
        <=: Trivial
        => : If uabs and conc are adjoined: conc(uabs(l)) = conc(dabs(lp)) =>
              l = conc(dabs(lp)) => uabs(l) = dabs(lp). Similarly if dabs and conc are
```

down-adjoined: conc(uabs(l)) = conc(dabs(lp)) => conc(uabs(l)) = lp =>

uabs(l) = dabs(lp).

PROOF OF 2.4.3-12:

We know that conc • uabs is isotone and extensive and it is easy to show that conc • uabs is idempotent (in fact conc • uabs • conc = conc); so conc • uabs is an upper closure operator. Obviously $\{conc(uabs(l)) | l \in L\} \subseteq \{conc(m) | m \in M\}$. Conversely, let $conc(m) \in \{conc(m') | m' \in M\}$. From conc • uabs • conc = conc follows $conc(m) = conc(uabs(conc(m))) \in \{conc(uabs(l)) | l \in L\}$.

To show that the upper closure operator is unique, we let uco1 and uco2 be two upper closure operators with $\{uco1(l) | l\in L\} = \{uco2(l) | l\in L\} = \{conc(m) | m\in \mathbb{N}\} \}$. Then for any let: $l\subseteq uco1(l) = uco2(l) \subseteq uco2(uco1(l)) = uco1(l)$ since uco2 is idempotent and uco1(l) $\in \{uco2(l') | l'\in L\}$ so that uco2(l) $\subseteq uco1(l) \}$. Conversely uco2(l) $\supseteq uco1(l) \}$. This shows uco1 = uco2, i.e. uniqueness.

PROOF OF 2.4.3-13:

APPENDIX 3

PROOF OF 3.1-2:

- 1) Since there are no reflexive domains the domains (including S, I, A and C) obviously exist and are complete lattices.
- 2) Obviously, wrong ϵ C and finish ϵ C.
- 3) We only prove g \in Par -t> C -c> C for primitive functions as the proofs are tedious and the cases of setup, attach, and cond more or less are like this proof.
 - a) Dg \in Par -t> $\mathcal{P}(Sta)$ -c> $\mathcal{P}(Sta)$ Clearly Dg(par) is well-defined. It is a complete- \mathfrak{u} -morphism because for any $s \in \mathcal{P}(S) = \mathcal{P}(\mathcal{P}(Sta))$: Dg(par)(\mathfrak{U}_S)

= $\{ std-Bg(par)(sta) \mid std-Vg(par)(sta) = true \land sta \epsilon(Us) \}$

= {std-Bg(par)(sta) | std-Vg(par)(sta)=true $\wedge \exists \underline{sta} \in \underline{s}$: sta $\underline{\epsilon} \underline{sta}$ } (this was by \sqcup being \cup)

= \sqcup {{std-Bg(par)(sta) | std-Vg(par)(sta)=true \(sta \) esta \(\) sta \(\) being \(\) being \(\) \(\)

- = $U\{Dg(par)(sta) \mid sta \in s\}$
- b) Clearly g(par) is well-defined. If c≤C then g(par)(⊔c) = (∪c)∘(Dg(par))

 = U{c∘Dg(par) | c∈c}

PROOF OF 3.1-6:

To prove the theorem we need the predicates

P-S: $\mathcal{P}(Sta)$ ->B where P-S(\underline{sta}) = $\forall sta \in \underline{sta}$:topfree[Sta](sta)

P-C:(col-CXsts-C)->B where P-C(col-c,sts-c) = $\forall \underline{sta}$:

 $[P-S(sta)] \Rightarrow sts-c(sta) = U(col-c(sta)) | sta \in sta]$

The proof is by structural induction (case 5 below), but we first show some auxiliary results:

- For any primitive function g ∈ Par -t> C -c> C we show that if P-C(col-c,sts-c) then P-C(col-g(par)(col-c), sts-g(par)(sts-c)).
 - i) We first show topfree[Sta](sta) => std-Vg(par)(sta)≠τ. We only consider g=assign as the remaining cases are similar. Assume topfree[Sta]<env,inp,out,wit>. Then #wit≠τ by property of # and (#wit<<1)≠τ by property of <<. As false≠τ and true≠τ and ⊥ ≠ τ the result follows.</p>
 - ii) We then show P-S(\underline{sta}) => P-S(\underline{sta}) => P-S(\underline{sta}). It suffices to show topfree[Sta](\underline{sta}) \wedge std-Vg(par)(\underline{sta})=true =>

topfree[Sta](std-Bg(par)(sta)). Let $sta = \langle env, inp, out, wit \rangle$ and assume std-Vg(par)(sta) = true as well as topfree[Sta](sta).

- a) If g = assign: Clearly topfree[Wit](<val>§wit) => topfree[Wit](wit).
 Also topfree[Val](val) \(\) topfree[Env](env) \(\) ide\(\{\pm\)_T} \) yield
 topfree[Env](env[Val/ide]). To see this assume topfree[Ide\(\Pm\)](ide\(\)).
 Then env[Val/ide]ide\(\{\pm\)_Val,envFide\(\Pm\)_T because Assumption 2.2-3 and ==
 continuous implies that (ide==ide\(\))\(\{\pm\)_True,false\(\).
 This shows
 topfree[Sta](std-BassignFide\(\Pm\)_Stalled\(\)
- b) The cases content, read and write are similar to the above case (but simpler). The cases apply and push use Assumption 3.1-4.
- iii) Finally we show the result for primitive functions. Assume P-S(\underline{sta}) and P-C(col-c, sts-c). Then

sts-g(par)(sts-c)(sta)

- = $sts-c(sts-Dg(par)(\underline{sta}))$ (and by "ii" and P-C(col-c, sts-c):)
- = $U\{(col-c)(col-Bg(par)(sta)) \mid staesta \land std-Vg(par)(sta)=true\}$
- = $U\{col-g(par)(col-c)(sta) \mid staesta \land std-Vg(par)(sta)=true\}$
- = $U\{col-g(par)(col-c)(sta) \mid sta \in \underline{sta}\}$ (which was by "i" and $lu_{\perp}=l$)
- 2) Similarly to "1)" we can prove P-C(col-c1,sts-c1) P-C(col-c2,sts-c2) =>
 P-C(col-cond(col-c1,col-c2), sts-cond(sts-c1,sts-c2)). In step "i)" we
 show that if topfree[Sta](sta) then
 std-Vcond(sta)=true => col-Scond(sta) + \tau and col-Vcond(sta) + \tau
- 3) Similarly to "1)" we can prove P-C(col-c,sts-c) =>
 P-C(col-attach(pla)(col-c), sts-attach(pla)(sts-c))
- 4) Similarly to "1)" we can prove

 [P-C(col-c,sts-c) ∧ ∀inp∈inp: topfree[Inp]inp] =>
 sts-setup(sts-c)inp = U(col-setup(col-c)(inp) |inp∈inp).
- 5) We now perform the structural induction. We define the predicates P-Cmd:Cmd->B by P-Cmd(cmd)=

Structural Induction on Dcl: This is straight-forward using "1)" to "4)".

Structural Induction on Exp: As above.

Structural Induction on Cmd: Most cases are as above.

Case WHILE exp D0 cmd OD. Assume P-C(col-c,sts-c). Let $g=\lambda c'$. GrexpIocc§<1>; cond(GremdIocc§<2>; c', attach<occ,"cmd)">; c). Then by "1)" to "4)" and induction hypotheses it easily follows that P-C(col-c',sts-c') => P-C(col-g(col-c'), sts-g(sts-c')). Since P-C(1,1) a proof by induction shows $\forall n \geq 0$: P-C((col-g)"1, (sts-g)"1).

To deduce P-C(FIX(col-g), FIX(sts-g)) we assume $P-S(\underline{sta})$. Then

FIX(sts-g)<u>sta</u>

= $U\{(sts-g)^n \perp \underline{sta} | n \ge 0\}$

- = $u\{U\{(col-g)^n\}$ sta $sta \in sta\}$ $n\geq 0\}$ (and by Lemma 2.1.1-7 twice:)
- = \sqcup { \sqcup { $(col-g)^n_\perp$ sta $\lfloor n \geq 0$ } \rfloor staesta}
- = U{ FIX(col-g) sta |staesta}

This shows P-C(FIX(col-g), FIX(sts-g)) from which

P-Cmd(WHILE exp DO cmd OD) easily follows.

<u>Structural Induction on Pro</u>: Surely P-C(col-finish, sts-finish) so that the above inductions give P-C(AcolEdclI<1>; CcolEcmdI<2>; col-finish, AstsEdclI<1>; CstsEcmdI<2>; sts-finish). Then the result follows by "4)".

PROOF OF 3.1-10:

The proof is by structural induction. We define the following predicates:

P-C:(apr1-CXapr2-C)->B by P-C(apr1-c,apr2-c) =

(apr1-c oconc 5 (R conc) oapr2-c)

P-Cmd:Cmd->B by P-Cmd(cmd) = P-C(apr1-c,apr2-c) =>

P-C(apr1FcmdIocc apr1-c, apr2FcmdIocc apr2-c)

and P-Exp:Exp->B and P-Dcl:Dcl->B similarly.

<u>Structural induction on Dcl</u>: The proof is straight-forward using apr1 E<uabs,conc> apr2.

Structural induction on Exp: As above.

Structural Induction on Cmd: The cases mostly are as above. Consider the case WHILE exp DO cmd OD. Let g[c] = $\lambda c'$. CFexpIocc§<1>; cond(CFcmdIocc§<2>; c', attach<occ,"cmd)">; c). Assume P-C(apr1-c,apr2-c). Then P-C(apr1-c',apr2-c') => P-C(apr1-g[apr1-c] apr1-c', apr2-g[apr2-c] apr2-c'). Since P-C(1,1) a proof by induction shows $\forall n \geq 0$: P-C((apr1-g[apr1-c])"1, (apr2-g[apr2-c])"1). To show P-C(FIX(apr1-g[apr1-c]), FIX(apr2-g[apr2-c])) we calculate: FIX(apr1-g[apr1-c]).conc

= $U\{(apr1-g[apr1-c])^n \perp \circ conc \mid n \geq o\}$

 $\subseteq U\{(R \text{ conc}) \circ (apr2-g[apr2-c])^n \perp [n\geq 0\}$

E (R conc) • U{(apr2-g[apr2-c]) * 1 | n≥0}

(which was by isotony of R conc)

= (R conc) • FIX(apr2-g[apr2-c]).

PROOF OF 3.1-12:

We must show the conditions of Definition 3.1-9: Let P-C(sts-c,ind-c) = $(sts-c \circ conc \in (R \ conc) \circ ind-c)$.

- a) P-C(sts-wrong, ind-wrong) and P-C(sts-finish, ind-finish) are immediate.
- b) Assume P-C(sts-c1,ind-c1) and P-C(sts-c2,ind-c2). Then sts-cond(sts-c1,sts-c2) oconc

5 \lambdas.sts-c1(conc(uabs(sts-Dt-cond(conc(s))))) \[
sts-c2(conc(uabs(sts-Df-cond(conc(s)))))\]

(which was because sts-c1 and sts-c2 isotone and concouabs extensive)

 $\subseteq \lambda s.(R conc)(ind-c1(ind-Dt-cond(s)))$

(R conc)(ind-c2(ind-Df-cond(s)))

(which was by assumptions)

5 (R conc) • (ind-cond(ind-c1,ind-c2))
 (which was by R conc isotone)

This shows P-C(sts-cond(sts-c1, sts-c2), ind-cond(ind-c1, ind-c2)).

c&d&e) The proof goes essentially as in case "b)" above. In the proof of "c)" we use the fact $\forall s \in S$: $\bot [conc(s)/pla] = (R conc)(\bot [s/pla])$.

PROOF OF 3.1-13:

Define the predicates

P:(sts-CXind-C)->B by P(sts-c,ind-c)=[sts-c • conc = (R conc) • ind-c] Q:(ind-CXapr-C)->B by Q(ind-c,apr-c)=[ind-c \ apr-c]

- 1) Assume ind<uabs,conc> $\leq \langle \lambda_s, \lambda_s \rangle$ apr and show sts $\leq \langle \lambda_s, \lambda_s \rangle$ apr by proving the conditions of Definition 3.1-9.
 - a) Clearly P(sts-wrong, apr-wrong) and P(sts-finish, apr-finish).
 - b) Assume P(sts-c1,apr-c1) and P(sts-c2,apr-c2). Then by Lemma 3.1-12 sts-cond(sts-c1, sts-c2) conc = (R conc) (ind-cond(apr-c1, apr-c2)) But Q(apr-c1,apr-c1) A Q(apr-c2,apr-c2) so ind 5s.3s.s> apr implies ind-cond(apr-c1,apr-c2) = apr-cond(apr-c1,apr-c2) Also (R conc) is isotone. This implies sts-cond(sts-c1,sts-c2)oconc 5 (R conc)o(apr-cond(apr-c1,apr-c2)) From this P(sts-cond(sts-c1, sts-c2), apr-cond(apr-c1, apr-c2) follows.

c&d&e) The proof goes as in "b)" above.

- 2) Assume sts = <uabs,conc> apr and show ind<uabs,conc> = <As.s, As.s> apr by proving the conditions of Definition 3.1-9.
 - a) Obviously Q(ind-wrong, apr-wrong) and Q(ind-finish, apr-finish).
 - b) Assume Q(ind-c1,apr-c1) and Q(ind-c2,apr-c2). Since apr-cond is isotone in both parameters we only need to show

ind-cond(ind-c1, ind-c2) = apr-cond(ind-c1, ind-c2)

to be able to deduce Q(ind-cond(ind-c1,ind-c2), apr-cond(apr-c1,apr-c2)).

Define $sts-c1 = (R conc) \circ ind-c1 \circ uabs$

 $sts-c2 = (R conc) \circ ind-c2 \circ uabs$

Then P(sts-c1,ind-c1) and P(sts-c2,ind-c2) because uabsoconc is the identity (reductive is enough). Then (by hypothesis)

P(sts-cond(sts-c1,sts-c2), apr-cond(ind-c1,ind-c2))

i.e.

(sts-c1 ∘ sts-Dt-cond ∘ conc) ⊔ (sts-c2 ∘ sts-Df-cond ∘ conc) €

(R conc) • apr-cond(ind-c1, ind-c2)

and because (R uabs) is isotone we get:

[(R uabs) o(R conc) oind-c1 ouabs osts-Dt-condoconc] u [...] 5

(R uabs) • (R conc) • apr-cond(ind-c1, ind-c2)

When <uabs,conc> is exact this is equivalent to

ind-c1oind-Dt-cond ind-c2oind-Df-cond 5 apr-cond(ind-c1,ind-c2) as was to be shown.

c&d&e) The proof goes as in "b)" above.

PROOF OF 3.1-14:

That <concouabs, \(\lambda \sta \cdot \sta \) is a pair of semi-adjoined functions is immediate. Define ind1=ind<conc• uabs, $\lambda \underline{sta}.\underline{sta}$ and ind2=ind<uabs, conc>. We show the result by a structural induction that uses the predicates: P-C:(ind1-cXind2-c)->B where P-C(ind1-c,ind2-c) =

```
[ (R uabs) oind1-coconcouabs = ind2-couabs ]
P-Cmd:Cmd->B where P-Cmd(cmd) = [ P-C(ind1-c.ind2-c) =>
   P-C(Gind1 EcmdIocc ind1-c, Gind2 EcmdIocc ind2-c)
and P-Dcl and P-Exp are defined similarly.
   Before we approach the structural induction ("6" below) it is convenient
to show some properties of primitive functions, auxiliary functions and
constants.
1) Since uabs and conc are adjoined we have uabs(\perp) = \perp so
  P-C(ind1-wrong,ind2-wrong) and P-C(ind1-finish,ind2-finish).
2) We show P-C(ind1-c1, ind2-c1) \wedge P-C(ind1-c2, ind2-c2)
  => P-C(ind1-cond(ind1-c1,ind1-c2), ind2-cond(ind2-c1,ind2-c2))
  Assume P-C(ind1-c1,ind2-c1) and P-C(ind1-c2,ind2-c2). Then
  (R uabs) o ind1-cond(ind1-c1, ind1-c2) o concouabs
  = (R uabs) o ind1-c1 o conco uabs o sts-Dt-cond o conco uabs u
    (R uabs) ind1-c2 concouabs osts-Df-condoconcouabs
       (which was by uabs a (complete-)u-morphism)
  = [ind2-c1oind2-Dt-cond \( \text{u} \) ind2-c2oind2-Df-cond]ouabs
       (which was by assumtions)
  = ind2-cond(ind2-c1,ind2-c2) o uabs
  Hence P-C(ind1-cond(ind1-c1,ind1-c2), ind2-cond(ind2-c1,ind2-c2)).
3) We show P-C(ind1-c, ind2-c) =>
     P-C(ind1-attach(pla)(ind1-c), ind2-attach(pla)(ind2-c))
  Assume P-C(ind1-c, ind2-c). Then
  (R uabs) • (ind1-attach(pla) • ind1-c) • conc•uabs
  = \lambda s_*(R \text{ uabs})(\text{ind1-c(conc(uabs(s)))}) \sqcup (R \text{ uabs})(\bot[\text{conc(uabs(s))/pla]})
       (which was because uabs a (complete-)_-morphism)
  = λs. ind2-c(uabs(s)) μ μ[(uabs conc ouabs)(s)/pla]
        (which was by assumption P-C(..., and uabs(\tau)=\tau and uabs(\bot)=\bot)
  = (ind2-attach(pla)(ind2-c)) ouabs
       (which was by uabs concouabs = uabs which is
        a property of a pair <uabs,conc> of adjoined functions)
  Hence P-C(ind1-attach(pla)(ind1-c), ind2-attach(pla)(ind2-c)).
4) The proof of P-C(ind1-c,ind2-c) => ∀inp:
  (R uabs)(ind1-setup(ind1-c)inp) = ind2-setup(ind2-c)inp is easy.
5) The proof of P-C(ind1-c,ind2-c) =>
  P-C(ind1-g(par)ind1-c, ind2-g(par)ind2-c) for a primitive function g goes
  as case "2)".
6) The structural induction is mostly straight-forward using the results of
  "1)" to "5)". We consider the case WHILE exp DO cmd OD. Define
  g[c] = \lambdac'.&FexpIocc§<1>; cond(&FcmdIocc§<2>;c', attach<occ,"cmd)">;c)
  Then by hypotheses we may assume
  P-C(ind1-c,ind2-c) \( P-C(ind1-c',ind2-c') =>
    P-C(ind1-gEind1-c]ind1-c', ind2-gEind2-c]ind2-c').
  Assume P-C(ind1-c,ind2-c). We now show
    P-C(FIX(ind1-g[ind1-c]),FIX(ind2-g[ind2-c]))
  Since P-C(1, 1) a proof by induction yields \forall n > 0:
```

P-C([ind1-g[ind1-c]]",[ind2-g[ind2-c]]"). Furthermore,

(R uabs) \circ (\sqcup {(ind1-g[ind1-c])" \perp |n \geq 0}) \circ conc \circ uabs = \sqcup { (R uabs) \circ (Eind1-g[ind1-c]]" \perp) \circ conc \circ uabs |n \geq 0}

This shows P-C(FIX(ind1-g[ind1-c]), FIX(ind2-g[ind2-c])). From this P-Cmd(WHILE exp DO cmd OD) easily follows.

PROOF OF 3.1-15:

Abbreviate uco1=conc1•uabs1, uco2=conc2•uabs2, id= λsta . ind1=ind<uco1,id> and ind2=ind<uco2,id>.

We omit the proof of ind1 5<id,id> ind2, since it is straight-forward.

From this result and Theorem 3.1-10 we have

Vpro: Ving: Pind1 Eproling ⊆ Pind2 Eproling

and by isotony of uco1 and uco1 5 uco2

 $\forall pro: \forall \underline{inp}: (R uco1)(\mathcal{P}ind1\mathbb{E}pro\mathbb{I}\underline{inp}) \subseteq (R uco2)(\mathcal{P}ind2\mathbb{E}pro\mathbb{I}\underline{inp})$ By Lemma 3.1-14:

PROOF OF 3.1-16:

If $\langle uabs, conc \rangle$ is a pair of adjoined functions then concouabs is an upper closure operator by Lemma 2.4.3-12.

Conversely, let $uco:\mathcal{P}(Sta) \to \mathcal{P}(Sta)$ be an upper closure operator. Let $S = \{uco(\underline{sta}) \mid \underline{sta} \in \mathcal{P}(Sta)\}$ and $id:S \to S$ be $\lambda s.s.$ Then $\langle uco, id \rangle$ is a pair of adjoined functions, as can easily be shown. Furthermore $uco(\tau) = r$ because uco is extensive. Below we show that S is a complete lattice.

Let \subseteq , \sqcup and \sqcap be those of P(Sta). Clearly (S, \sqsubseteq) is a partially ordered set. We show $\forall \underline{s} \in S$. This follows from

 $\Pi_{\underline{S}} \in uco(\underline{n}_{\underline{S}}) \in \Pi\{uco(\underline{s}) \mid \underline{s} \in \underline{s}\} = \underline{n}_{\underline{S}}$

(where we have used the properties of an upper closure operator) so that $\Pi_{\underline{S}} = uco(\Pi_{\underline{S}}) \in S$. This implies that for arbitrary $\underline{S} \in S$

₩s€S: Π<u>s</u> 3 s <=> <u>s</u> 3 s

(because Π is meet of $\mathcal{P}(\text{Sta})$ and $S\subseteq\mathcal{P}(\text{Sta})$) so that Π is also meet of S (and exists).

 $\underline{s} \subseteq s1 \Rightarrow \{s2 \mid s2 \nmid \underline{s}\} \Rightarrow s1 \Rightarrow s0 \subseteq s1$ and

s0 ≤ s1 => \forall s3 \in \forall s4 \s42 s3 \forall \in \s0 \in \s1 => \s \in \s1

PROOF OF 3.1-17:

The part uco15uco2 => ind < uco1, id > 5 < id, id > ind < uco2, id > is to be proven as in the proof of Lemma 3.1-15 (where we omitted the proof).

For the converse implication abbreviate ind1 = ind<uco1,id> and ind2 = ind<uco2,id>. Define $c \in P(Sta)-i>Pla-c>P(Sta)$ by $c=\lambda_{\underline{S}\underline{t}\underline{a}}=\lambda_{\underline{P}}la_{\underline{s}\underline{t}\underline{a}}$. Note $\forall_{\underline{S}\underline{t}\underline{a}}=\lambda_{\underline{P}}la_{\underline{s}\underline{t}\underline{a}}$. Note $\forall_{\underline{S}\underline{t}\underline{a}}=\lambda_{\underline{P}}la_{\underline{s}\underline{t}\underline{a}}$. Note $\forall_{\underline{S}\underline{t}\underline{a}}=\lambda_{\underline{P}}la_{\underline{s}\underline{t}\underline{a}}$. So by ind1 \leq id, id> ind2 we get $\forall_{\underline{S}\underline{t}\underline{a}}$: uco1($\underline{s}\underline{t}\underline{a}$) \subseteq uco2($\underline{s}\underline{t}\underline{a}$), i.e uco1 \subseteq uco2.

APPENDIX 4

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PROOF OF 4.1-6:
 The proof is by structural induction. Define the predicates:
 P-S:\theta(Sta*)->B by P-S(s)=\forall sta*\epsilon: topfree[Sta*](sta*)\(\pi\) \pu sta*\epsilon[\lambda_1,\tau_0\)
 P-C:(his-col-CXhis-sts-C)->B by P-C(his-col-c,his-sts-c) =
     \forall s \in \mathcal{P}(Sta^*): P-S(s) \Rightarrow his-sts-c(s) = U\{his-col-c(sta^*) \mid sta^* \in s\}
 P-Cmd:Cmd->B by P-Cmd(cmd) = [ P-C(his-col-c,his-sts-c) =>
     P-C(Chis-colEcmdIocc his-col-c, Chis-stsEcmdI occ his-sts-c)
 and P-Exp and P-Dcl similarly.
     It is easy to modify the proof of Theorem 3.1-6 to hold in this setting;
 note that topfree[Sta*](sta*) ~ #sta**\(\epsilon_{\pi,\tau_0}\) => topfree[Sta](sta*.last) []
PROOF OF 4.1-9:
 To show that uabs and conc are adjoined is by straight-forward calculations.
 To show exactness: We know uabs(conc(\underline{sta})) \leq \underline{sta}. Let \underline{sta} \in \underline{sta}. Then
 \langle sta \rangle \in conc(\underline{sta}) so \{\langle sta \rangle\} \subseteq conc(\underline{sta}) so
 sta \in uabs(\{\langle sta \rangle\}) \subseteq uabs(conc(\underline{sta})), i.e. uabs(conc(\underline{sta})) \supseteq \underline{sta}.
                                                                                                PROOF OF 4.1-10:
 Define P-C:(sts-CXhis-ind-C)->B by P-C(sts-c,his-ind-c) = (sts-c=his-ind-c).
 a) P-C(sts-wrong, his-ind-wrong) and P-C(sts-finish, his-ind-finish)
 b) Suppose P-C(sts-c1, his-ind-c1) and P-C(sts-c2, his-ind-c2). Then
   his-ind-cond(his-ind-c1, his-ind-c2)
    = sts-c1° uabs ohis-sts-Dt-cond oconc u sts-c2° uabs ohis-sts-Df-cond oconc
   Now uabs(his-sts-Dt-cond(conc(sta)))
   = uabs {his-std-Bcond(sta*) | sta*econc(sta) \ his-std-Vcond(sta*)=true
                                         ^ his-std-Scond(sta*)=true}
   = {( sta^* { < std-Bcond(sta^*.last)> ).last | sta^*.last \epsilon \underline{sta}
                                         ∧ std-Vcond(sta *.last) = true
                                         std-Scond(sta*.last) = true }
   = {( sta * \underline{\$} < std - Bcond(sta * . last) > ). last | sta * \underline{\$} < [1, T]}
                                         A ...conditions as above... }
          This was because sta^* = \bot \Rightarrow sta^* \le <... > = \bot \Rightarrow (sta^* \le <... >).last = \bot
          since \pm \psi_{\perp} = 1. But \pm \psi_{\perp} \in \text{sta} \Rightarrow \langle \pm \rangle \in \text{conc}(\text{sta}) and \langle \pm \rangle \cdot \text{last} = \pm \langle \pm \rangle \in \text{conc}(\text{sta})
          so that no elements were excluded from the set by requiring sta* # 1.
          Similarly for T. So
   = \{ std-Bcond(sta) \mid staesta \land std-Vcond(sta)=true \land std-Scond(sta)=true \}
   = sts-Dt-cond(sta)
   Similarly for ...-Df-cond, so we have his-ind-cond(his-ind-c1, his-ind-c2)
   = sts-c1 • sts-Dt-cond \( \omega \) sts-c2 • sts-Df-cond
   = sts-cond(sts-c1,sts-c2)
   showing P-C(sts-cond(sts-c1,sts-c2), his-ind-cond(his-ind-c1,his-ind-c2)).
```

```
c) Clearly P-C(sts-c_his-ind-c) =>
      P-C(sts-attach(pla)(sts-c), his-ind-attach(pla)(his-ind-c))
 d) Clearly P-C(sts-c,his-ind-c) =>
      sts-setup(sts-c)(inp) = his-ind-setup(his-ind-c)(inp)
      since uabs{<sta>|...} = {sta|...}
 e) Along the same lines as in "b)" we show P-C(sts-c,his-ind-c) =>
      P-C(sts-g(par)(sts-c), his-ind-g(par)(his-ind-c)).
  Similarly to the above result it is not difficult to show the two results
  stated in square brackets.
PROOF OF 4.2.1-2:
 We only prove the result for std since the proof for his-sts essentially is
  similar to that of std. Below we elide the prefix std-.

    For g anyone of apply, content, push and for arbitrary c∈C we have:

      c@[Pg(par)]
     = \lambdasta.Pg(par)(sta) ESta -> c((Pg(par)(sta)) |Sta), "wrong" inA
     = \lambda sta_Vg(par)(sta) -> c(Bg(par)(sta)), "wrong" inA
     = g(par)(c)
 2) Similarly, for c \in C we have c \oplus [Pattach pla] = attach(pla)(c).
 3) We then show c\theta(ss1*ss2) = (c\theta ss1)\theta ss2 for any c \in C, ss1 \in Sta -c > R,
     ss2 € Sta -c> R. We have c⊕(ss1*ss2)
     = \lambda sta.(ss1*ss2)(sta) ESta -> c((ss1*ss2)(sta) |Sta), "wrong" inA
     = \lambda sta_{s2}(sta) = Sta_{s3}(ss2(sta) | Sta), ss2(sta) = Sta_{s3}(ss2(sta) | Sta), ss2(sta), ss2(s
                        c((ss1*ss2)(sta) |Sta), "wrong" inA
     = \lambdasta. ss2(sta) ESta -> [ss1(ss2(sta) | Sta) ESta ->
                       c((ss1*ss2)(sta) |Sta), "wrong" inA ], "wrong" inA
     = \lambdasta. ss2(sta) ESta -> [ ss1(ss2(sta) | Sta) ESta ->
                        c(ss1(ss2(sta) | Sta) | Sta), "wrong" in A ],
                        "wrong" inA
     = \lambdasta. ss2(sta) ESta -> [(c\thetass1)(ss2(sta) |Sta)], "wrong" inA
     = (c\theta ss1)\theta ss2
 4) The proof of the lemma is by structural induction on Exp. This is
     straight-forward by "1)", "2)" and "3)".
                                                                                                                                                    PROOF OF 4.2.1-4:
 The proof is by structural induction on Exp. Define predicates P-S:Sta->B by
 P-S(sta) = sta.wit \notin \{1, \tau\} and P-Exp:Exp->B by
 P-Exp(exp) = \forall s \in P(Sta*): [ (\forall sta*es: P-S(sta*.last)) =>
       [ {sta*.last | sta*∈(Pchis-stsFexpIocc s) √1}
       = {(PtstdFexpIocc (sta*_last)) |Sta | sta*∈s} ∧
       ∀sta*e(Pchis-stsTexpTocc s) \v1: P-S(sta*.last) ]]
 1) <u>Case bas</u>: Assume ∀sta*es: P-S(sta*.last). Then
     Pchis-stsEbas Tocc sv1
     = his-sts-DpushEbas1 s
     = {his-std-BpushEbasI sta* |sta*\epsilon std-VpushEbasI sta* = true}
     = {sta*§<std-BpushEbas1(sta*.last)> |sta*es}
     Since 1, T∉s we have
     {sta*.last |sta*∈(P2his-stsIbasIocc s) \1}
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= {std-BpushEbas1(sta*.last) | sta*es}
     = {(P2stdEbasI occ (sta*.last)) |Sta | sta*es}
     and (e.g. from 4.2.1-3) sta*es => P-S(P%stdEbas*locc (sta*.last) |Sta).
     Hence P-Exp(bas).
 2) Case ide: This case is similar to the above case.
 3) <u>Case exp1 ope exp2</u>: Assume ∀sta*es: P-S(sta *_last). Then
     P&his-sts Texp1 ope exp2 I occ s V1
       = his-sts-DapplyFopeI s2
     where s2 = P_{his-sts} = xp2 I occ < 3> s1 <math>\sqrt{1}
                 s1 = P_6^2 his - sts \mathbb{E} exp1 \mathbb{I} occ \leq <1 > s \psi 1
     So that by P-Exp(exp1) and P-Exp(exp2)
     {sta*.last | sta*es2}
       = {P %std Texp2 I (occ < < 3>) (sta * . last) | Sta
                                                                                     | sta*es1}
       = \{P_{s}^{2} td \mathbb{E} exp2 \mathbb{I}(occ \leq <3>) (P_{s}^{2} td \mathbb{E} exp1 \mathbb{I}(occ \leq <1>) (sta^{2} \cdot last) | Sta) | Sta 
                                                                                         I sta<sup>*</sup>€ s}
     and by several applications of Lemma 4.2.1-3
     { sta*.last | sta*∈P$his-sts Lexp1 ope exp2 I occ s √1}
       = { sta*.last | sta*ehis-sts-DapplyEope  s2 }
                 and by 1,T$ s2
       = { std-BapplyFopeI(sta*.last) | sta*es2 \( \) std-VapplyFopeI(sta*.last)=true}
       = { std-PapplyFopeIsta|Sta | stae{sta*.last | sta*es2}}
       = { (std-PapplyFopeI * P&stdFexp2Iocc§<3> * P&stdFexp1Iocc§<1>)
                (sta*.last)|Sta | sta*es }
       = { (P&stdFexp1 ope exp2I occ (sta*.last)|Sta) | sta*es }
     Also sta*es => P-S( (P?stdTexp1 ope exp21 occ (sta*.last)) |Sta) as follows
     from Lemma 4.2.1-3. Hence P-Exp(exp1 ope exp2).
PROOF OF 4.2.2-9:
 Shown after the proof of 4.2.2-10.
                                                                                                                                                  PROOF OF 4.2.2-10:
 Lemma 4.2.1-3 shows pre3(sta1,sta2,exp) => sta1.wit(⟨1,+⟩ ∧ sta2.wit(⟨1,+⟩
 => [(PcstdFexpI sta1 ESta)=true \( (PcstdFexpI sta2 ESta)=true \( \)
         #((P2stdTexpIsta1 | Sta).wit) \( \( \) \( \) \( \) \( \)
         #((Pcstdlexplsta2 | Sta).wit)e{1,...}]
 It therefore suffices to show ∀exp: P-Exp(exp) where P-Exp: Exp->B is
 P-Exp(exp) = ∀sta1,sta2∈Sta: [ pre3(sta1,sta2,exp) =>
         [ (PtstdEexpIstal | Sta).witv1 = (PtstdEexpIsta2 | Sta).witv1 ~
             pre3(PfstdFexpIsta1 | Sta, PfstdFexpIsta2 | Sta, exp) ]]
 The proof is by a structural induction:
 1) Case bas: Assume pre3(<env1,inp1,out1,wit1>, <env2,inp2,out2,wit2>, bas).
     Then PrstdEbasI<env[i], inp[i], out[i], wit[i]> |Sta
     = std-BpushEbasI<env[i],inp[i],out[i],wit[i]>
     = <env[i],inp[i],out[i], <std-BEbas I>€wit[i]>
     From this P-Exp(bas) easily follows.
 2) <u>Case ide</u>: As above.
 3) Case exp = exp1 ope exp2: Let sta1, sta2 be such that
     pre3(sta1,sta2,exp). Then P6stdFexp1 ope exp2∃ sta[i]
     = ((std-PapplyFopeI * P&stdFexp2I) * P&stdFexp1I ) sta[i]
     = (std-PapplyFopeI * PfstdFexp2I) sta[i]
```

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where Lemma 4.2.1-3 implies that there exists val[i] '€ Val such that
      sta[i]' = <sta[i].env, sta[i].inp, sta[i].out, <val[i]'>{(sta[i].wit) >
   Since pre3(sta1,sta2,exp) => pre3(sta1,sta2,exp2) we get from P-Exp(exp2)
   that val1'=val2'. Obviously pre3(sta1', sta2', exp) because
   sta[i]'.env = sta[i].env. So P&stdFexp1 ope exp2I sta[i]
   = std-PapplyFopeI sta[i]"
      where Lemma 4.2.1-3 implies that there exists val[i]"eVal so sta[i]" =
      <sta[i].env, sta[i].inp, sta[i].out, <val[i]",val[i]"> §(sta[i].wit) >
   As before, val1"=val2" and pre3(sta1",sta2",exp). Then
   PastdFexp1 ope exp21 sta[i]
   = sta[i]" in(Sta+{"wrong"}) where
   sta[i]" = <sta[i].env, sta[i].inp, sta[i].out
   , <std-@EopeI<val[i]', val[i]"> §(sta[i].wit) >
Then sta1"'.wit\1 = sta2"'.wit\1 and pre3(sta1"',sta2"',exp).
   This shows P-Exp(exp1 ope exp2).
                                                                              PROOF OF 4.2.2-9:
 To show wabs-r2 ⊆ wabs-r3 it suffices to show \sta*eSta*: r2(sta*) ≥
 r3(sta*). By the form of the definitions of r2 and r3 it is enough to show
 ₩sta1,sta2,exp: pre3(sta1,sta2,exp) => pre2(sta1,sta2,exp).
 This follows from Lemma 4.2.2-10.
                                                                              PROOF OF 4-2-3-2:
After the proof of 4.2.3-6.
                                                                              PROOF OF 4.2.3-5:
Define the predicate P-Exp: Exp->B by P-Exp(exp) =
 E P-S(his-sts-s,ae-s => [
P-S( (Pthis-stsTexpTocc his-sts-s) \( \psi \), (PtaeTexpTocc ae-s) \( \psi \) \( \lambda \)
Pthis-stsTexpTocc his-sts-s \2 \( \text{R conc-r3} \) ( PtaeTexpT occ ae-s \( \text{2} \)]]
1) We must show P-C(his-sts-c,ae-c) =>
   P-C(Zhis-stsEexp1 occ his-sts-c, ZaeEexp1 occ ae-c). Assume
   P-C(his-sts-c,ae-c) A P-Exp(exp) A P-S(his-sts-s,ae-s). Then
  this-sts Fexp Tocc his-sts-c his-sts-s
   = his-sts-c( Pthis-stsTexpI occ his-sts-s V1) u
      Pchis-sts Fexp I occ his-sts-s √2
         which was by Lemma 4.2.1-2
    E his-sts-c(Pahis-stsTexpI occ his-sts-s √1) ⊔
      (R conc-r3)(Ptaelexpl occ ae-s√2)
         which was by P-Exp(exp); by P-Exp(exp) A P-C(his-sts-c,ae-c) we get
    E (R conc-r3)(ae-c(P$aelexp1 occ ae-s √1)) ∪
      (R conc-r3)(Paelexpl occ ae-s v2)
   ⊆ (R conc-r3)[ ae-c(P&aelexp1 occ ae-s \v1) \ P&aelexp1 occ ae-s \v2]
         and by Lemma 4.2.3-4
   = (R conc-r3)(Zaelexpl occ ae-c ae-s)
We then are left with showing P-Exp(exp). This is done by a structural
induction on Exp (cases 2, 3 and 4 below).
2) <u>Case bas</u>: Assume P-S(his-sts-s,ae-s).
  a) Pchis-sts bas occ his-sts-s
    = <his-sts-s', \[Lhis-sts-s/<occ,"(exp">] \(\pi\) \[Lhis-sts-s'/<occ,"exp)">] >
    where
          his-sts-s¹ = his-sts-DpushEbasI his-sts-s
```

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= {his-std-BpushIbasI sta* | sta*ehis-sts-s}
                         (this was because his-std-VpushEbas I sta = true )
                    = {sta*&< std-BpushEbasI(sta*.last)> |sta*&his-sts-s}
  b) Praelbasi occ ae-s
    = <ae-s', *[ae-s/<occ,"(exp">] = *[ae-s'/<occ,"exp)">]>
    where
         conc-r3(ae-s') = conc-r3(ae-s)
                        = \{sta^* \mid r3(sta^*) \ge ae-s\}
  c) We now show his-sts-s' conc-r3(ae-s'). Let sta*ehis-sts-s. Then
    sta* ∮{⊥, +} so r3(sta* §< std-Bpush Ibas I(sta* last) >)
     2 r3(sta*) n {exp |pre3(sta*.last, std-BpushEbasI(sta*.last), exp)}
     = r3(sta^*)
                     (which was by obvious property of std-Boush)
     2 ae-s
                     (which was by using P-S(his-sts-s,ae-s))
    This yields his-sts-s' 5 conc-r3(ae-s')
 d) For any sta*€his-sts-s' we have sta*.last.wit∉{.,...} as easily follows
    from Lemma 4.2.1-3. This yields P-S(his-sts-s', ae-s') and P-Exp(bas).
3) Case ide: This case is similar to case 2.
4) Case expl ope exp2: Assume P-S(his-sts-s,ae-s). This case does not follow
  the pattern of cases 2 and 3. We abbreviate:
    F4 = Pattach<occ, "exp)">
    F3 = F4 * PapplyFopelFexp1 ope exp21
    F2 = F3 * PEEexp2I occ < 3>
    F1 = F2 * P6 \text{Fexp} 1 \text{I occ} <1>
  Then
  a) PEhis-stsTexp1 ope exp2I occ his-sts-s
    = his-sts-F1(his-sts-s) \( \( \( \( \)_{\psi} \) \( \) \( \)_\( \) \( \)_\( \)
    = his-sts-F2(his-sts-s1) u <1, his-sts-a1 u 1[his-sts-s/<occ,"(exp">]>
       where <his-sts-s1, his-sts-a1> = P6his-sts Fexp1 I occ €<1> his-sts-s
    Similarly, Paelexp1 ope exp21 occ ae-s
    = ae-F2(ae-s1) u <1, ae-a1 u _[ae-s/<occ,"(exp">]>
    By induction hypothesis P-Exp(exp1) we know
       his-sts-a1  (R conc-r3)(ae-a1) 
       P-S(his-sts-s1, ae-s1)
    and by Lemma 4.2.1-4 we know
       {sta*.last |sta*€his-sts-s1}
       = {P&stdFexp1 I(sta*.last) |Sta |sta*€his-sts-s}
  b) P6his-stsTexp1 ope exp2I occ his-sts-s
    = his-sts-F3(his-sts-s2) u
      <1, his-sts-a2 u his-sts-a1 u _[his-sts-s/<occ,"(exp">] >
    and Paelexp1 ope exp21 occ ae-s
    = ae-F3(ae-s2) u <1, ae-a2 u ae-a1 u [ae-s/<occ,"(exp">]>
    where we know
       his-sts-a2 5 (R conc-r3)(ae-a2)
       P-S(his-sts-s2, ae-s2)
    and by Lemma 4.2.1-4
       {sta*.last | sta*ehis-sts-s2 }
       = {P6stdEexp21(P6stdEexp11(sta*.last) | Sta) | Sta | sta*e his-sts-s}
  c) Phis-stsTexp1 ope exp21 occ his-sts-s
```

```
= his-sts-F4(his-sts-s3) u < , his-sts-a2 u his-sts-a1 u
                                     L[his-sts-s/<occ,"(exp">]>
     where his-sts-s3
     = his-sts-DapplyFopeI(his-sts-s2)
     = {sta*s< std-BapplyFope1(sta*_last) > |sta*ehis-sts-s2}
     because Lemma 4.2.1-3 shows that when sta^*\epsilon his-sts-s2 then sta^*.last.wit
     is of the form \langle val1, val2 \rangle \S wit for wit \in \{\bot, \tau\} so that
     std-VapplyFopeI(sta * last) = true.
     Similarly, Paelexp1 ope exp21 occ ae-s
     = ae-F4(ae-s3) u <1, ae-a2 u ae-a1 u 1[ae-s/<occ,"(exp">]>
     where ae-s3 = ae-s \upsilon {exp1 ope exp2}.
     We want to show P-S(his-sts-s3, ae-s3). We must show 2 things:
     i) ∀sta*∈his-sts-s3: sta*_last_wit {{⊥,-¬}}. This is straight-forward
       because ∀sta*ehis-sts-s2: #(sta*.last.wit)e{2,3,...}.
     ii) ∀sta*€his-sts-s2 that
       r3(sta*6< std-BapplyFope1(sta*.last) >) ≥ (ae-s) v {exp1 ope exp2}.
       We have r3(sta*5< std-BapplyFope1(sta*.last)>)
       = [r3(sta*)]
         n {exp | pre3(sta *.last, std-BapplyFope1(sta *.last), exp} ]
          υ {exp |gen3(std-BapplyFopeI(sta*.last), exp)}
       = r3(sta*) u {exp| gen3(std-BapplyFope1(sta*.last), exp)}
       So it suffices to show gen3(std-BapplyFope1(sta*.last), exp1 ope exp2).
       We know by "4b)" ∃sta such that sta.wit¢{⊥,τ} and
       std-BapplyFope (sta*.last)
       = std-BapplyFopeI( PtstdFexp2I( PtstdFexp1I sta |Sta)|Sta)
       which by Lemma 4.2.1-3 is seen to be P&stdFexp1 ope exp21 sta.
       So we must show gen3( P&std(exp1 ope exp2\)sta |Sta, exp1 ope exp2)
       knowing sta.wite{⊥, 7}. An equivalent formulation is to show
       pre2(sta, P&stdlexp1 ope exp21 sta|Sta, exp1 ope exp2).
       But we know pre3(sta, P&stdFexp1 ope exp21 sta|Sta, exp1 ope exp2)
       (by 4.2.1-3) so Lemma 4.2.2-10 shows this.
     We have shown P-S(his-sts-s3, ae-s3)
   d) Pchis-stsTexp1 ope exp2I occ his-sts-s
     = <his-sts-s3, \[Lhis-sts-s3/<occ,"exp)">] u
                     his-sts-a2 u his-sts-a1 u Lhis-sts-s/<occ,"(exp">]>
     and Paelexp1 ope exp21 occ ae-s
     = <ae-s3, \( \( \text{Lae-s3/<occ, "exp) "> ] \( \text{lae-a2 u ae-a1 u \( \text{Lae-s/<occ, "(exp">} ) } \)
     It easily follows that P-Exp(exp1 ope exp2) holds.
                                                                             PROOF OF 4.2.3-6
 Assume that P-C(his-sts-c,ae-c) and P-S(his-sts-s,ae-s) hold. We calculate
his-sts-g(par)(his-sts-c)(his-sts-s) = his-sts-c(his-sts-s')
where his-sts-s'
= {his-std-Bg(par)(sta*) |sta*€his-sts-s ∧ his-std-Vg(par)(sta*)=true}
= {sta*$< std-Bg(par)(sta*.last)> |sta*ehis-sts-s ^
                                        std-Vg(par)(sta * last)=true}
Similarly, ae-g(par)(ae-c)(ae-s) = ae-c(ae-s) where ae-s' = PREg(par) \cdot n ae-s
because GENg(par) = 0. It suffices to show P-S(his-sts-s',ae-s').
1) Clearly, ∀sta*ehis-sts-s': sta *last.wite{⊥,+}
```

2) $conc-r3(ae-s') = {sta* | r3(sta*) \ge PREg(par) \land ae-s}$

Let $sta^* \in his$ —sts—s and assume std—Vg(par)($sta^* = last$) = true. Abbreviate sta' = std—Bg(par)($sta^* = last$). We now show r3($sta^* = last$) $\geq PREg(par)$ n ae—s. Since r3(sta^*) $\geq PREg(par)$. We show this for each primitive function (except apply):

g = assign: Let exp ϵ PREassignFideI. Then ide ϵ JFexpI and since ide ϵ L, τ and JFexpI α { ι , τ } = 0 we have \forall ide' ϵ JFexpI: (sta*.last.env)Fide'I = (sta'.env)Fide'I. Hence pre3(sta*.last,sta',exp).

g € {content, push, read, write}: Trivial since sta * last.env = sta !.env[]

PROOF OF 4.2.3-2:

The proof is by structural induction. Define the predicates P-Cmd: Cmd->B by P-Cmd(cmd) = [P-C(his-sts-c,ae-c) => P-C(his-stsEcmdI occ his-sts-c, &aeEcmdI occ ae-c)] and P-Dcl and P-Exp similarly.

<u>Structural induction on Dcl</u>: Along the lines of Lemma 4.2.3-6 we can prove P-C(his-sts-c, ae-c) => P-C(his-sts-attach(pla)(his-sts-c), ae-attach(pla)(ae-c)). Then, in view of Lemma 4.2.3-6, the proof is straight-forward.

Structural induction on Exp: Use Lemma 4.2.3-5 instead.

<u>Structural induction on Cmd</u>: Along the lines of Lemma 4.2.3-6 we can prove P-C(his-sts-c1,ae-c1) A P-C(his-sts-c2,ae-c2) => P-C(his-sts-cond(his-sts-c1, his-sts-c2), ae-cond(ae-c1, ae-c2)). This makes the structural induction easy, except for the WHILE loop.

For the WHILE loop: Assume P-C(his-sts-c,ae-c) and define $g=\lambda c'$. The xplocc <1>; cond(FirmdIocc <2>; c', attach<occ, "cmd)">; c). Clearly P-C(his-sts-c',ae-c') => P-C(his-sts-g(his-sts-c'), ae-g(ae-c')). Also P-C(1,1) so that $\forall n \geq 0$: P-C(his-sts-g'(1), ae-g'(1)). Hence $\forall n \geq 0$: P-C(his-sts-g'(1), FIX(ae-g)) and P-C(FIX(his-sts-g), FIX(ae-g)). Then P-C(This-sts-WHILE exp DO cmd OD Iocc his-sts-c, Cae-EWHILE exp DO cmd OD Iocc ae-c) easily follows. Hence P-Cmd(WHILE exp DO cmd OD).

Structural induction on Pro: We must show P-C(his-sts-c,ae-c) =>
\forall inper(Inp): his-sts-setup(his-sts-c)(inp)

\(\text{Structural induction on Pro: We must show P-C(his-sts-c,ae-c) =>
\forall inper(Inp): his-sts-setup(his-sts-c)(inp)

\(\text{Structural induction on Pro: We must show P-C(his-sts-c,ae-c) =>
\forall inper(Inp): his-sts-setup(his-sts-c)(inp)

\(\text{Structural induction on Pro: We must show P-C(his-sts-c,ae-c) =>
\forall inper(Inp): his-sts-setup(his-sts-c)(inp)

\(\text{Structural induction on Pro: We must show P-C(his-sts-c,ae-c) =>
\forall inper(Inp): his-sts-setup(his-sts-c)(inp)

\(\text{Structural induction on Pro: We must show P-C(his-sts-c,ae-c) =>
\forall inper(Inp): his-sts-setup(his-sts-c)(inp)

\(\text{Structural induction on Pro: We must show P-C(his-sts-c,ae-c) =>
\forall inper(Inp): his-sts-setup(his-sts-c)(inp)

\(\text{Structural induction on Pro: We must show P-C(his-sts-c,ae-c) =>
\forall inper(Inp): his-sts-setup(his-sts-c)(inp)

\(\text{Structural induction on Pro: We must show P-C(his-sts-c,ae-c) =>
\forall inper(Inp): his-sts-setup(his-sts-c)(inp)

\(\text{Structural induction on Pro: We must show P-C(his-sts-c,ae-c) =>
\forall inper(Inp): his-sts-setup(his-sts-c)(inp)

\(\text{Structural induction on Pro: We must show P-C(his-sts-c,ae-c) =>
\forall inper(Inp): his-sts-setup(his-sts-c)(inp)

\(\text{Inper(Inp): his-sts-setup(his-sts-c) inper(Inp): his-sts-setup(his-sts-c)(inp)

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APPENDIX 5

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PROOF OF 5.2-5:
 Part of the result follows from 5.1-5(1). For the remaining part, assume
 pure[Pla](pla) and assume pla-in ∉ local(Aattach pla) = {pla}. Let c∈C and
 s≤S be given. Define
 cl = Close(Aattach(pla)<pla-in, \lambdas.s>\v2, pla-in, s)
    = \lambda pla'. { s | ses \lambda pla' = pla}
 Then (R 4)cl
  = \lambdapla'. U{ s | ses \lambda pla'=pla}
= \lambdapla'. U( U{ {s|pla'=pla} | ses})
  = λpla'. U{ U{s|pla'=pla} | ses}
                                                    (by 2.1.1-7)
  = λpla'. U{ pla'=pla -> s, 1 | sεs}
 EQ \lambdapla'. U{ pla==pla -> s, \perp | ses}
      (which was by pure[Pla](pla) and Assumption 2.2-3)
  = U{_L[s/pla] | ses}
 so that U\{attach(pla)(c)(s) \mid ses\}
  = U{ c(s) u_l[s/pla] | ses}
  = U\{c(s) \mid ses\}u U\{L[s/pla] \mid ses\}
 EQ U{ c(s) | s € cl(out(Aattach pla)) } (R U)cl
                                                                                       PROOF OF 5.2-7:
 Part of the result is by 5.1-5(3), because out(Ag2) \( \epsilon \) local(Ag2) implies
 out(Ag2) #local(Ag1) when local(Ag1) nlocal(Ag2) = 0. For the remaining part,
 assume P-G(g1,Ag1) \wedge P-G(g2,Ag2) \wedge local(Ag1) \cap local(Ag2)=0 and
 pla-in¢local(Ag1)ulocal(Ag2). Let c€C and s≤S be given. Then
Uf (g1;g2;c)s | ses }
  EQ U(g2;c)s \mid s \in cl1[out(Ag1)] \} \cup (R U)cl1
        which was by hypothesis where
        cl1 = Close( Ag1<pla-in,\lambdas.s>\forall2, pla-in, s)
  EQ LK c(s) | s \in cl2[out(Ag2)] } \sqcup (R \sqcup)cl1 \sqcup (R \sqcup)cl2
        which was by hypothesis where
        cl2 = Close( Ag2<out(Ag1),\lambdas.s>\forall2, out(Ag1), cl1[out(Ag1)])
  = Lf c(s) | s e (cl1 \( \text{cl2}) \( \text{Lout(Ag2)]} \( \text{L} \) (cl1 \( \text{cl2})
        because cl1[out(Ag2)] = \bot (from local(Ag1) \land local(Ag2) = \emptyset)
 Define cl = Close( (Ag2*Ag1)<pla-in, \lambdas.s>\psi2, pla-in, \underline{s}}
            = Close(Ag2<out(Ag1),\lambdas.s>\forall2 \rightarrow Ag1<pla-in,\lambdas.s>\forall2, pla-in, s)
 Then it suffices to show cl = cl1 \mu cl2, where \mu is the binary join of
 Pla -t> P(S).
To show cl ∃ cl1 ⊔ cl2 we show cl2cl1 and cl2cl2. That cl2cl1 is by
 Observation 5.2-2. That cl2cl2 is by straight-forward calculations simpler
 than those below for the case cl 5 cl1 
ightharpoonup cl2. So consider the converse
 inclusion. Let pla' be arbitrary and assume s'ecl(pla'). Define trans(i) as
 a shorthand for <<pla[i-1],pla[i]>,d[i]>. Then
    ∃ S€S
    \exists trans(1),...,trans(n) \in Ag1<pla-in\lambdas.s>\forall2 \cup Ag2<out(Ag1),\lambdas.s>\forall2
 so pla[0] = pla-in \wedge pla[n] = pla' \wedge s' = dn(...(d1(s)))
```

Since pla-in∉{out(Ag1)}ulocal(Ag2) we know trans(1)eAg1<pla-in, 1s.s>ψ2.

This implies the existence of

```
k1 = \max\{j \mid trans(1),...,trans(j) \in Ag1 < pla-in, 2s.s > \psi2\}
 Then d[k1](...(d1(s))) \in cl1(pla[k1]) and we are done if k1 = n. Otherwise
 k1 < n so that
   k2 = max\{j \mid trans(k1+1),...,trans(j) \in Ag2<out(Ag1),\lambda s.s>\psi 2\}
 exits. Then plack1] \epsilon local(Aq1) \Lambda plack1] \epsilon local(Aq2)\cup{out(Aq1)} so
 pla[k1] = out(Ag1) showing d[k2](...(d[k1](...(d1(s))) \in cl2 pla[k2].
 We are done if k2 = n. To see that k2 = n assume k2 < n. Then
 pla[k2] \( \text{local(Ag2)} \) \( \text{pla[k2] \( \text{elocal(Ag1)} \( \text{vfla-in} \) \( \text{which is a contradiction[]} \)
PROOF OF 5.2-8:
 Proof is shown after the proof of 5.2-11.
                                                                                        PROOF OF 5.2-9:
 Part of the result follows from 5.1-5(2,4). For the remaining part, assume
 P-G(g1,Ag1) \wedge P-G(g2,Ag2) \wedge out(Ag1) = out(Ag2) \wedge
 local(Ag1)/nlocal(Ag2)={out(Ag2)} and pla-in (Ag1)/ulocal(Ag2). Let c and
 s be given and let trans(i) be an abbreviation of <<pla[i-1],pla[i]>,d[i]>.
 Then U{cond(g1;c, g2;c)s | ses}
 = \mathbb{I}\{(g1;c)(Dt-cond(s))| ses\}_{u} \mathbb{I}\{(g2;c)(Df-cond(s))| ses\}
 EQ U{ c(s) | secl1[out(Ag1)]} и (R Ц) cl1 и
    U{ c(s) | secl2[out(Ag2)]} и (R U)cl2
 which was by assumptions where
 cl1 = Close(Ag1<pla-in, \lambdas.s>\forall2, pla-in, {Dt-cond(s) | s\epsilons})
     = \lambdapla. {dn(...(d1(Dt-cond(s))) | ses \lambda \existstrans(1),...,trans(n) \in
                 Ag1<pla-in, \(\lambda \s. \s>\\\ 2\) so pla[0]=pla-in \(\lambda \pla[n]=\pla\)
        (and by iii of P-F(Ag1) and pla-in∉local(Ag1) )
     = \lambdapla. {dn(...(d1(s))) | ses \existstrans(1),...,trans(n) \in
                 Ag1<pla-in,Dt-cond>\forall2 so pla[0] = pla-in \land pla[n] = pla}
     = Close( Ag1<pla-in,Dt-cond>\v2, pla-in, s)
      = Close( [Ag1*Arecord(Dt-cond)]<pla-in, λs.s>ψ2, pla-in, s)
     = Close( <u>trans1</u>, pla-in, <u>s</u>)
 where \underline{\text{trans1}} = [Ag1 \times Arecord(Dt-cond)] < pla-in, <math>\lambda s.s > \psi 2
 Similarly,
 cl2 = Close( Ag2<pla-in,\lambdas.s>\psi2, pla-in, {Df-cond(s) |s\epsilons})
     = Close( trans2, pla-in, s)
 where trans2 = [Ag2*Arecord(Df-cond)]<pla-in,\(\lambda\)s.s>\\\2
 Since out(Ag1)=out(Ag2) we get U\{cond(g1;c,g2;c)s \mid s \in s\}
 = U\{c(s) \mid s \in (cl1 \cup cl2)[out(Ag2)]\} \cup (R \cup (cl1 \cup cl2)
 (by using Lemma 2.1.1-7). Define
 cl = Close( (EAg1*Arecord(Dt-cond)] WITH EAg2*Arecord(Df-cond)])
               \langle pla-in, \lambda s.s \rangle / 2, pla-in, s)
    = Close( <u>trans1vtrans2</u>, pla-in, <u>s</u>)
 It suffices to show cl = cl1 \, \mu \, cl2. The \frac{3}{2} inclusion is obvious by 5.2-2 so
 consider the \( \sigma\) inclusion. Let pla' be arbitrary and assume s'ecl(pla'). Then
    f trans(1),...,trans(n) e trans1vtrans2
 so pla[0] = pla-in \wedge pla[n] = pla' \wedge s' = dn(...(d1(s)))
 Assume (without loss of generality) that trans(1) € trans1 so that
 k = max\{j \mid trans(1),...,trans(j) \in trans1\} is well-defined. Also k=n, because
 otherwise plack] elocal(Ag1) 
plack] e(local(Ag2) - {out(Ag2)}) u {pla-in} which
 is a contradiction. Clearly s'eClose(trans1, pla-in, s) pla' = cl1 pla'. []
```

```
PROOF OF 5.2-11:
  Note by 5.1-4 that out(Ag1) = plaT \Lambda local(Ag1) \subseteq xpld(occ\S<1>) and
  out(Ag2) = plaB \ local(Ag2) \ xpld(occ\{<2>).
  1) We first develop a formulation of \iint \{g[c](c')(s) \mid s \in s\}. In the sequel
        plae{pla-begin, plaB} intuitively is the arc along which s has been
        propagated. Let
        a = U\{ g[c](c')(s) \mid ses \}
          EQ U{ cond(g2;c', attach(pla-out);c)s | secl1<pla,s>plaT} u
                    (R U)(cl1<pla,s>)
                          which was by P-G(g1, Ag1) where
                          cl1 < pla, s > = Close(Ag1 < pla, \lambda s.s > \lambda 2, pla, s)
              = at u af u (R U)(cl1<pla,s>)
        where
        at = \mathbb{I} (g2;c')(Dt-cond(s)) | secl1<pla,s>plaT}
              EQ U\{ c'(s) | s\include{cl2\left\rangle} cl2\left\rangle cl2\
                          which was by P-G(g2, Ag2) where
                          cl2 < pla_s > = Close(Ag2 < plaT_\lambda s.s > \psi_plaT_\lambda
                                                                                      {Dt-cond(s) | secl1<pla,s>plaT})
                                                           = Close( Ag2<plaT,Dt-cond>√2, plaT, cl1<pla,s>plaT)
                          reasoning as in Lemma 5.2-9
        and
         af = U{ (attach(pla-out);c)(Df-cond(s)) | secl1<pla,s>plaT}
              EQ U(c(s) \mid s \in c(3 \leq p(a,s))) | (R U(c(3 \leq p(a,s)))
                          which is by 5.2-5 where
                          cl3<pla,s> = Close( Aattach(pla-out)<plaT,\lambdas.s>\psi2, plaT,
                                                                                      {Df-cond(s) | sect1 < pta, s > ptaT})
                                                            = Close( Aattach(pla-out)<plaT,Df-cond>√2, plaT,
                                                                                      cl1<pla,s>plaT)
                          reasoning as above.
        Then
         a EQ U{ c'(s) | secl2<pla,s>plaB} u
                       U{ c(s) | secl3<pla,≤>pla-out}⊔
                       (R U)(cl1<pla,s> u cl2<pla,s> u cl3<pla,s>)
              = U{ c'(s) | s €[cl1<pla,s> u cl2<pla,s> u cl3<pla,s>]plaB} u
                       لا د(s) | seccl1<pla,s> عدا2<pla,s> عدا3<pla,s>Jpla-out} ت
                       (R U)[ cl1<pla,s> u cl2<pla,s> u cl3<pla,s>]
        where the last step is because cl1 \leq pla, \leq plaB = cl3 \leq pla, \leq plaB = 0 and
        cl1 \leq pla, \leq pla - out = cl2 \leq pla, \leq pla - out = 0.
  2) We now derive a formulation of U\{(g[c])^n c^n \le | s \in \underline{s}\}. This formulation is
        not the desired one but serves as a useful auxiliary stage. By calculations
        for k=1,2 one may guess (for k>1):
        \coprod \{(g[c])^k c's \mid s \in S\} \in \coprod \{c'(s) \mid s \in bk \text{ plaB}\} \sqcup

    U { c(s) | s ∈ [bku...ub1] pla-out}    u

                                                                             (R U) [bku...ub1]
        where
        b1 = cl1<pla-begin,s> u cl2<pla-begin,s> u cl3<pla-begin,s>
        bk = cl1 < plaB, b[k-1] plaB > ucl2 < plaB, b[k-1] plaB > ucl3 < plaB, b[k-1] plaB > ucl3 < plaB, b[k-1] plaB > ucl3 < plaB > 
        It may be helpful to note that bk \epsilon Pla -t> \theta(S) so
        (R ∐)(bku...ub1) € Pla -t> S. We verify the guess by induction on k.
        k=1: The result is immediate from "1)".
        k+1>2: We calculate
             ∐{ (g[c]) K+1 c's | ses}
```

```
= \coprod{ (g[c])<sup>K</sup>(g[c];c')s | s\ins}
    EQ U{ (g[c];c')s | se(bk plaB)} u {c(s) | se([bku...ub1] pla-out)} u
        (R U) [bku ... ub1]
           which was by induction hypothesis; by "1)" we get:
    EQ U( c'(s) | se(b[k+1] plaB)} μ
         U{ c(s) | se(b[k+1]u...b1) pla-out}u
        (R L) (bEk+1]u...ub1)
3) We now prove \forall k \ge 1: bk = ak because then the desired result easily follows
  from "2)". The proof is by induction on k.
  k=1: The proof can be obtained by adapting (simplifying) the proof below.
  k+1>2: We have by the inductive hypothesis:
    b[k+1] = cl1<plaB,(bk plaB)> u cl2<plaB,(bk plaB)> u cl3<plaB,(bk plaB)>
            = cl1<plaB,(ak plaB)> u cl2<plaB,(ak plaB)> u cl3<plaB,(ak plaB)>
    Abbreviate
        trans1 = Ag < pla-begin, \lambda s. s > \psi 2
        trans2 = {\langle \langle plaB, plaR \rangle, \lambda s.s \rangle}
    and let pla' be arbitrary. We now show b[k+1] pla' = a[k+1] pla'. We use
    trans(i) as a shorthand for < <pla[i-1],pla[i]>, d[i]>.
    Inclusion ≤:
    i) Assume s' € cl1<plaB,(ak plaB)> pla'. Then
          ∃ ses
          ∃ trans(1),...,trans(m) ∈ trans1vtrans2
       so pla[0] = pla-begin \( \text{pla[m]} = \text{plaB} \( \text{\lambda} \)
          |\{i \mid i \le m \land trans(i) \in \underline{trans2}\}| = k-1 \land
          dm(...(d1(s))) \in (ak plaB)
       Also \exists trans(m+1),...,trans(n) \in Ag1<plaB,\lambdas.s>\forall2
       so pla[m] = plaB , pla[n] = pla',
          s' = dn(...(dn(...(d1(s)))))
       By 5.1-4(b,c) we have
       Ag1<plaB, \( \gamma \) s.s>\( \forall 2 \) trans2 \( \forall 2 \) trans2 \( \forall 2 \) trans2.
       From "ii" of P-F(Ag1) and by 5.1-4(b): j \in \{m+2,...,n\} = >
       pla[j-1] \in xpld(occ\{<1>) => pla[j-1] \neq plaB => trans(j) \notin trans2. Also
       trans(m+1) = \langle plaB, plaR \rangle, \lambda s.s \rangle follows from plaEm] = plaB and 5.1-4(c)
       so that trans(m+1) \in \text{trans2}. This shows s' \in a[k+1] pla'.
    ii) Let s' € cl2<plaB, ak plaB>. Then (as above)
          3 ses
          ∃ trans(1),...,trans(n) € trans1vtrans2
       so pla[0] = pla-begin \( \text{pla[n]} = \text{plaT}_\( \text{\lambda} \)
          dn(...(d1(s))) \in cl1 < plab, ak plab> plaT = a[k+1] plaT
       Also \exists trans(n+1),...,trans(q) \in Ag2<plaT,Dt-cond>\forall2 \subseteq trans1
       so pla[n] = plaT \ pla[q] = pla' \
          s' = dq(...(dn(...(d1(s)))
       Then s' \in aEk+1] pla' because Ag2<plaT, Dt-cond>\forall2 o trans2 = 0
       which is by "ii" of P-F(Ag2).
    iii) Let s' € cl3<plaB, ak plaB>. As before s' € a[k+1] pla'.
    Inclusion 2:
    Assume s' ∈ a[k+1] pla'. Then
        ∃ S€S
```

```
\exists trans(1),...,trans(m) \in trans1 \cup trans2
     so pla[0] = pla-begin A pla[m] = pla'A
         s' = dm(...(d1(s))) \wedge
         |\{i \mid trans(i) \in \underline{trans2}\}| = k
     Define q = max{j | trans(j) € trans2}. Obviously q is well-defined
     because k>1. Then trans(q) = \langle plaB, plaR \rangle, \lambda s.s \rangle and
     d[q-1](...(d1(s))) \in (ak plaB). By 5.1-4(c) we have
     trans(q) \in Ag1<plaB, \lambdas.s>\forall2 so that
     q1 = \max\{j \mid trans(q),...,trans(j) \in Ag1 < plab, \lambda s.s > \psi 2\} is well-defined.
     Clearly dq1(...(d1(s))) \in cl1 \leq plaB, (a[k] plaB) > pla[q1] so that we are
     finished if q1 = m. Otherwise q1 < m and trans(q+1) is in
     Ag2<plaT,Dt-cond>\v2 or Aattach(pla-out)<plaT,Df-cond>\v2.
     i) Assume trans(q1+1) & Ag2<plaT,Dt-cond>\v2. Then
        pla[q1] \epsilon xpld(occ\{<1>) \land pla[q1] \epsilon xpld(occ\{<2>)\upsilon{plaT} so
        pla[q1] = plaT. Furthermore
        q2 = max{j | trans(q1+1),...,trans(j) \in Ag2<plaT,Dt-cond>\$\$2} is
        well-defined and dq2(...(dq1(...(d1(s))) \epsilon cl2<plaB,(ak plaB)> pla[q2].
       We are finished if q2 = m. To see that q2 = m assume otherwise: Then
        trans[q2+1] & Ag1<pla-begin, \(\frac{1}{2}\)s.s>\(\psi\)2 \(\omega\) Aattach(pla-out)<plaT, \(\omega\)f-cond>\(\psi\)2
        implying [by P-F(Ag1) and 5.2-5] that
        pla[q2] ← xpld(occ <<1>)v{pla-begin} which is impossible when P-F(Ag2)
        implies pla[q2] & xpld(occ << 2>).
     ii) Assume trans(q1+1) € Aattach(pla-out)<plaT,Df-cond>\dagge2. Then
        pla[q1] \in xpld(occ <<1>) \land pla[q1] \in \{plaT\}  so that pla[q1] = plaT and
        dEq1+13(...(d1(s))) \in cl3 < plaB, (ak plaB) > plaEq1+13. We are done if
        q1+1 = m. This is the case because
        pla[q1+1] = pla-out \notin xpld(occ\{<1>) \cup xpld(occ\{<2>) \cup {pla-begin}.
PROOF OF 5.2-8:
The proof is by structural induction. We only show the proof for
WHILE...DO...OD. Part of the result follows by 5.1-4(a). For the remaining
 part, assume pure[Occ](occ) and make the abbreviations of Lemma 5.2-11. To
 save space they are not repeated here.
 1) Our first goal is to show (for arbitrary c and s)
   U\{FIX(g[c])s \mid s \in \underline{s}\}
   EQ U(c(s) | secl(out(Ag))} u (R L cl)
   where cl = Close([Ag ALSO {<plaB,plaR>,\lambdas.s>}]
                      <pla-begin, \(\lambda \)s.s>\(\psi^2\), pla-begin, s)
   By 5.1-4 and 5.1-5 this amounts to
   P-G(\lambdac.FIX(g[c]), Ag ALSO {<<plaB,plaR>,\lambdas.s>}) except that pla-in of P-G
   can only be pla-begin.
   By the induction hypothesis and Lemma 5.2-4 the result of Lemma 5.2-11
   holds in this setting. So
   U { FIX(g[c]) s | ses}
    = LK LK (g[c])" x s | n>1} | ses}
    = Ц{ Ц{ (g[c])" _ s | ses} | n>1}
        which was by Lemma 2.1.1-7 twice, and by Lemma 5.2-11 we get:
   EQ U{ LK c(s) | s \epsilon([an\omega...\omegaa1]pla-out)} \omega (R \omega)(an\omega...\omegaa1) | n\geq1}
    = X 1 Y
   where
```

 $x = U\{ U\{ c(s) \mid se([anu...ua1] pla-out)\} \mid n\geq 1\}$

```
= \bigcup \{ c(s) \mid \exists n > 1 : s \in ([an \sqcup \ldots \sqcup a1] \mid pla - out) \}
                       which was by Lemma 2.1.1-7
               = U\{c(s) \mid s \in ((U\{an|n\geq 1\}) \text{ pla-out})\}
       and
         y = U\{ (R \cup )(an_{\mu \cdot \cdot \cdot \cdot \mu}a1) \mid n>1 \}
               = U\{\lambda_{pla}, U[(an pla), ..., u(al pla)] | n>1\}
               = \lambdapla. U{ U[(an pla)\sigma...\sigma(a1 pla)] | n\geq1}
               = λpla. U( U{(an pla)υ...υ(a1 pla) | n≥1})
                       which was by Lemma 2.1.1-7
               = \lambdapla. \square((\mathbb{I}\{an|n>1\})pla)
               = (R \sqcup) ( \sqcup \{an \mid n > 1\})
        so U{ FIX(g[c])s | ses}
         EQ \coprod{ c(s) | se((\coprod{an|n\geq1})pla-out)} \coprod (R \coprod) (\coprod{an|n\geq1})
       This shows the result because U{an|n>1}
         = \coprod{ Luk( Ag<pla-begin, \lambdas.s>\forall2, pla-begin, \underline{s}, n,
                                 {\langle plaB_plaR \rangle, \lambda s.s \rangle} \mid n \geq 0}
          = Close( Ag<pla-begin, \lambda s.s > \psi 2 u {<<plaB,plaR>, \lambda s.s > \}, pla-begin, s)
          = Close( [Ag ALSO {<<plab,plaR>, \lambdas.s>}]<pla-begin, \lambdas.s>\psi2, pla-begin, \underline{s})
  2) By Lemma 5.2-5 P-G(attach(pla-begin), Aattach(pla-begin)) so that "1)" and
        reasoning as in the proof of Lemma 5.2-7 yields
       P-G(FEWHILE exp DO cmd ODI occ, AFEWHILE exp DO cmd ODI occ) where we have
       used ACTWHILE exp DO cmd ODI occ =
        (Ag ALSO {<<plaB,plaR>, \( \alpha \). s.s>}) * Aattach(pla-begin). This ends the proof of
       the WHILE exp DO cmd OD case.
PROOF OF 5.2-12:
 Lemmas 5.2-4, 5.2-8 and 5.2-7 imply
  P-G()c.DEdct4<1>; &Fcmd4<2>;c. A&Fcmd4<2>*ADEdct4<1>). Since
  < <>, "(pro"> $\int \text{local(AfficmdI<2>*AffictI<1>)} we get \text{\inp}\inp\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text{\inp}\text
 PindIBEG dcl IN cmd ENDIinp
    = U{ (AEdclI<1>; &EcmdI<2>; finish)s |
                    s \in \{ uabs \{ \langle \lambda ide."nil" inVal, inp, \langle \rangle, \langle \rangle \} | inp \epsilon inp \} \}
  EQ (R U) (Close( APEBEG dcl IN cmd ENDI, <<>,"(pro">,
                                                  { uabs{ \langle \lambda \text{ide."nil" inVal, inp, } \langle \rangle, \langle \rangle \} | inpeinp}}))}
    = \lambdapla. U{dn(...(d1(uabs{\lambdaide."nil" inVal, inp, \lambda, \lambda) | inpeinp}))) |
                                        n >1 , 3 << pla[0], pla[1] >, d1 >,..., << pla[n-1], pla[n] >, dn >
                                                                  € APIBEG dcl IN cmd ENDI
                                                        so that pla[0] = \langle \langle \rangle, "(pro"> \( pla[n] = pla \)
```

APPENDIX 6

PROOF OF 6.1.2-3:

```
The proof is an extension of the proof of Lemma 4.2.1-2 (for the std case):
1) For any c \in C_p ss1 \in S -c> R and ss2 \in S -c> R we can prove (c \oplus ss1) \oplus ss2 =
  c\theta(ss1*ss2) as in 4.2.1-2.
2) For g € Par -t> C -c> C any primitive function and c€C we can prove
  g(par)(c) = c\theta[Pg(par)] as in 4.2.1-2.
3) For pla∈Pla and c∈C we can prove attach(pla)(c) = c⊕[Pattach(pla)] as in
  4.2.1-2.
4) For c \in C, ss1 \in S -c> R and ss2 \in S -c> R we have c \oplus Pcond(ss1, ss2) =
  cond(c\thetass1,c\thetass2). To see this: cond(c\thetass1,c\thetass2)
   = \lambda s. Vcond(s) -> (Scond(s) -> c\thetass1, c\thetass2)(Bcond(s)), "wrong"inA
   = \lambda s. Vcond(s) -> E c \theta (Scond(s) -> ss1, ss2)](Bcond(s)), "wrong"inA
        (which was by cases of Scond(s))
   = c \oplus [ \lambdas. Vcond(s) -> [ Scond(s) -> ss1, ss2 ](Bcond(s)), "wrong"inR ]
        (which was by cases of Vcond(s))
   = c \oplus Pcond(ss1.ss2)
5) Define strict c = \lambda r. rESta -> c(r | Sta), "wrong" in A. It is not
  difficult to show that strict \epsilon [S -c> A] -c> [R -c> A].
6) The result is shown by a structural induction. We only consider the
  "difficult" case WHILE exp DO cmd OD. So assume root(tree).str =
  "WHILE exp DO cmd OD" and c€C and abbreviate:
   (P)gO = (P)attach<root(tree).lab,"(">
   (P)g1 = (P)\mathcal{T}(son1(tree))
   (P)g2 = (P)\mathcal{T}(son2(tree))
   (P)g3 = (P)attach<root(tree).lab,")">
    cn = [\lambda c', g1; cond(g2; c', g3; c)]^n \bot
   ssn = [\lambda ss. Pcond(ss*Pg2, Pg3)*Pg1]^n \bot
  It is easy to show
  c\theta ss = c' \Rightarrow c \theta E Pcond(ss*Pg2,Pg3)*Pg1 I = g1;cond(g2;c', g3;c) using
  induction hypotheses and "4", "3" and "1". Since c\theta \perp = \perp a proof by
  induction yields \forall n > 0: cn = c\thetassn. We now want to deduce \coprod \{cn \mid n > 0\} =
  c\theta(LKssn | n>0). We have LKcn | n>0
   = \coprod {c \oplus ssn \mid n>0}
   = U{ (strict c) \circ ssn | n \ge 0 }
    = (strict c) \circ (\coprod{ssn | n>0})
         which was because (strict c) continuous and {ssn | n≥0} a directed set
   = c \theta ( \mathbf{U} \{ ssn \mid n \geq 0 \} )
  Hence g0; (L{cn | n \ge 0}) = c \theta ((L{ssn | n \ge 0}) * Pg0) showing
  \mathcal{T}(\text{tree})c = c \oplus P \mathcal{T}(\text{tree}).
```

PROOF OF 6.1.3-2:

We first prove 4 auxiliary results and then (case 5) perform a proof by structural induction.

1) We show P-G(std-ss1,sts-ss1) A P-G(std-ss2,sts-ss2) => P-G(std-ss1*std-ss2,sts-ss1*sts-ss2)

Let stacp(Sta) and calculate (sts-ss1*sts-ss2)sta V1

- = { (std-ss1(std-ss2(sta) | Sta) | Staesta \((std-ss2(sta) \)ESta) = true \(\) (std-ss1(std-ss2(sta) | Sta) \(\)ESta) = true \(\)
- 2) For any primitive function g it is easy to show P-G(std-Pg(par),sts-Pg(par)).
- 3) It is easy to show P-G(std-Pattach(pla), sts-Pattach(pla)).
- 4) We show P-G(std-ss1,sts-ss1) \wedge P-G(std-ss2,sts-ss2) => P-G(std-Pcond(std-ss1,std-ss2), sts-Pcond(sts-ss1,sts-ss2)). Let $\underline{stae}\Theta$ (Sta) and calculate: sts-Pcond(sts-ss1,sts-ss2) \underline{sta} ψ 1

= { $(std-ss1(std-Bcond(sta)) | Sta) | staesta \land std-Vcond(sta) = true \land std-Scond(sta) = true \land (std-ss1(std-Bcond(sta)) ESta) = true}$

U { ... }

- 5) We now perform the structural induction. We only consider the "difficult" case where root(tree).str = "WHILE exp DO cmd OD". Abbreviate

Pg0 = Pattach<root(tree).lab,"(">

Pg1 = PT(son1(tree))

 $Pg2 = P\pi(son2(tree))$

Pg3 = Pattach<root(tree).lab.")">

 $ss[n][ss'] = [\lambda ss'] \cdot Pcond(ss''*Pg2,Pg3) * Pg1]^n ss'$

From P-G(1,1), the induction hypotheses and "1", "3" and "4" a proof by induction yields $\forall n \geq 0$: P-G(std-ss[n][1], sts-ss[n][1]). Our goal is to show P-G(\sqcup {std-ss[n][1] | $n \geq 0$ }, \sqcup {sts-ss[n][1] | $n \geq 0$ }. To do so we first show an auxiliary result about {std-ss[n][1] | $n \geq 0$ } and then prove the desired P-G(....).

i) Auxiliary Result:

The result

VstaeSta: {std-ss[n][1]sta | n≥0} = {1, U{std-ss[n][1]sta | n≥0}} easily follows from (omitting prefix std- in the rest of "i)")

Vn≥0: VstaeSta: [ss[n][1]sta ≠ 1 => ss[n][1]sta = ss[n+1][1]sta]

From ss[n+1][1] = ss[n][ss[1][1]] we only need to show by induction in n:

VstaeSta: [ss[n][1]sta ≠ 1 => (Vss': ss[n][1]sta = ss[n][ss']sta)]

For n=0 the result is obvious so assume it for n≥0 and prove it for n+1.

Let sta and ss' be arbitrary and assume ss[n+1][1]sta ≠ 1. Our strategy is to prove ss[n+1][ss'] equivalent to an expression which does not depend on ss' (because then the desired result holds).

We have (from ss[n+1][ss'] = ss[1][ss[n][ss']])
ss[n+1][ss']sta = (Pcond(ss[n][ss']*Pg2,Pg3) * Pg1)sta
There are four possibilities of (Pg1 sta). If

```
(Pg1 sta) \in \{1,7,\text{"wrong"inR}\}\ then ss[n+1][ss']sta = (Pg1 sta) is
      independent of ss'. Otherwise (Pg1 sta) = sta' inR for sta' independent
      of ss'. Proceeding like this we are left with:
        ss[n+1][ss']sta = ss[n][ss']sta"
      for sta" independent of ss'.
      From ss[n+1][1]sta # 1 we get ss[n][1]sta" # 1 so by induction hypothesis
      ss[n+1][ss']sta = ss[n][ss']sta" = ss[n][_]sta" is independent of ss'.
   ii) To show P-G(U\{std-ss[n][\bot] \mid n\geq 0\}, U\{sts-ss[n][\bot] \mid n\geq 0\}) we calculate
      for sta \in P(Sta): ((U{sts-ss[n][\bot] | n>0})sta)\forall1
       = U {{ ((std-ss[n][+]sta) | Sta) | staesta ^
              (std-ss[n][\bot]sta \ ESta) = true  | n \ge 0
          which was by ∀n≥0: P-G(std-ss[n][+],sts-ss[n][+])
       = { ((std-ss[n][+]sta) | Sta) | staesta ^
            ∃n>0: (std-ss[n][_]sta ESta) = true }
       = { U { std-ss[n][1]sta | n>0} | staesta ^
            (U\{std-ss[n][\bot]sta \mid n>0\} ESta) = true }
          which was because i) implies
             \exists n \ge 0: (std-ss[n][\bot]sta \inSta) = true <=>
             ((U{std-ss[n][\bot]sta | n>0}) \in Sta) = true
             (std-ss[n][1]sta ESta) = true =>
             std-ss[n][L]sta = L( std-ss[m][L]sta | m>0 }
      Then P-G( PJstd(tree), PJsts(tree)) easily follows.
                                                                                           PROOF OF 6.1.3-5:
 The proof is by structural induction. We only show the proof of the case
 root(tree).str = "WHILE exp DO cmd OD". Abbreviate (omitting prefix sts-).
   lab = root(tree).lab
   PgO = Pattach<lab,"(">
   Pg1 = PT(son1(tree))
   Pg2 = PJ(son2(tree))
   Pg3 = Pattach<lab,")">
   ss[n] = [\lambda ss. Pcond(ss*Pg2,Pg3) * Pg1]^n_{\perp}
   F(sta) = Pg2(Dt-cond(Pg1(sta) 1))1
 Calculating ss[n+1]sta
  = ss[n](F(sta)) \rightarrow Pg3(Df-cond(Pg1(sta) \forall 1)) \rightarrow
     \langle \bot, Pg2(Dt-cond(Pg1(sta)\psi1))\psi2 \bot Pg1(sta)\psi2 >
 makes it easy to show by induction on n≥0 that:
 ss[n]sta = U{< Df-cond(Pg1(F<sup>J</sup>(sta))\forall 1)}
                 , \perp \text{EDf-cond}(Pg1(F^{j}(sta)) \psi 1) / \langle lab, ")" \rangle ] \mu
                   Pg2(Dt-cond(Pg1(F^{j}(\underline{sta}))\psi1))\psi2 \rightarrow Pg1(F^{j}(\underline{sta}))\psi2>
                | 0<j<n }
 So that (by Lemma 2.1.1-7) \coprod{ ss[n]sta | n>0 }
  = U\{ < Df-cond(Pg1(F^n(sta)) \psi 1) \}
        , \perp EDf-cond(Pg1(F<sup>n</sup>(sta))))) / < lab,")"> ] u
           Pg2(Dt-cond(Pg1(F^{\prime\prime}(\underline{sta}))\psi1))\psi2
           Pg1(F^n(sta)) \sqrt{2} >
 and thereby P\mathcal{R} tree) sta
  = < U{ Df-cond(Pg1(F<sup>n</sup>(sta))\psi1) | n\ge0}
     , \perp [ \coprod \{ Df-cond(Pg1(F''(sta)) \psi 1) \mid n \geq 0 \} / \langle Lab, " \rangle " \rangle ] \sqcup
       U{ Pg2(Dt-cond(Pg1(F<sup>n</sup>(sta))\psi1))\psi2 | n\geq0} \sqcup
       U{ Pg1(F<sup>n</sup>(<u>sta</u>)) \ 2 | n≥0} ⊔
       1[ sta / <lab,"(">] >
```

By this result, by $dom(tree) = dom(son1(tree)) \cup dom(son2(tree)) \cup {lab}, by$

```
induction hypotheses and assumptions on == it is straight-forward to show
Pa(tree) ^ Pb(tree) ^ Pc(tree).
                                                                                    PROOF OF 6.1.3-7:
The result is shown by a structural induction. So let treeeTree .
 labedom(tree) \wedge staeP(Sta) and assume
root(tree at lab).cate{"pro","dcl","cmd","exp"}. We are to prove Pd(tree, lab). This is done by cases of root(tree).str using
that root(tree).cate{"ide", "ope", "bas"}. Most cases consider two
 possibilities: lab = root(tree).lab and lab # root(tree).lab. We are rigorous
about the first possibility and slightly less rigorous about the second.
Below we only show the proof of the case root(tree).str =
"WHILE exp DO cmd OD". We omit the prefix sts- and abbreviate:
   PgO = Pattach<root(tree).str,"(">
   Pg1 = PT(son1(tree))
   Pq2 = PT(son2(tree))
   Pq3 = Pattach<root(tree).str,")">
       = \lambda sta' Pg2(Dt-cond(Pg1(sta')\psi1))\psi1
       = P¶(tree)sta √2
From the calculations in the proof of Lemma 6.1.3-5
a pla = \bot[ \bot{Df-cond(Pg1(F<sup>n</sup>(sta))\psi1) | n\ge0} / <lab,")"> ] pla \bot
         ሀ\{ (Pg2(Dt-cond(Pg1(F''(sta)))))\} pla | n\geq 0} ு
         _{\rm L}{ (Pg1(F'(sta))\psi2)pla | n\geq0} _{\rm L}
         1 sta / <lab,"("> ] pla
 i) Assume lab = root(tree).lab
   To show Pd(tree, lab) we calculate:
   a <lab,")"> = P\pi(tree)sta \psi1
                                                     by Pb(tree)
                 = PT(tree) (a<lab,"(">) \psi1
                                                     by Pa(tree)
   To show Pe(tree, lab) we calculate:
   a <lab\{<1>,"("> = <math>\coprod{ (Pg1(F<sup>n</sup>(sta))\psi2) <lab\{<1>,"("> | n\geq0\} by Pc(...)
                     = U\{F'(sta) \mid n \ge 0\}
                                                             by Pa(son1(tree))
                     = U\{F^n(\overline{a} \leq lab, "(">) \mid n>0\}
                                                                     by Pa(tree)
   a <lab<<2>,"("> = U{ (Pg2(Dt-cond(Pg1(F*(sta))\psi1))\psi2) <lab<<2>,"("> | n>0}
                            which was by Pc(...)
                     = Dt-cond( U{ Pg1(F^n(\underline{sta}))\psi1 | n \ge 0} ) by Pa(son2(tree))
                     = Dt-cond( U{ (Pg1(F^{\eta}(\underline{sta}))\psi2) < Lab§<1>,")"> | n>0})
                            which was by Pb(son1(tree))
                     = Dt-cond( a<lab <<1>,")"> )
                                                               by Pc(...)
 ii) Assume lab # root(tree).lab
   Then lab = [root(tree).lab] < i,...> for i < {1,2}. Since the cases are
   similar we consider only i=1 below.
      To be rigorous the proof of Pd(tree, lab) \( \Lambda \) Pe(tree, lab) is by cases of
   root(tree at lab).str. To condense the proof we choose to give a general
   discussion covering all cases.
      By inspection of the definitions of Pd(tree, lab) and Pe(tree, lab) it is
   easy to see that verification of Pd(tree,lab) A Pe(tree,lab) amounts to
   showing one or more equalities
     (a pla1) = G[ tree \underline{at} lab ] (a pla2)
   for pla1 \psi 1 = lab < ... >  pure [Pla](pla1) and
   pla2\psi1 = lab\S<...> \wedge pure[Pla](pla2) and G[tree at lab]: \mathcal{P}(Sta) \rightarrow \mathcal{P}(Sta) a
   complete-u-morphism (Corollary 6.1.3-3) that does not depend upon tree
```

except tree at lab. Obviously, (a pla1) = U{ (Pg1(Fⁿ(sta)) $\sqrt{2}$)pla1 | n>0 } by Pc(...) and i=1= U{ G[son1(tree) at lab] $((Pg1(F^n(sta)))/2)pla2) | n>0 }$ which was by Pd(son1(tree)) A Pe(son1(tree)) = G[son1(tree) at lab] (U{ (Pg1($F^n(sta)$) ψ 2)pla2 | n>0}) which was by G[...] a complete-u-morphism = G[tree at lab] (a pla2) which was by $Pc(...) \wedge i = 1$ PROOF OF 6.1.4-2: The proof is by induction on #lab. For #lab=0 it is obvious so we only need to show P1(t1,t2,lab \leq <i>,sta) => P1(t1,t2,lab,sta). Therefore, assume P1(t1,t2,lab << i>,sta). Let teTree(<>,"pro") and t1',t2' Tree(<>,"pro") u Tree(<>,"dcl") u Tree(<>,"cmd") u Tree(<>,"exp") be such that t1 = t(lab << i> <- t1 ') and similarly for t2. Define (for j=1.2) $tj'' = {\langle lab', prod' \rangle | \langle lab \{ lab', prod' \rangle \in tj \underline{at} lab \}.}$ Clearly $t1 = t(lab \leftarrow t1")$ and $t2 = t(lab \leftarrow t2")$ as well as t1",t2" \in Tree(<>,"pro") vTree(<>,"dcl") v Tree(<>,"cmd") vTree(<>,"exp"). This leaves us with showing P2(t1,t2,lab,sta). This proof is by cases of root(t1 at lab).str. We only show the proof for the case root(t1 at lab).str = "WHILE exp DO cmd OD". The definition of Tree ensures that $i \in \{1,2\}$. Let i'=3-i so that $\{i,i'\}=\{1,2\}$. Then PFstd(t1 at labs<i'>) = PFstd(t2 at labs<i'>) so that P2(t1,t2,labs<i'>,sta)holds. We only use this weaker characterization because we then avoid having to consider the cases i=1 and i=2 separately. Abbreviate for $j \in \{1,2\}$: Pgj0 = Pattach<lab,"("> Pgj1 = PT(tj at lab <1>) $Pgj2 = P\pi(tj \underline{at} lab < 2>)$ Pgj3 = Pattach<lab,")"> $ssj[n] = [\lambda ss.Pcond(ss*Pgj2,Pgj3)*Pgj1]^n \bot$ $sts-a = (Pfsts(t1)sta) \sqrt{2}$ We must show ∀sta € sts-a<lab,"("> that PIstd(t1 at lab)sta = PIstd(t2 at lab) Now Pfstd(tj at lab) sta = $((U{std-ssj[n] | n>0}) * std-Pgj0) sta$ = **U**{std-ssj[n](sta) | n>0} so it suffices to show ∀n≥0 ∀sta e(sts-a<lab,"(">) that std-ss1[n](sta) = std-ss2[n](sta) We do this by showing by induction in n \forall \fora This is an appropriate result because Pe'(t1) implies $sts-a<lab,"("> \subseteq sts-a<lab <<1>,"(">. The case n=0 is obvious so we are left$ with showing it for n+1 assuming it holds for n>0. Let sta ϵ sts-a<lab $\{<1>$,"(">. We show std-ss1[n+1](sta) = std-ss2[n+1](sta) by showing std-ssj[n+1]sta equivalent to an expression that does not depend on j. We have std-ssj[n+1]sta = [std-Pcond(std-ssj[n]*std-Pgj2,std-Pgj3)*std-Pgj1](sta) By P2(t1,t2,lab $\{<1>$,sta) we know std-Pg11(sta) = std-Pg21(sta) = std-a1 for

"independent of j". Otherwise std-a1 = sta1 inR for sta1 "independent of i"

some std-a1. If (std-a1ESta) # true then std-ssj[n+1]sta = std-a1 is

and

[Appendix 6]

std-ssj[n+1]sta = std-Pcond(std-ssj[n]*std-Pgj2, std-Pgj3) sta1 Also Pd'(t1) and 6.1.3-2 implies sta1 ϵ sts-a<lab δ <1>,")">.

Proceeding like this we are left with the case std-ssj[n+1]sta = std-ssj[n]sta2 for sta2 \(\) sts-a<lab \(\) 2>,")"> and sta2 "independent of j". The result follows by the induction hypothesis if sta2 \(\) sts-a<lab \(\) (">. It is not difficult to show (using Pd'(t1) and Pe'(t1) and 6.1.3-3) that sts-a<lab \(\) ("> \(\) sts-a<lab \(\) (2>,")">

This finishes the proof for the case n+1.

PROOF OF 6.1.4-3:

Let $\underline{sta} = \{<\lambda \text{ide."nil" inVal, inp, }<>, <>> | inpeinp}. Then <math>\mathcal{S}$ sts(t1) $\underline{inp} = \text{sts-setup}(\mathcal{I}\text{sts}(t1); \text{sts-finish}) \underline{inp} = P\mathcal{I}\text{sts}(t1) \text{sta } \sqrt{2}$

which was by 6.1.2-4 and definitions of sts-setup and sts-finish.

So the premise of the theorem merely amounts to P1(t1,t2,lab, \underline{sta}). By Theorem 6.1.4-2 then P1(t1,t2,<>, \underline{sta}) which implies $\forall sta \in (PTsts(t1)\underline{sta} \forall 2) <<>,"(">: PTstd(t1)sta = PTstd(t2)sta$

which by Pa(t1) and 6.1.2-3 implies $\forall sta \underline{\epsilon sta}$: ($\Im std(t1)$; std-finish) $sta = (\Im std(t2)$; std-finish) sta

By definition of <u>sta</u> and std-setup this is equivalent to $\forall inp \in Pstd(t1) inp = Pstd(t2) inp$